- GPS as a Solar observational instrument: Real-time
- ² estimation of EUV photons flux rate during strong,
 ³ medium and weak Solar flares

Talwinder Singh,¹ M. Hernandez-Pajares,² Enric Monte,³ A. Garcia-Rigo,²

G. Olivares-Pulido 2

¹Department of Physics, Indian Institute

of Technology (BHU) ,Varanasi, India.

²Departament Matem tica Aplicada IV,

IonSAT res. group, Universitat Politcnica

de Catalunya, Barcelona, Spain.

³Departament de Teoria del Senyal i

Comunicacions, TALP res. group,

Universitat Politcnica de Catalunya,

Barcelona, Spain.

X - 2 TALWINDER ET. AL: GPS AS A SOLAR OBSERVATIONAL INSTRUMENT Abstract. In this manuscript, the authors show how the Global Navigation Satellite Systems, GNSS (exemplified in the Global Positioning Sys-5 tem, GPS), can be efficiently used for a very different purpose from that for 6 which it was designed; as an accurate Solar observational tool, already op-7 erational from the open global GPS measurements available in real-time, and 8 with some advantages regarding dedicated instruments onboard spacecraft. 9 The very high correlation of the solar Extreme Ultraviolet (EUV) photon 10 flux rate in the 26-34 mm spectral band, obtained from the SEM instrument 11 onboard the SOHO spacecraft during Solar flares, is shown with the GNSS 12 Solar Flare Activity Indicator (GSFLAI). The GSFLAI is defined as the gra-13 dient of the ionospheric vertical total electron content (VTEC) rate versus 14 the cosine of the Solar zenith angle in the day hemisphere (which filters out 15 non-Solar over-ionization), and it is measured from data collected by a global 16 network of dual frequency GPS receivers (giving in this way continuous cov-17 erage). GSFLAI for 60 X class flares, 320 M class flares and 300 C class flares, 18 occurred since 2001, were directly compared with the EUV Solar flux rate 19 data to show existing correlations. It was found that the GSFLAI and EUV 20 flux rate present the same linear relationship for all classes of flares, not only 21 the strong and medium intensity ones, X and M-class, as in previous works, 22 but also for the weakest C-class Solar flares, which is a remarkable result. 23

November 6, 2015, 4:51pm

1. Introduction

The scope of space geodesy technique applications is in continuous growth, in particular for measuring, in different and better ways, parameters of the Sun (see for instance *Soja et al.* [2014]). This is the context of the research and the results presented in this paper; the utilization of the Global Navigation Satellite Systems as an instrument of Solar observation by indirectly measuring the Solar EUV flux rate from the sudden over-ionization of the overall Earth ionosphere during Solar Flares.

Indeed, Solar flares are sudden flashes of brightness in the Solar atmosphere associated to 30 energetic charged particle emission (primarily high energy protons) and electromagnetic 31 (EM) radiation emission across the whole electromagnetic spectrum (primarily X rays 32 and EUV rays). Solar flares generally originate in active regions, expanses of intense 33 Solar magnetic field, and are often accompanied by coronal mass ejections (CMEs, see 34 Yashiro and Gopalswamy [2008]). X-rays and EUV rays emitted during Solar flares can 35 affect the Earth's ionosphere by producing photo electrons. These photo electrons are only produced in the daylight ionosphere and their enhancement can be approximated by 37 the Chapman model (see *Mendillo et al.* [1974]). This enhancement in electron number 38 results in increased reflection, refraction and diffraction of EM waves passing through 39 the ionosphere, and hence can affect satellite communications. Solar flares also have an 40 indirect adverse effect on the lifetime of satellites in the Earth's orbit. X-rays, along with 41 EUV radiation, heat up the earth's outer atmosphere, causing it to expand. This, in turn, 42 increases the drag acting on these Earth orbiting satellites, thus reducing their lifetime 43 in orbit. Since EUV bands are optically thick in the Solar atmosphere, flares originating 44

DRAFT

November 6, 2015, 4:51pm

X - 4 TALWINDER ET. AL: GPS AS A SOLAR OBSERVATIONAL INSTRUMENT

closer to the center of the Solar disk are more geo-effective than those closer to the limb 45 (Qian et al. [2010]). Sometimes, after the arrival of a Solar flare radiation, associated 46 nearly-relativistic electrons can also arrive, typically several minutes after the onset of the 47 EM signature of the Solar flare (Simnett et al. [1974] and Fig. 6 in Hernández-Pajares et 48 al. [2012]), which may affect the readings of direct sensors such as the SOHO SEM. But 49 since these electrons enter the Earth's atmosphere through the polar caps, the associated 50 increase in ionization in the atmosphere does not follow the expected flare overionization 51 dependence of the Solar zenith angle, and then it can be filtered-out. 52

Dual Frequency GPS satellites have become an excellent tool for ionosphere monitoring 53 today. The total number of permanent GPS receivers around the globe, whose data is 54 provided by the International GNSS Service (IGS, see *Dow et al.* [2009]), is currently more 55 than 300, giving high spatial and temporal resolution to measure the electron content in 56 the ionosphere. In the following sections we will show how Solar flares can be monitored 57 using GPS data and how the high geo-effectiveness of Solar EUV radiation allows for the 58 determination of its flux rate by measuring the ionospheric response to Solar flares. A previous study by Hernández-Pajares et al. [2012] on this subject mainly focused, and 60 demonstrated the approach, for X class flares. Recently, this GNSS-ionospheric proxy of 61 the Solar EUV flux rate has been used to characterize the main statistical properties of 62 Solar flares (Monte-Moreno and Hernández-Pajares [2014]). The present paper covers M 63 and C class flares along with X class flares, showing that the same approach is also valid 64 for mid and low intensity Solar flares. 65

⁶⁶ The organization of the manuscript is as follows: Section 2 explains the GSFLAI, an ⁶⁷ approach introduced in *Hernández-Pajares et al.* [2012] to detect and characterize Solar

flares. Section 3 explains how dual frequency GPS data can be used to calculate total electron content. In sections 4 and 5, information regarding input GPS data and reference EUV data is given. Section 6 discusses Solar flare events and results. This paper is concluded in Section 7.

2. The GNSS Solar flare activity indicator (GSFLAI)

During a Solar flare event, the ionospheric electron density increases very rapidly. There-72 fore the assumption that the change in electron density is only due to the ionization process 73 and not resulting from loss due to recombination processes or physical migration is valid. 74 Indeed, it can be seen that the rate of production of ion-electron pairs at some level of the 75 atmosphere (typically in equilibrium at any given time with the losses by recombination) 76 is proportional at any given time to the intensity of the ionizing radiation (see for instance 77 Eq. 1.19 in page 15 of Hunsucker & Hargreaves [2002]). It is then straightforward to 78 derive that, under a sudden increase of Solar radiation (where transport phenomena can 79 typically be neglected), an increase in the rate of production of ion-electron pairs will 80 occur, with the associated sudden generation of extra free electrons. This is exactly what 81 is observed for the main Solar flares (in Hernández-Pajares et al. [2012]), and for low 82 intensity flares (as we are going to show in this manuscript). Then the rate of VTEC 83 V, for a given Solar zenith angle χ , is related to the Solar flux rate I by the following 84 equation: 85

86

$$\dot{V} = \eta' \cdot C(\chi) \cdot \dot{I} \tag{1}$$

where η' stands for geo-effectiveness of the considered spectral range.

It has been shown that $C(\chi)$ can be reasonably approximated by $\cos \chi$ for all values of χ

⁸⁹ (Hernandez-Pajares et al. 2012). Since the ionization process takes place a few hundred ⁹⁰ kilometers above Earth's surface, enhanced ionization for $\chi > 90$ degrees can be expected ⁹¹ due to the Solar irradiance at such height. On plotting \dot{V} against $\cos \chi$ for different Solar ⁹² flare events, enhanced ionization is clearly visible for $\cos \chi > -0.2$. Thus when \dot{V} is ⁹³ plotted against $\cos \chi$ for $\cos \chi = -0.2$ to 1, a straight line is observed described by the ⁹⁴ equation:

107

$$\dot{V} = a_1 \cos \chi + a_2 \tag{2}$$

The independent term, a_2 , is expected due to enhanced ionization for $\chi > 90$ deg. In this paper, GSFLAI is considered as the slope of this line, i.e. a_1 , and it is adjusted as a single parameter to enhance the estimation (assuming over-ionization for $\cos \chi > -0.2$, corresponding approximately to the ionospheric effective height). From Eq. 1 and 2, it is clear that with this definition, the GSFLAI is linearly related to the Solar flux rate \dot{I} with a certain slope and an intercept whose magnitude is directly related to the over-ionization at $\cos \chi = 0$, i.e. a_2 .

3. VTEC from GPS data

TEC is the total number of electrons between two points along a cylinder of cross-section one meter squared. Slant TEC(STEC) can be defined as the total number of electrons between a satellite and a receiver along a 1 m^2 cylinder, i.e. the corresponding integral of the electron density N_e :

$$S = \int_{r_r}^{r_s} N_e \cdot dl \tag{3}$$

where r_s and r_r represent the transmitting satellite and receiver positions, respectively. Vertical TEC (VTEC) then corresponds to the STEC when the satellite-zenith angle is

110 Zero.

In Ionospheric observations are generally derived from dual-frequency GPS phase measurements (L_1 and L_2) in terms of the "Ionospheric combination of carrier phases" L_I . It provides a direct but ambiguous measurement of STEC, S, with a nominal error of 0.02 TECU, where 1 $TECU = 10^{16}m^{-2}$ (see for instance Hernández-Pajares et al. [2011]). L_I can be expressed in terms of S as:

116

$$L_I \equiv L_1 - L_2 = \alpha S + w_I + B_I \tag{4}$$

where $\alpha = 1.05 \times 10^{-17} m^3$, w_I is due to the wind up effect which is easily corrected for permanent stations and B_I is the ambiguity term, which cancels out when considering the rate of L_I (taking into account the fact that no cycle slips have occurred).

¹²⁰ Vertical TEC is estimated from STEC by assuming a simple 2D ionospheric model i.e. ¹²¹ the ionospheric electron content is considered to be situated at 450 km above the Earth's ¹²² surface. Nevertheless, this is not a relevant parameter in this problem due to the predom-¹²³ inant data available at high elevations (where the assumed mapping is very accurate), ¹²⁴ the elevation mask used (15 degrees) and the overall fitting and outlier removal processes ¹²⁵ (performed at every epoch) versus the cosine of the Solar-zenith angle for filtering out of ¹²⁶ extreme cases. The VTEC rate can be written as

$$\dot{V} \equiv \frac{\partial V}{\partial t} \simeq \frac{1}{M} \frac{\Delta S}{\Delta t} = \frac{1}{\alpha M} \frac{\Delta L_I}{\Delta t}$$
(5)

where $M \simeq \frac{1}{\cos Z}$ is called the ionospheric mapping function, which is the de-projection coefficient from the vertical to line-of-sight (slant) directions calculated from the satellite zenith angle Z (the detailed expression can be found as well in *Hernández-Pajares et al.* [2011]).

Therefore, from Eq. 2 and 5 taking into account Eq. 1, our targeted magnitude for, the Solar flux rate \dot{I} , can be computed.

4. Input Data

The input global GPS data are acquired from the IGS association, a voluntary fed-134 eration that provides open access to high quality GNSS data and products. It pro-135 vides data from more than 300 dual frequency GPS receivers distributed worldwide and 136 which are capable of ionospheric monitoring with high spatial resolution (see *Hernández*-137 The time series of GNSS measurements captured at a sam-Pajares et al. [2009]). 138 pling period of 30 seconds were used in this paper. These time series are available at 139 ftp://cddis.gsfc.nasa.gov/gps/data/daily/. In general, 4 to 8 values of 140 STEC can be computed from a single receiver, corresponding to different line of sight di-141 rections for several GPS satellites in view, covering in this way most of the values of Solar 142 zenith angle χ . Presently, it is running in real-time, with a latency of 30 seconds, and 143 since 2012 has been used in the context of the ESA MONITOR and MONITOR-2 projects 144 (see *Beniguel et al.* [2012] and *Hernández-Pajares et al.* [2015] respectively), supported 145 also by the RTIGS project (see *Caissy et al.* [2012]). 146

5. Reference Data

GSFLAI calculations obtained from global GPS network data were compared with EUV measurements taken done by Solar EUV Monitor (SEM) on-board Solar and Heliospheric Observatory (SOHO, see *Judge et al.* [1998]) to obtain a relation between GSFLAI and EUV flux rate. EUV Solar flux data provided in the range 26-34 nm were used in this study. This choice was motivated by the fact that this range is dominant in the total

EM emissions by active regions, and also the high absorption of this range at Earth's ionosphere, mostly by atomic oxygen (dominant species and source of ionization up to 500 km). Also, the classification of Solar flares into X, M and C class flares was performed based on the X-Ray intensity data provided by the X-Ray Sensor (XRS) instrument onboard Geosynchronous Operational Environmental Satellite (GOES, *Garcia* [1994]).

6. Solar Flare Events and Results

To study the validity of GSFLAI as a potential Solar flare detector (complementing the Sunlit Ionospheric Sudden TEC Enhancement Detector, SISTED; see *García-Rigo* [2012]) and a proxy for the EUV flux rate, 60 X class flares, 320 M class flare and 300 C class flares that occurred between January 2001 and March 2014 were chosen. These flares were selected from the pool of total flares which were clearly picked-up by the SEM sensor on-board SOHO:

GSFLAI was computed for all the X and M class flares from Jan 2001 to March 2014.
 Because a large number of C class flares occurred during this period, we only considered
 C class flares that occurred on same days as X or M class flares. This prevented us from
 downloading any extra data while maintaining the sample unbiased.

2. Some of these flares were not picked up by the SEM, most probably because they originated close to the Solar limb (but they were picked up by the GOES X-Ray sensor as the X-Ray band is transparent in the Solar atmosphere). Because of the large number of total flares in our sample, we devised an automatic method to reject those flares from the study which were not picked up by the SEM. The method was to compare the epochs at which the GSFLAI and EUV flux rate achieved their maximas after the onset of the

DRAFT

November 6, 2015, 4:51pm

X - 10 TALWINDER ET. AL: GPS AS A SOLAR OBSERVATIONAL INSTRUMENT

¹⁷³ flare. If both epochs were within 50 seconds of each other, then the flare concerned was ¹⁷⁴ considered fit for study.

Section 6.1 discusses the validity of the GSFLAI method for the detection of various intensities of Solar flares. Also, the correlation of the GSFLAI with the EUV flux rate is shown for representative flares of different intensities. In section 6.2, the GSFLAI is directly compared with the EUV flux rate for all the Solar flares studied in this paper, to show that a linear relationship exists between the GSFLAI and EUV flux rate and to compute their linear relationship equation.

6.1. Representative GSFLAI examples

To demonstrate how the GSFLAI is computed during a Solar flare and to aid visualiza-181 tion, one plot for each Solar flare intensity class (X, M and C) are shown in Fig. 1. Some 182 outliers have been removed from the data, mainly due to local ionospheric perturbations 183 and carrier phase measurement errors which do not follow the expected dependence with 184 Solar zenith angle. It is clearly visible that the rate of change of VTEC (V) shows a 185 linear relation to $\cos \chi$, where $\cos \chi$ ranges from -0.2 to 1.0. After removing the outliers 186 by rejecting the points having an error greater than twice the standard deviation, in a first 187 least squares linear fitting, a final straight line is fitted through the data at each epoch 188 (e.g. each 30 seconds, or each second). The GSFLAI is defined as the slope of this line. It 189 is clear from the figure that the ionization effect is maximum for X class flares, followed by 190 M and C class flares, respectively. But it will be later shown that this might not always be 191 the case. Also, as mentioned earlier, the occasional nearly-relativistic electrons associated 192 with certain Solar flares enter the Earth's atmosphere through the polar caps. Since the 193 increase in atmospheric ionization due to these electrons is not a function of the Solar 194

¹⁹⁵ zenith angle, the GSFLAI is not affected by them (*Hernández-Pajares et al.* [2012]).

Also, the time evolution of the GSFLAI and EUV flux rate will be shown together to demonstrate the correlation between the two types of data. The top panel of Fig. 2 shows the time evolution of the GSFLAI and the EUV flux rate for an X class Solar flare classified as X6.2 according to GOES X-Ray flux data. It can be seen that they are well correlated. There are two points to note here:

²⁰¹ 1. The EUV measurements by SEM-SOHO are lagging behind the GSFLAI measure-²⁰² ments by 20-30 seconds. This lag, which is corrected for, is coincident with the one ²⁰³ found by *Hernández-Pajares et al.* [2012] working at 1 Hz, and it is smaller than the time ²⁰⁴ resolution of the GPS data used in this study (30 seconds).

205 2. After a peak in the GSFLAI and EUV flux rate, the GSFLAI is not able to follow 206 the EUV rate (GSFLAI decreases slowly), likely due to the slow recombination rate of 207 the ionosphere compared to its sudden ionization rate.

Furthermore, the typical correlation between GSFLAI and EUV flux rate is shown for M 208 and C class flares in the middle and bottom panels of Fig. 2, respectively. An M3.5 flare 209 that occurred on 30 November 2001 and a C5.3 flare that occurred on July 22 2004 are 210 chosen for this. A very good correlation can be seen in both cases. An important thing to 211 observe is that the GSFLAI (and EUV flux rate) presents a higher peak in the case of the 212 (weeker) C5.3 flare. This result stems from the fact that flare classification is made on the 213 basis of the X-Ray flux, which is relatively transparent to the Solar atmosphere, in contrast 214 to the EUV rays. Therefore a lot of EUV radiation is absorbed in the Solar atmosphere 215 if the source of the Solar flare is farther from the Solar disk center. This is true in this 216 case as the source of the C5.3 flare was located closer to the Solar disk center (N04E10) 217

X - 12 TALWINDER ET. AL: GPS AS A SOLAR OBSERVATIONAL INSTRUMENT

when compared to the source of the M3.5 flare (S07E54). Indeed, the location of the 218 flare in the Solar disc is important for the ionospheric response to the flare. The influence 219 of the flare's location has already been studied and discussed in Hernández-Pajares et 220 al. [2012] in which the excellent correlation between the direct EUV Solar flux rate and 221 ionospheric over-ionization (measured at a global scale by many GPS receivers) was not 222 observed when the X-band Solar flux rate was considered. In this way, by considering a 223 simple model (dependence on the cosine of the Solar flare angular distance to the Solar 224 disc center) for the EUV flux extinction in the Solar atmosphere (which does not affect 225 the X-band radiation, as it is well known), both kind of measurements were in agreement, 226 as is shown in Fig. 9 of Hernández-Pajares et al. [2012]. 227

Similar to the relationship between the GSFLAI and the SOHO-EUV flux rate, we find a good correlation between the GSFLAI and GOES-EUVI irradiance rate (see Fig. 3). At the moment, the GOES EUV irradiance data is only available at the cadence of 1 minute from ftp://satdat.ngdc.noaa.gov/sem/goes/data/new_avg. Future work can focus on extending the study of the relationship between GSFLAI and the GOES-EUVI irradiance rate.

²³⁴ Nevertheless, it can be seen that, in the case of low and mid geo-effectiveness Solar ²³⁵ flares, the amount of noise could masks the shape of the underlying function between ²³⁶ the cosine of χ and the GSFLAI index. Although the method used in this work allows ²³⁷ for the rejection of the outliers, and therefore allows finding of the correct slope, which is ²³⁸ consistent with the hypothesis of the model as shown in Eq. 1, it does not allow for the fact ²³⁹ that there might be other dependencies that are not captured by the model. In particular, ²⁴⁰ by trying another method (one-dimensional median filter -*Pratt* [1979]- plus a zero phase

low pass filter designed by means of the Kaiser window -*Hamming* [1989]-) we have found
that for weak and mid-intensity flares, the underlying dependency consistently manifests
some consistent nonlinear dependencies (low-frequency oscillations along the regression
line, see Fig. 4), which deserves investigation in further work.

6.2. Relationship between GSFLAI and direct EUV flux rate measurements

Direct comparison of the GSFLAI and the SOHO/SEM Solar EUV flux rate is shown 245 in Fig. 5 for strong, mid and weak Solar flares. An almost linear relationship is observed, 246 which is in full agreement with Eq. 1. Table 1 summarizes the linear relationships obtained 247 on linear fitting of the data (fifth and seventh columns on one hand, and sixth and eight 248 columns on the other hand -filtered in the last case to points with maximum ionization 249 increase per flare). It was observed that the slope of these fittings (0.18, 0.13 and 0.11)250 TECU/10⁹/cm²/s for X, M and C class Solar flares with correlation factors 0.83, 0.63 251 and 0.46, respectively) are in agreement, but with some initial differences for each class. 252 Indeed, the slope is slightly greater for strong Solar flares and slightly lower for weak Solar 253 flares. This effect is attributed to two reasons: 254

1. Points considered immediately after a peak in GSFLAI are not so well correlated with the EUV flux rate, likely due to the slower recombination rate. This effect is predominant in higher intensity flares so that they show a slightly greater slope of GSFLAI vs EUV flux rate.

259 2. The measurement/modelling of noise in lower intensity flares tends to decrease the
 260 slope of the GSFLAI vs EUV flux rate graph.

To check the validity of the above explanations, we plotted only those points corresponding to the highest GSFLAI for each given flare and which had an EUV flux rate

X - 14 TALWINDER ET. AL: GPS AS A SOLAR OBSERVATIONAL INSTRUMENT

(in units $photons \cdot 10^9/cm^2/s^2$) greater than 0.0075¹. Points satisfying this criteria are 263 plotted in Fig. 6 along with their regression line. This resulted in the selection of only 264 those points that corresponded to maximum ionization, rather than recombination and 265 were less affected by measurement/modelling noise. Fitting a straight line to these points 266 gave almost identical results (slopes of $0.152-0.159 \text{ TECU}/10^9/\text{cm}^2/\text{s}$) for all intensities 267 of flare. These results are summarized in Table 1 (columns 4 and 6). We also observe in 268 the same table, that the correlation factor of the GSFLAI vs EUV flux rate data increases 269 very significantly after restricting our selection of data points as mentioned above (up 270 to 0.94, 0.70 and 0.94 for X, M and C classes, respectively). This result confirms that 271 other sources of ionospheric activity such as that of Medium Scale TIDs (see for example 272 Hernández-Pajares et al. [2012b]), geomagnetic storms or scintillation, are mostly filtered 273 out in our model. This is due to the fitting requirement at each epoch such that the 274 VTEC rate measurements should be dependent on the Solar-zenith angle computed in 275 the ionospheric pierce point (IPP) in the ionospheric thin shell, χ (see Eq. 2), either for 276 the weakest C-class flares. 277

Also as explained in Section 2, we observe that, as expected, the *intercept* is greater for those flares that cause more ionization at $\cos \chi = 0$, which is generally in the decreasing order of X, M and C class flares.

7. Conclusions

Through this paper, it is demonstrated how GNSS (by means of the GNSS Solar Flare Activity Indicator, GSFLAI) can become an efficient Solar observational instrument in the characterization of all of kinds of geo-effective Solar flares with remarkable accuracy (which can be better than that of direct EUV flux detectors on board spacecraft²). Indeed,

an extensive study of X, M and C class flares occurred between January 2001 and March 285 2014 confirmed the use of GSFLAI as a proxy for EUV flux rate direct measurements 286 (taken from the SOHO Solar probe instrument) during such strong, mid and even weak 287 Solar flares, in a very consistent way. Such confirmation has been extended by first time to 288 a second Solar probe providing direct EUV measurements; the GOES-EUVI data. In this 289 way, global real-time networks of GNSS receivers (such as the one supporting the above 290 mentioned MONITOR project) are already becoming Solar sensors. This role extends 291 the previous usage of GNSS data to detect and characterize Solar flares (an example is 292 the Sunlit Ionosphere Sudden TEC Enhancement Detector, SISTED, see section 7.4 in 293 Hernández-Pajares et al. [2012]). 294

Acknowledgments. The data for this paper are available and it can be requested to any of the authors, in particular to Talwinder Singh (talwinder.singh.app11@iitbhu.ac.in) and Manuel Hernández-Pajares (Manuel.Hernandez@upc.edu). The solar flare detection technique was developed in the context of the authors participation in the ESA MONI-TOR activity, under a contract of the European Space Agency in the frame of the European GNSS Evolutions Programme. This work has been partially supported by project TEC2012-38939-C03-02 funded by the Spanish Ministry of Science and Innovation.

Notes

- These points are, for instance, suitable for defining a proxy of the geophysical intensity of the flare, once the effect of distance to the Solar disc center is corrected, as was shown in *Hernández-Pajares et al.* [2012] (Fig. 9 and associated comments).
- Which can be affected, in particular, by huge measurement error sources such as the arrival of relativistic electrons, sometimes simultaneously emitted with the flare, which however do not affect the GNSS-based technique (see *Hernández-Pajares et al.* [2012], top plot of Fig. 6).

DRAFT

November 6, 2015, 4:51pm

References

- ³⁰³ Beniguel, Y. et al. (2012, December). Ionospheric Effects on GNSS Performance. In Satel-
- lite Navigation Technologies and European Workshop on GNSS Signals and Signal Pro cessing,(NAVITEC), 2012 6th ESA Workshop on (pp. 1-8). IEEE.
- Caissy, M., L. Agrotis, G. Weber, M. Hernandez-Pajares and U. Hugentobler (2012), The
 International GNSS Real-Time Service, GPS World, June 2012.
- ³⁰⁸ Dow, J., R. Neilan, and C. Rizos (2009), The international GNSS ser- vice in a ³⁰⁹ changing landscape of global navigation satellite systems, J. Geod., 83(34), 191198, ³¹⁰ doi:10.1007/s00190-008-0300-3.
- Garcia, H. A. (1994), Temperature and emission measure from goes soft X-ray measurements, Sol. Phys., 154(2), 275308.
- ³¹³ García-Rigo, A. (2012), Contributions to ionospheric determination with Global Posi-
- tioning System: solar flare detection and prediction of global maps of Total Electron
- ³¹⁵ Content, Ph.D. dissertation. Doctoral Program in Aerospace Science and Technology,
- ³¹⁶ Universitat Politecnica de Catalunya, Barcelona, Spain.
- Hamming, R.W. (1989), Digital filters, Prentice-Hall.
- Hernández-Pajares, M., J. M. Juan, J. Sanz, A. García-Rigo, J. Feltens, A. Komjathy,
- S. C. Schaer, and A. Krankowski (2009), The IGS VTEC maps: A reliable source of ionospheric information since 1998, J. Geod., 83(34), 263275.
- ³²¹ Hernández-Pajares, M., J.M. Juan, J. Sanz, A. Aragón-Àngel, A. García-Rigo, D. Salazar,
- M. Escudero (2011), The ionosphere: effects, GPS modeling and the benefits for space

DRAFT

³²³ geodetic techniques, J. Geod., 85, 887907, doi:10.1007/s00190-011-0508-5.

- ³²⁴ Hernández-Pajares, M., A. García-Rigo, J. M. Juan, J. Sanz, E. Monte and A. Aragón ³²⁵ Àngel (2012), GNSS measurement of EUV photons flux rate during strong and mid
- ³²⁶ solar flares, SPACE WEATHER, VOL. 10, S12001, doi:10.1029/2012SW000826.
- ³²⁷ HernándezPajares, M., Juan, J. M., Sanz, J., & AragónÀngel, A. (2012). Propagation of
- medium scale traveling ionospheric disturbances at different latitudes and solar cycle conditions. Radio Science, 47(6).
- ³³⁰ Hernández-Pajares, M., R. Prieto-Cerdeira, Y. Béniguel, A. García-Rigo, J. Kinrade, K.
- ³³¹ Kauristie, R. Orus-Perez, S. Schlueter, D. Serant, B. Nava, A. Krankowski, H. Secretan,

R. Sampedro and X. Prats, MONITOR ionospheric monitoring system: analysis of

- ³³³ perturbed days affecting SBAS performance, Proceedings of the ION 2015 Pacific PNT
- ³³⁴ Meeting, Institute of Navigation, pages 970 978.
- Hunsucker, R. D., & Hargreaves, J. K. (2002). The high-latitude ionosphere and its effects
 on radio propagation. Cambridge University Press.
- Judge, D. L., et al. (1998), First solar EUV irradiances obtained from SOHO by the Celias/Sem, Sol. Phys., 177(12), 161173.
- Mendillo, M., et al. (1974), Behavior of the ionospheric F region during the Great Solar Flare of August 7, 1972, J. Geophys. Res., 79(4), 665672.
- Monte-Moreno, E., and M. Hernández-Pajares (2014), Occurrence of solar flares viewed
 with GPS: Statistics and fractal nature, J. Geophys. Res. Space Physics, 119,
 doi:10.1002/2014JA020206.
- Pratt, W.K. (1978), Digital Image Processing, John Wiley & Sons, New York, vol. 1191,
 pp. 491-556.

DRAFT

November 6, 2015, 4:51pm

- X 18 TALWINDER ET. AL: GPS AS A SOLAR OBSERVATIONAL INSTRUMENT
- Simnett, G. M. (1974), Relativistic electron events in interplanetary space, Space Sci.
 Rev., 16(1-2), 257323.
- Soja, B., Heinkelmann, R., & Schuh, H. (2014). Probing the solar corona with very long
 baseline interferometry. Nature communications, 5.
- ³⁵⁰ Qian, L., A. G. Burns, P. C. Chamberlin, and S. C. Solomon (2010), Flare location on
- the solar disk: Modeling the thermosphere and ionosphere response, J. Geophys. Res.,
- ³⁵² 115, A09311, doi:10.1029/2009JA015225.
- ³⁵³ Yashiro, S., N. Gopalswamy (2008), Statistical relationship between solar flares and coro-
- nal mass ejections, Universal Heliophysical Processes Proceedings IAU Symposium No.
- ³⁵⁵ 257, 233–243, doi:10.1017/S1743921309029342.

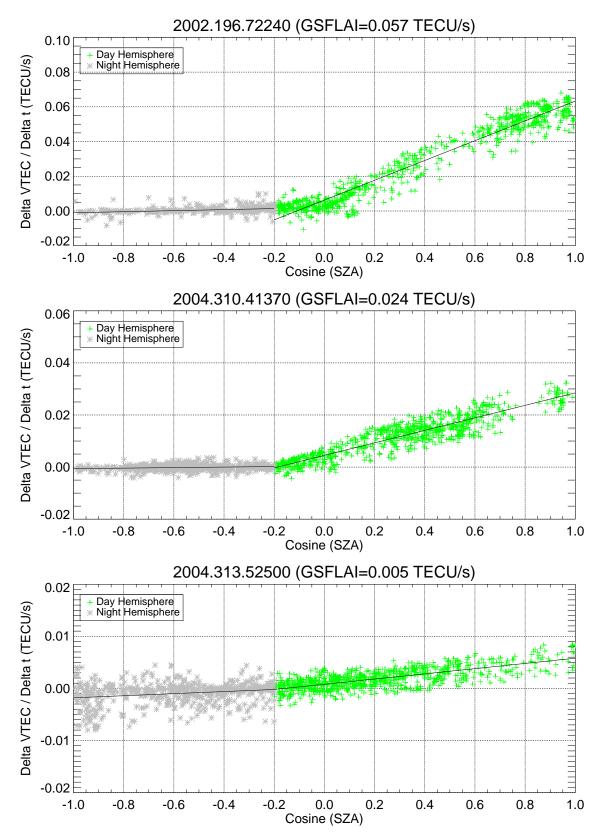


Figure 1. VTEC rate \dot{V} vs cos χ from top to bottom: a major X class Solar flare that occurred on day 196 of year 2002 at 72240 GPS time; an M class Solar flare that occurred on day 310 of year 2004; a C class flare on day 313 of year 2004 at 52500 GPS time. Data is fitted with a D R A F T November 6, 2015, 4:51pm D R A F T simple regression line individually for day and night hemispheres (note that the Y-axes are not at the same scale).

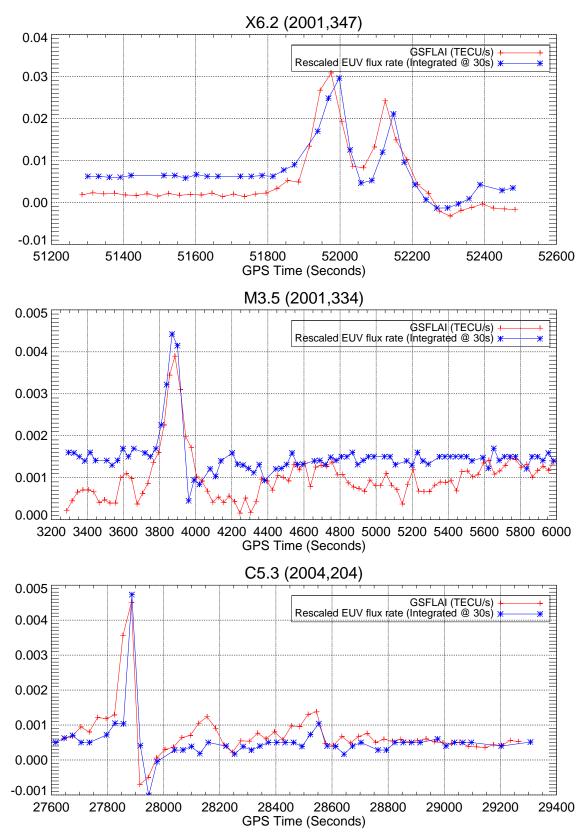


Figure 2. Correlation shown between GSFLAI and EUV flux rate data provided by SEM on-board SOHO for top to bottom: an X6.2 flare that occurred on day 347 of year 2001. EUV flux rate data is scaled as $\frac{0.165}{3*10^{10}}$ + 0.0046; an M3.5 flare that occurred on day 334 of year 2001. D R A F T EUV flux rate data is scaled as $\frac{0.157}{3*10^{10}}$ + 0.001; a C5.3 flare that occurred on day 204 of year 2004. EUV flux rate data is scaled as $\frac{0.159}{3*10^{10}}$ + 0.0003. (see also Table 1, columns 3 and 5)

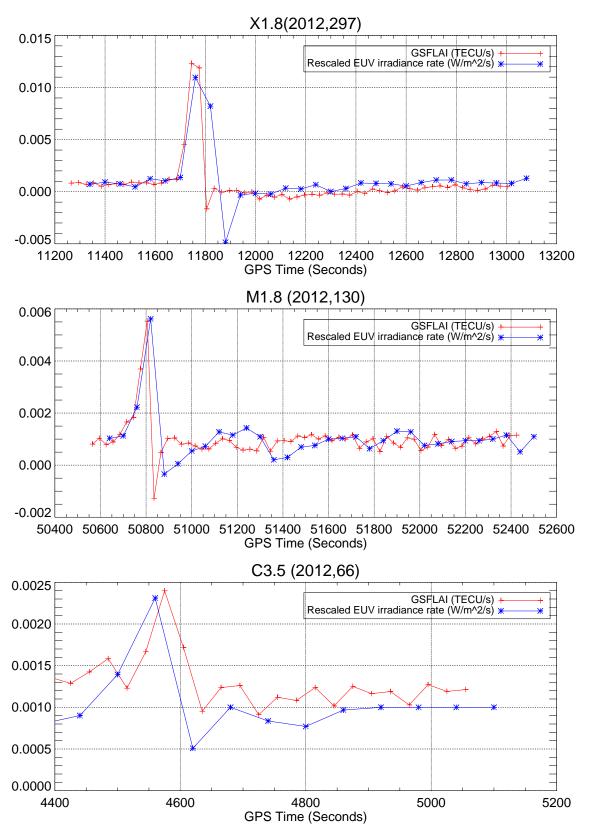


Figure 3. Correlation shown between GSFLAI and EUV irradiance rate data provided by channel B of EUVS on-board GOES-15 for top to bottom: an X1.8 flare that occurred on day 2977 of year 2012. EUV irradiance rate data is scaled as 2500.x + 0.001; an M1.8 flare that D R A F T November 6, 2015, 4:51pm D R A F T occurred on day 130 of year 2012. EUV flux rate data is scaled as 1800.x + 0.001; a C3.5 flare that occurred on day 66 of year 2012. EUV flux rate data is scaled as 2000.x + 0.001.

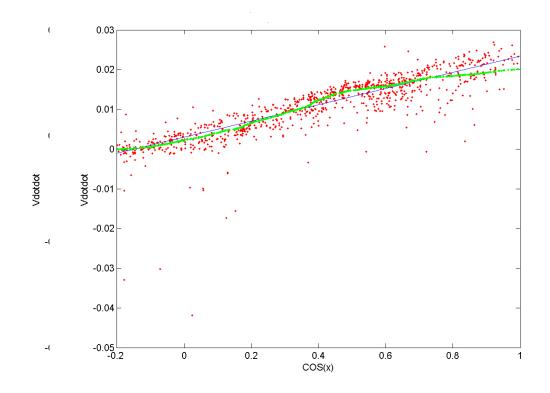


Figure 4. VTEC rate \dot{V} vs cos χ -red points-, compared with the regression line used in the study -blue line-, and the filtered VTEC rate -green points-, by means of a one dimensional median filter followed by a zero phase low pass filter: left, for a minor geoeffective Solar flare (GPS time 35970 seconds of day 310, 2013); right, for a mid geoeffective Solar flare (GPS time 30990 seconds of day 258, 2005)

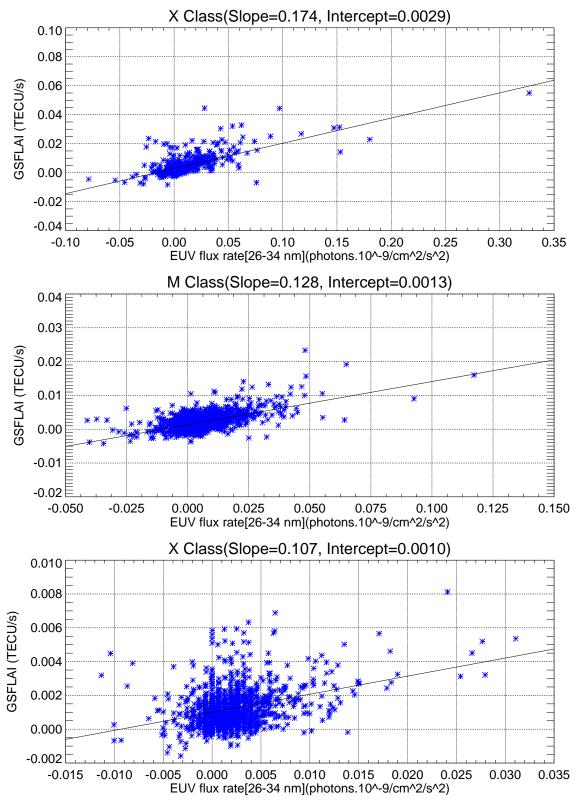


Figure 5. GSFLAI vs EUV flux rate data provided by SOHO-SEM in the 26-34 nm range for selected, top to bottom, X, M and C class flares which have occurred since 2001. Calculated simple regression lines are also shown for reference.

F	,
	F

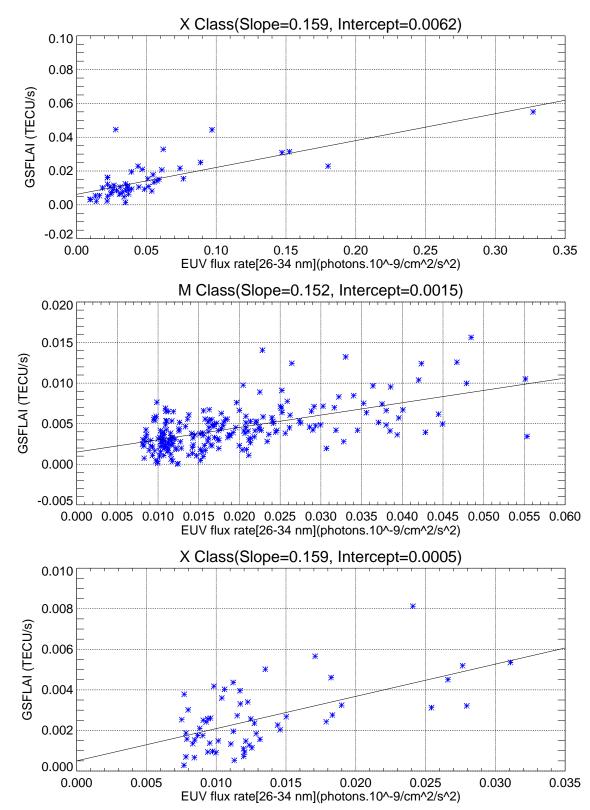


Figure 6. GSFLAI vs EUV flux rate data provided by SOHO-SEM in the 26-34 nm range for those points meeting specific criteria mentioned in Sec. 6.2 for top to bottom: X, M and C class flares which have occurred since 2001. Calculated simple regression lines are also shown for PeferenceF Very few points are available for C, class Hares 4b 5 apre EUV rate greater Than 40.0075 photons $* 10^9/cm^2/s^2$ is rare in low intensity flares.

$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		Peaks 53 0 219 7	All Peaks 523 53 1600 219	<u>.</u>
-	0.128 ± 0.004 (0.107+0.008 (0 219 0.128±0.004 0 58 0 107+0 008 0	1000 219 0.128±0.004 0.152±0.012 0.0015±0.00005 0.003 0.00 0.00 1.01 1163 58 0.107±0.008 0.150±0.090 0.0010±0.0002 0.50 0 0.01 0.54 0	

November 6, 2015, 4:51pm

ux rate.
flux
² for EUV flux rate.
for
/s
$^{-9/cm^{2}}$
6-(
$s.10^{-6}$
on
ioqc
AI and <i>photons</i> .
I aı
ĹΑ
GSFL/
for
l/s
TECU/
TE
are
The units are $TECU/s$ for GSFLAI and pl
n ət
Τł

ಹ

D R A F T

