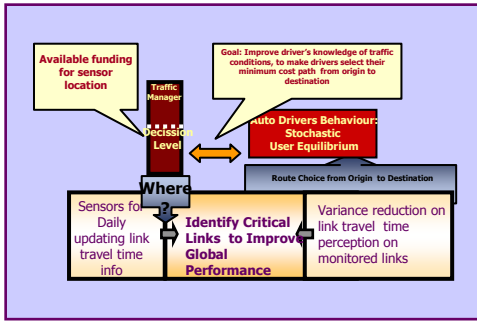
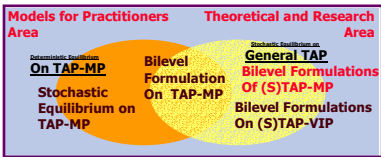


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## Transportation Planning Framework ...



## Bilevel Programming Formulation ...

$$\min_x \sum_{a \in A} E[C(v(x))]^T v(x)$$

subject to  $x \in X$

$$v(x) \in S(x) \quad X \stackrel{\text{def}}{=} \{ \sum x_a \geq \delta; \underline{\gamma} \leq x_a \leq \bar{\gamma} \}$$

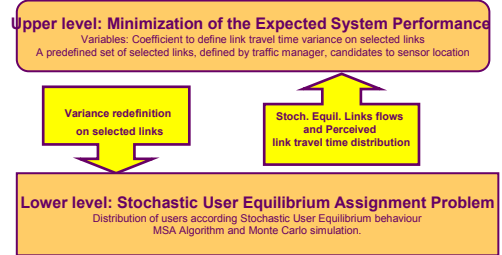
$S(x)$  is the set of feasible link volumes satisfying stochastic user equilibrium parametrized by the upper level variables  $x$ .

The information of traffic conditions to drivers has as purpose the enhancement of the global quality of service for network users.

Quality of detection (and thus, information given to users) is postulated to directly affect the variance of the perceived link travel time random variable.

A hierarchical decision-making problem of two levels is adopted in order to assess the allocation of information points.

An upper level function that is the **system equilibrium performance** function and the lower level is an **Stochastic User Equilibrium Assignment Problem (STAP)**.



The decision process of allocating information points is **heuristically** attained by inspecting the optimal values of the upper level variables that should be interpreted as **the influence of the quality of detection** on the system performance function (upper level).

The approach is static, in the sense that, no variation in time of the traffic conditions is considered

## LOWER LEVEL : Stochastic TAP- Random Models for Link Travel Cost...

$$C_a \sim N(c_a, \sigma_a) \quad \forall a \in A$$

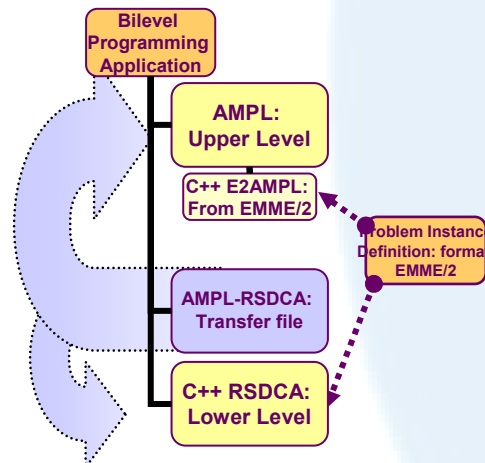
$$\sigma_a = \beta x_a c_a (s_a)$$

- Expected perceived link travel time dependent on link volume (congestion dependent case).
- Additive models: route cost is addition of link costs defining the route.
- Expectation of perceived link travel cost is measured link travel time.
- Variance of perceived link travel cost independent of link volumes: proportional to travel time on saturation

## MSA ALGORITHM FOR STOCH. TAP

- The Method of Successive Averages (MSA) with a predetermined step size was proposed by Daganzo (82) and Sheffi and Powell (82).
- MSA algorithm is a Monte-Carlo based method and does not required explicit path enumeration.
- MSA algorithm shows slow convergence, since it does not evaluate the objective function.
- Software Architecture fully developed.
- C++E2AMPL Interface operative.
- C++ RSDCA Environment operative.
- Upper level AMPL implementation of the Optimization Method is still on duty.

## Software Architecture



## Preliminary Results and Conclusions

- Available the estimate by MonteCarlo of upper level function at  $x$ , **expected system equilibrium performance function** at  $v(x)$ .
- System Performance function reduction when perceived link cost variance is reduced