

On bifurcations of area-preserving and non-orientable maps with quadratic homoclinic tangencies ^{*}

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Abstract

We study bifurcations of non-orientable area-preserving maps with quadratic homoclinic tangencies. We study the case when the maps are given on non-orientable two-dimensional surfaces. We consider one and two parameter general unfoldings and establish results related to the emergence of elliptic periodic orbits.

1 Introduction

The main goal of the paper is the study of bifurcations of area-preserving maps (APMs) defined on non-orientable surfaces and possessing homoclinic tangencies.

For dissipative systems, the study of bifurcations of homoclinic tangencies is quite traditional and many results obtained here have a fundamental value for the theory of dynamical chaos. One of such results, known as *theorem on cascade of periodic sinks (sources)*, goes back already to the paper [1] of Gavrilov and Shilnikov, see also [2, 3]. Note that in this paper the general case was considered, when the initial two-dimensional diffeomorphism has a saddle fixed point O with multipliers λ and γ , where $0 < |\lambda| < 1 < |\gamma|$ and the *saddle value* $\sigma \equiv |\lambda||\gamma|$ is not equal to 1, and the invariant manifolds of O are quadratically tangent at the points of some homoclinic orbit. In this case, bifurcations of the homoclinic tangency lead to the appearance of asymptotically stable (if $\sigma < 1$) or completely unstable (if $\sigma > 1$) periodic orbits. Moreover, in any one parameter general unfolding such orbits are observed for values of the parameter belonging to an infinite sequence (cascade) of intervals that do not mutually intersect and accumulate to the value of the parameter corresponding to the initial homoclinic tangency.

Concerning related results in the conservative case, we mention, above all, the well known result of S. Newhouse, [4], on the emergence of the so-called 1-elliptic periodic orbits (there is only one pair multipliers, $e^{i\varphi}$ and $e^{-i\varphi}$ with $\varphi \neq 0, \pi$, on the unit circle) under bifurcations of homoclinic

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tangencies of multidimensional symplectic maps. However, the Newhouse theorem from [4] does not give answer whether these 1-elliptic periodic orbits are generic.¹ This fact is very important for the two-dimensional case where an 1-elliptic periodic orbit is elliptic and the genericity means the KAM-stability. The birth of such generic elliptic periodic orbits under homoclinic bifurcations in symplectic two-dimensional maps was established by Mora and Romero in [7].² In [7] a one parameter family f_μ of two-dimensional symplectic maps was considered such that (i) f_0 has a saddle fixed point O with multipliers λ and λ^{-1} , where $0 < |\lambda| < 1$, and the invariant manifolds of O have a quadratic tangency at the points of a homoclinic orbit Γ_0 , and (ii) this tangency splits generally when μ varies. Then, as is shown in [7], there exists an infinite cascade of intervals δ_k , $k = \bar{k}, \bar{k} + 1, \dots$ (where \bar{k} is a sufficiently large integer) of values of μ such that the intervals δ_k accumulate at $\mu = 0$ as $k \rightarrow \infty$ and f_μ has at $\mu \in \delta_k$ a single-round elliptic orbit of period k . Note that all points of this orbit belong to a small fixed neighborhood of the contour $O \cup \Gamma_0$ and any such point is a fixed one for the corresponding first return map T_k . It was shown in [7] that the map T_k can be written in some rescaled coordinates in the form

$$\bar{x} = y, \bar{y} = M_k - x - y^2 + \nu_k(y), \tag{1}$$

where the new coordinates (x, y) and parameter $M_k \sim \lambda^{2k}(\mu - \alpha_k)$ can take arbitrary finite values as k are large and the coefficient α_k and function $\nu_k(y)$ tend to zero as $k \rightarrow \infty$ (the latter, along with their derivatives up to order $(r - 2)$ if $f_\mu \in C^r$). Thus, the map T_k is asymptotically close (as $k \rightarrow \infty$) to the conservative Hénon map $\bar{x} = y, \bar{y} = M_k - x - y^2$ that has an elliptic fixed point when $-1 < M_k < 3$. This point is generic for all such values of M_k except for $M_k = 0$ and $M_k = 1/2$ when the map has a fixed point with multipliers $e^{\pm i\pi/2}$ and $e^{\pm i2\pi/3}$, respectively. This result gives immediately the intervals δ_k with border points corresponding to $M_k = 3$ and $M_k = -1$, respectively.

However, the question on coexistence of single-round periodic orbits of different periods, i.e., whether the intervals δ_k with different numbers intersect, was not considered in [7]. Although, this problem is very important, since its solution is only necessary for construction of the bifurcation diagram. We note also that the Hénon map is degenerate with respect to bifurcations of the fixed point with multipliers $e^{\pm i\pi/2}$ (the strong resonance 1:4), and this would be strange if the same is valid for the first return map T_k . Both these problems were solved in the work [8]. However, it was required a development of new technics, in particular, the construction of finite-smooth analogous of the analytical Birkhoff-Moser normal form for a saddle map [27]. First, it was shown in [8] that the intervals δ_k can intersect indeed and, moreover, they can be even nested. In the latter case *the phenomenon of global resonance*, discovered by S.Gonchenko and Shilnikov in [13, 14], can be observed when, in particular, the symplectic map f_0 can have simultaneously infinitely many single-round elliptic periodic orbits of *all successive periods* $k = \bar{k}, \bar{k} + 1, \dots$. Second, conditions of nondegeneracy of the resonance 1:4 in the first return maps were found.

In principle, these results were obtained by the way of more accurate calculations of the small terms α_k and $\nu_k(y)$ in the rescaled form of T_k . As result, the map of form (1) was deduced with $M_k = -d^{-1}\lambda^{-2k}(\mu - \alpha\lambda^k(1 + O(k\lambda^k))) + s_0 + O(k\lambda^k)$ and $\nu_k(y) = s_1\lambda^k y^3 + \lambda^{2k}O(y^4)$, where $d \neq 0, \alpha, s_0$ and s_1 are some coefficients (invariants of a homoclinic structure). Then we can immediately see that if $\mu = 0$ and $\alpha = 0$ (a codimension two bifurcation case), then $M = s_0 + O(k\lambda^k)$ and, hence, all maps T_k are “the same” – all of them are close to the same map

¹ The birth of 2-elliptic generic periodic orbits was proved in [5, 6] for the case of four-dimensional symplectic maps with homoclinic tangencies to saddle-focus fixed points.

² Note that an analogous problem was considered in [9, 10] when studying bifurcations of three-dimensional conservative flows with a homoclinic loop of a saddle-focus equilibrium.

$\bar{x} = y$, $\bar{y} = s_0 - x - y^2$. In this case, if $-1 < s_0 < 3$, every T_k has an elliptic fixed point (with φ close to $\arccos(1 - \sqrt{1 + s_0})$). Note that the cubic term s_1 responses for nondegeneracy of the resonance 1:4 (if $s_1\lambda^k > 0$ the point is a saddle with 8 separatrices, if $s_1\lambda^k < 0$ the point is of elliptic type, i.e. KAM-stable).

In this paper we consider area preserving maps defined on a non-orientable surface \mathcal{M}_2 and study their homoclinic bifurcations.³ As in the paper [8], we construct bifurcation diagrams for single-round periodic orbits and study the phenomenon of “global resonance”. First of all, we establish the theorem on cascade of elliptic periodic orbits, Theorem 1. However, we note that, unlike the symplectic case, the first return maps T_k can be nonorientable. We note that, in the case under consideration, the maps T_k are rescaled to a map asymptotically close (as $k \rightarrow \infty$) to the nonorientable conservative Hénon map $\bar{x} = y$, $\bar{y} = M + x - y^2$ (see Lemma 1). Thus, T_k can not have elliptic fixed points. However, T_k^2 can have and, therefore, cascades from Theorem 1 relate to double-round elliptic points. In Theorem 2 we generalize results of Theorem 1 for two-parameter families $f_{\mu,\alpha}$ with governing parameters μ and α (see formula (11) for α) and deduce the result, Theorem 3, about the existence of infinitely many double-round elliptic periodic orbits of all successive even periods beginning from some number.

We note also that the problem under consideration, as in [13, 14, 8], is related to the Poincaré conjecture [15] on the density of stable (elliptic for the two-dimensional case) periodic orbits in the phase space of non-integrable Hamiltonian systems. This Poincaré problem is wide open.⁴ Therefore, the above mentioned phenomenon of global resonance (the coexistence of elliptic periodic orbits of all periods) can be considered as quite relevant. There are few explicit criteria for the existence of infinitely many elliptic periodic orbits, and this gives a rare opportunity for the construction of Hamiltonian systems with a given structure of stable modes. From this point of view, it is important that in the case considered in our paper, the global resonance is organized in a quite different way: we give an explicit criterion for the existence of elliptic periodic orbits of *all even periods*. It is worth mentioning that related problems on the coexistence of large number of elliptic periodic orbits in Hamiltonian systems are quite popular, see e.g. the paper [20] and the corresponding references in it.

Note also that non-orientable APMs appear naturally when restricting a multidimensional symplectic map onto a two-dimensional non-orientable surface as well as when factorizing orientable symplectic maps by a discrete symmetry group. For example, when a map (not necessarily symplectic one) admits certain symmetries, it can be expressed as some even power of a simpler non-orientable map and, thus, the study of the latter map becomes very important, see e.g. [21, 22].

³Notice that these maps cannot be symplectic due to the lack of orientation on \mathcal{M}_2 .

⁴In this connection, we note that for (multidimensional) C^1 -smooth symplectic diffeomorphisms given on compact manifolds, the following properties are generic: 1) hyperbolic periodic points are dense in the phase space, [16]; 2) every hyperbolic periodic orbit has a transverse homoclinic point in any neighborhood of any point of the phase space, [17, 18]; 3) if a symplectic diffeomorphism f is not Anosov, then the 1-elliptic periodic points of f are dense in the phase space, [4]. It is worth remarking that the above-mentioned C^1 generic properties can become nontypical if one requires a greater smoothness. Thus, for example, according to the KAM-theory, elliptic periodic orbits of C^r -smooth two-dimensional symplectic diffeomorphisms are generically stable at $r \geq 5$ ([19]), whereas, by property 2), all periodic elliptic orbits of generic C^1 -diffeomorphisms are unstable.

2 Statement of the problem and main results.

Consider a C^r -smooth ($r \geq 3$) APM f_0 defined on a *non-orientable* surface \mathcal{M}_2 and satisfying the following conditions.

- A.** f_0 has a saddle fixed point O with multipliers λ and λ^{-1} , where $|\lambda| < 1$.
- B.** f_0 has a homoclinic orbit Γ_0 where the stable and unstable invariant manifolds of the saddle O have a quadratic tangency.

Condition **A** means that there exists a neighborhood (disk) U_0 of the point O in which the map $T_0 = f_0|_{U_0}$ is symplectic, i.e., area-preserving and orientable. The map T_0 is called the *local map*, it is a saddle map that has the point O as a fixed one. By condition **B**, the stable W^s and unstable W^u invariant manifolds of O intersect non-transversally at the points of Γ_0 . Infinitely many such homoclinic points are inside U_0 . We take a pair of these points: $M^+ \in W_{loc}^s$ and $M^- \in W_{loc}^u$. Then a natural number n_0 exists such that $M^+ = f_0^{n_0}(M^-)$. Let $\Pi^+ \subset U_0$ and $\Pi^- \subset U_0$ be sufficiently small neighborhoods of the points M^+ and M^- , respectively. The map $T_1 = f_0^{n_0}|_{\Pi^-} : \Pi^- \rightarrow \Pi^+$ is called the *global map*. Evidently, the map T_1 is area-preserving (in the symplectic coordinates on U_0). However, emphasizing the non-orientability of phase space, we assume that

- C.** The map T_0 is symplectic in U_0 , whereas the map T_1 is area-preserving and non-orientable.

Let \mathcal{H}_0 be a (codimension one) bifurcation manifold composed of area-preserving C^r -maps on \mathcal{M}_2 close to f_0 and such that every map of \mathcal{H}_0 has a nontransversal homoclinic orbit close to Γ_0 . Let f_ε be a family of area-preserving C^r -maps that contains the map f_0 at $\varepsilon = 0$. We suppose that the family depends smoothly on parameters $\varepsilon = (\varepsilon_1, \dots, \varepsilon_m)$ and satisfies the following condition.

- D.** The family f_ε is transverse to \mathcal{H}_0 at $\varepsilon = 0$.

Let U be a small neighborhood of $O \cup \Gamma_0$ which consists of the small disk U_0 containing O and a number of small disks surrounding those points of Γ_0 that do not lie in U_0 (see Figure 1).

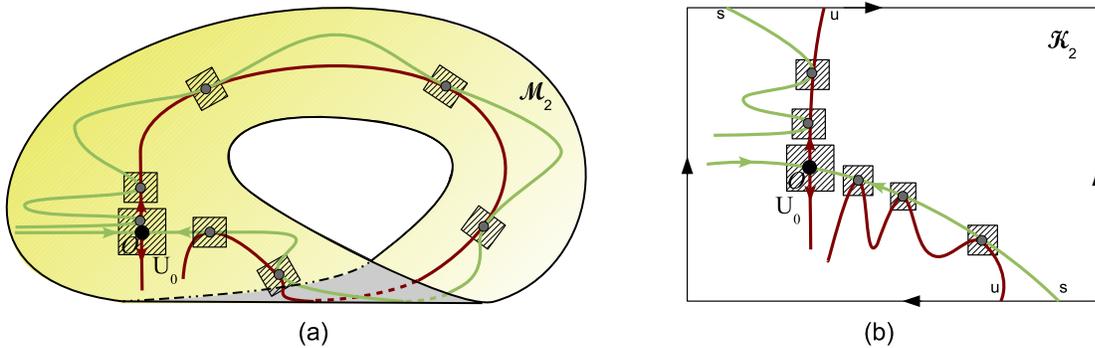


Figure 1: An example of non-orientable APM (a) on the Möbius band, (b) on the Klein bottle having a quadratic homoclinic tangency at the points of a homoclinic orbit Γ_0 . Some of these homoclinic points are shown as grey circles. Also a small neighborhood of the set $O \cup \Gamma_0$ is shown as the union of a number of “squares”.

Definition 1. A periodic or homoclinic orbit entirely lying in U is called p -round if it has exactly p intersection points with any disk of the set $U \setminus U_0$.

In this paper we study bifurcations of *single-round* ($p = 1$) *periodic orbits* in the families f_ε . Note that every point of such an orbit can be considered as a fixed point of the corresponding *first return map*. Such a map is usually constructed as a superposition $T_k = T_1 T_0^k$ of two maps $T_0 \equiv T_0(\varepsilon) = f_\varepsilon|_{U_0}$ and $T_1 \equiv T_1(\varepsilon) = f_\varepsilon^{n_0} : \Pi^- \rightarrow U_0$. Thus, any fixed point of T_k is a point of a single-round periodic orbit for f_ε with period $k + n_0$. We will study maps T_k for all sufficiently large integer k .

Condition D means that one can introduce in U_0 some *canonical coordinates* (x, y) such that $J(T_0) \equiv +1$ and $J(T_1) \equiv -1$, where $J(T)$ is the Jacobian of map T . Moreover, we can introduce coordinates (x, y) in such a way that the local map T_0 can be written in one of the so-called *finitely smooth normal forms* provided by the following lemma.

Lemma 1. [8] For any given integer n (such that $n < r/2$ or n is arbitrary for $r = \infty$ or $r = \omega$ - the real analytic case), there is a canonical change of coordinates, of class C^r for $n = 1$ or C^{r-2n} for $n \geq 2$, that brings T_0 to the following form

$$\begin{aligned}\bar{x} &= \lambda x (1 + \beta_1 \cdot xy + \dots + \beta_n \cdot (xy)^n) + x^{n+1} y^n O(|x| + |y|), \\ \bar{y} &= \lambda^{-1} y \left(1 + \hat{\beta}_1 \cdot xy + \dots + \hat{\beta}_n \cdot (xy)^n \right) + x^n y^{n+1} O(|x| + |y|).\end{aligned}\tag{2}$$

The smoothness of these coordinate changes with respect to parameters can be decreased by 2 unities, i.e., it is C^{r-2} for $n = 1$ or C^{r-2n-2} for $n \geq 2$, respectively.

In these coordinates, the equations of $W_{loc}^s \cap U_0$ and $W_{loc}^u \cap U_0$ are $y = 0$ and $x = 0$, respectively. Moreover, the normal forms (2) are very suitable for effective calculation of maps $T_0^k : (x_0, y_0) \rightarrow (x_k, y_k)$ with sufficiently large integer k . Indeed, the following result is valid.

Lemma 2. [8] Let T_0 be given by (2), then the map T_0^k can be written, for any integer k , in the so-called cross-form:

$$\begin{aligned}x_k &= \lambda^k x_0 \cdot R_n^{(k)}(x_0 y_k, \varepsilon) + \lambda^{(n+1)k} P_n^{(k)}(x_0, y_k, \varepsilon), \\ y_0 &= \lambda^k y_k \cdot R_n^{(k)}(x_0 y_k, \varepsilon) + \lambda^{(n+1)k} Q_n^{(k)}(x_0, y_k, \varepsilon),\end{aligned}\tag{3}$$

where

$$R_n^{(k)} \equiv 1 + \tilde{\beta}_1(k) \lambda^k x_0 y_k + \dots + \tilde{\beta}_n(k) \lambda^{nk} (x_0 y_k)^n,\tag{4}$$

$\tilde{\beta}_i(k)$, $i = 1, \dots, n$, are some polynomials (of degree i) with respect to k with coefficients depending on β_1, \dots, β_i , e.g. $\tilde{\beta}_1 = \beta_1 k$, $\tilde{\beta}_2 = \beta_2 k - \frac{1}{2} \beta_1^2 k^2$, ..., and the functions $P_n^{(k)}, Q_n^{(k)} = o(x_0^n y_k^n)$ are uniformly bounded in k along with all their derivatives with respect to coordinates up to order either $(r - 2)$ for $n = 1$ or $(r - 2n - 1)$ for $n \geq 2$.

Remark 3. 1) The normal form of the first order ($n = 1$) for T_0

$$\begin{aligned}\bar{x} &= \lambda x (1 + \beta_1 \cdot xy) + x^2 y O(|x| + |y|), \\ \bar{y} &= \lambda^{-1} y (1 - \beta_1 \cdot xy) + x y^2 O(|x| + |y|)\end{aligned}\tag{5}$$

is well known from [7, 24] where it was proved the existence of normalizing C^{r-1} -coordinates. The existence of C^r -smooth canonical changes of coordinates (which are C^{r-2} -smooth with respect to parameters) bringing a symplectic saddle map to form (5) was proved in [25].

2) Note that form (2) can be considered as a finitely smooth approximation of the analytical Moser normal form

$$\bar{x} = \lambda(\varepsilon)x \cdot B(xy, \varepsilon), \quad \bar{y} = \lambda^{-1}(\varepsilon)y \cdot B^{-1}(xy, \varepsilon), \quad (6)$$

taking place for $\lambda > 0$ [27], where $B(xy, \varepsilon) = 1 + \beta_1 \cdot xy + \dots + \beta_n \cdot (xy)^n + \dots$. Since the form (6) is integrable (e.g. it has integral xy), one can easily write the corresponding formula (5) for this case, see [11].

In the coordinates of Lemma 1, we can write $M^+ = (x^+, 0), M^- = (0, y^-)$. Without loss of generality, we assume that $x^+ > 0$ and $y^- > 0$. Let the neighborhoods Π^+ and Π^- of the homoclinic points M^+ and M^- , respectively, be sufficiently small such that $T_0(\Pi^+) \cap \Pi^+ = \emptyset, T_0^{-1}(\Pi^-) \cap \Pi^- = \emptyset$. Then, as usual (see e.g. [1, 26]), the map from Π^+ into Π^- by orbits of T_0 is defined, for all sufficiently small ε , on the set consisting of infinitely many strips $\sigma_k^0 \equiv \Pi^+ \cap T_0^{-k}\Pi^-$, $k = \bar{k}, \bar{k} + 1, \dots$. The image of σ_k^0 under T_0^k is the strip $\sigma_k^1 = T_0^k(\sigma_k^0) \equiv \Pi^- \cap T_0^k\Pi^+$. As $k \rightarrow \infty$, the strips σ_k^0 and σ_k^1 accumulate on W_{loc}^s and W_{loc}^u , respectively.

We can write the global map $T_1(\varepsilon) : \Pi^- \rightarrow \Pi^+$ as follows (in the coordinates of Lemma 1)

$$\bar{x} - x^+ = F(x, y - y^-, \varepsilon), \quad \bar{y} = G(x, y - y^-, \varepsilon), \quad (7)$$

where $F(0) = 0, G(0) = 0$. Besides, we have that $G_y(0) = 0, G_{yy}(0) = 2d \neq 0$ which follows from the fact (condition B) that at $\varepsilon = 0$ the curve $T_1(W_{loc}^u) : \{\bar{x} - x^+ = F(0, y - y^-, 0), \bar{y} = G(0, y - y^-, 0)\}$ has a quadratic tangency with $W_{loc}^s : \{\bar{y} = 0\}$ at M^+ . When the parameters ε vary this tangency can split and, moreover, by condition C, we can introduce the corresponding splitting parameter as $\mu \equiv G(0, 0, \varepsilon)$. Accordingly, we can write

$$\begin{aligned} F(x, y - y^-, \varepsilon) &= ax + b(y - y^-) + e_{20}x^2 + e_{11}x(y - y^-) + e_{02}(y - y^-)^2 + h.o.t., \\ G(x, y - y^-, \varepsilon) &= \mu + cx + d(y - y^-)^2 + f_{20}x^2 + f_{11}x(y - y^-) + f_{30}x^3 \\ &\quad + f_{21}x^2(y - y^-) + f_{12}x(y - y^-)^2 + f_{03}(y - y^-)^3 + h.o.t., \end{aligned} \quad (8)$$

where the coefficients a, b, \dots, f_{03} (as well as x^+ and y^-) depend smoothly on ε . Note also that

$$J(T_1) = \det \begin{pmatrix} F_x & F_y \\ G_x & G_y \end{pmatrix} \equiv -1 \quad (9)$$

since T_1 is non-orientable map by condition C. In particular, we have

$$\begin{aligned} bc &\equiv +1, \\ \tilde{R} &= (2a + 2e_{02}/bd - bf_{11}/d) \equiv 0 \end{aligned} \quad (10)$$

It is clear from (7) and (8) that μ is the parameter of splitting of manifolds $W^s(O_\varepsilon)$ and $W^u(O_\varepsilon)$ with respect to the homoclinic point M^+ . Indeed, the curve $l_u = T_1(W_{loc}^u \cap \Pi^-)$ has the equation $l_u : \bar{y} = \mu + \frac{d}{b^2}(\bar{x} - x^+)^2(1 + O(\bar{x} - x^+))$. Since the equation of W_{loc}^s is $y = 0$ for all (small) ε , it implies that the manifolds $T_1(W_{loc}^u)$ and W_{loc}^s do not intersect for $\mu d > 0$, intersect transversally at two points for $\mu d < 0$, and have a quadratic tangency (at M^+) for $\mu = 0$. Besides, since the strips σ_k^1 accumulate on the segment $W_{loc}^u \cap \Pi^-$ as $k \rightarrow \infty$, it follows that the images $T_1(\sigma_k^1)$ of σ_k^1 under T_1 have a horseshoe form and, moreover, horseshoes $T_1(\sigma_k^1)$ accumulate on l_u as $k \rightarrow \infty$. Therefore, the first return maps $T_k = T_1 T_0^k : \sigma_k^0 \rightarrow \sigma_k^0$ are, in fact, conservative horseshoe maps with the Jacobian -1 . Geometrically, the action of this map looks as in Figure 2.

When μ varies near zero infinitely many bifurcations of horseshoes creation (destruction) occur. In this paper we study these bifurcations and show that they include birth (disappearance) of *elliptic periodic points*.

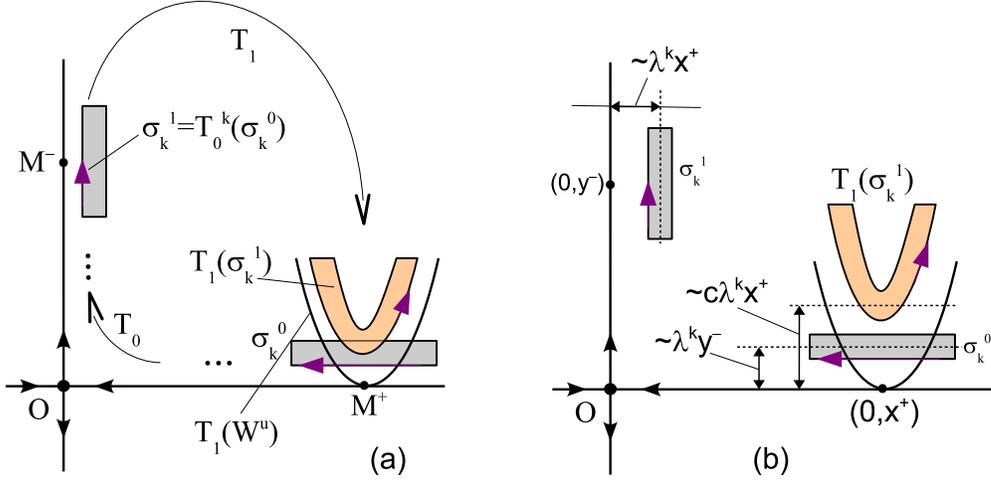


Figure 2: (a) Actions of the local and global maps T_0 and T_1 in U_0 . Under the map T_0^k some strip σ_k^0 near M^+ is transformed into a strip σ_k^1 lying near M^- . Under the global map T_1 the strip σ_k^1 is transformed into a horseshoe $T_1(\sigma_k^1)$. The latter map is non-orientable, i.e., changes the orientation of the boundary of the horseshoe with respect to the orientation of the pre-image σ_k^1 . The direction of the orientation is indicated by the arrows. We assume that T_0 is orientable, therefore, the boundary orientation of σ_k^0 and σ_k^1 is the same. (b) To a reciprocal position of the strips σ_k^0 and horseshoes $T_1(\sigma_k^1)$. The strips σ_k^0 and σ_k^1 are posed on a distance $\lambda^k y^-(1 + \dots)$ from W_{loc}^s and $\lambda^k x^+(1 + \dots)$ from W_{loc}^u , respectively. Hence, the top of horseshoe $T_1(\sigma_k^1)$ are posed on a distance $c\lambda^k x^+(1 + \dots)$ from W_{loc}^s .

However, we can also see that these horseshoe bifurcations must have different scenarios depending on the type of the initial homoclinic tangency. Indeed, at $\mu = 0$ the character of the reciprocal position of the strips σ_k^0 and their horseshoes $T_1(\sigma_k^1)$ is essentially defined by the signs of the parameters λ, c and d . Moreover, by this feature, we can select 6 different cases of APMs with quadratic homoclinic tangencies. The corresponding examples are shown in Figures 3 and 4. Note that in the cases with $\lambda < 0$ we can always consider d to be positive: if d is negative for the given pair of homoclinic points, M^+ and M^- , we can take another pair of points, like $\{T_0(M^+), M^-\}$ or $\{M^+, T_0^{-1}(M^-)\}$, for which the corresponding d' becomes positive.

Note that in the cases with $c < 0$, see Figure 3, the reciprocal position of all the strips σ_j^0 and their horseshoes $T_1(\sigma_j^1)$ at $\mu = 0$ is defined quite simply: $\sigma_j^0 \cap T_1(\sigma_j^1) = \emptyset$ if $\lambda > 0, d < 0$; the strips σ_j^0 and horseshoes $T_1(\sigma_j^1)$ have regular intersections if $\lambda > 0, d > 0$; the corresponding intersections are either regular for even j or empty for odd j if $\lambda < 0, d > 0$. Recall that regular intersection means here (by [28] and [29]) that the set $\sigma_j^0 \cap T_1(\sigma_j^1)$ consists of two connected components and, moreover, the first return map $T_j \equiv T_1 T_0^j : \sigma_j^0 \mapsto \sigma_j^0$ is the *Smale horseshoe map*: its nonwandering set Ω_j is hyperbolic and $T_j|_{\Omega_j}$ is topologically conjugate to the Bernoulli shift with two symbols (for more details see [29, 8]). Therefore, we can say that every map f_0 in the case $c < 0, d > 0$ has infinitely many horseshoes Ω_j , where j runs for all sufficiently large positive integers (respectively, even positive integers) in the case $\lambda > 0$ (respectively, in the case $\lambda < 0$). On the other hand, every map f_0 with $\lambda > 0, c < 0, d < 0$ has no horseshoes at all (in a small neighborhood U).

In the cases of homoclinic tangencies with $c > 0$, see Figure 4, the reciprocal position of the strips σ_j^0 and horseshoes $T_1(\sigma_j^1)$ depends also on other invariant quantities of the homoclinic

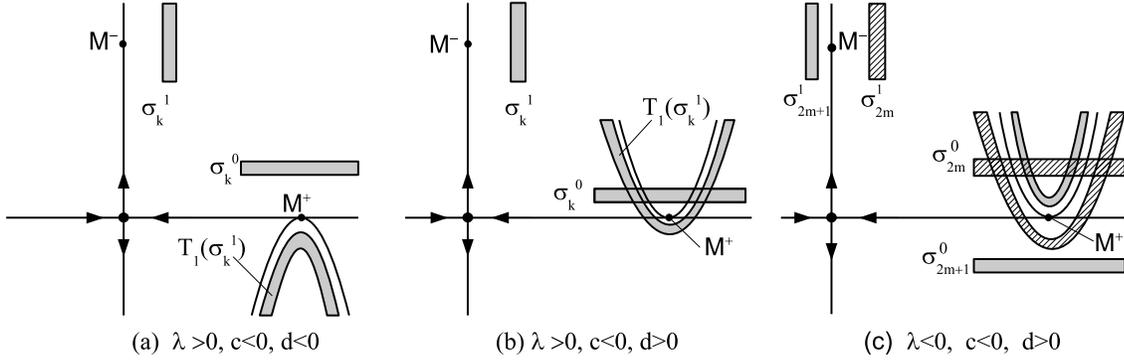


Figure 3: Types of APMs with a homoclinic tangency for $c < 0$.

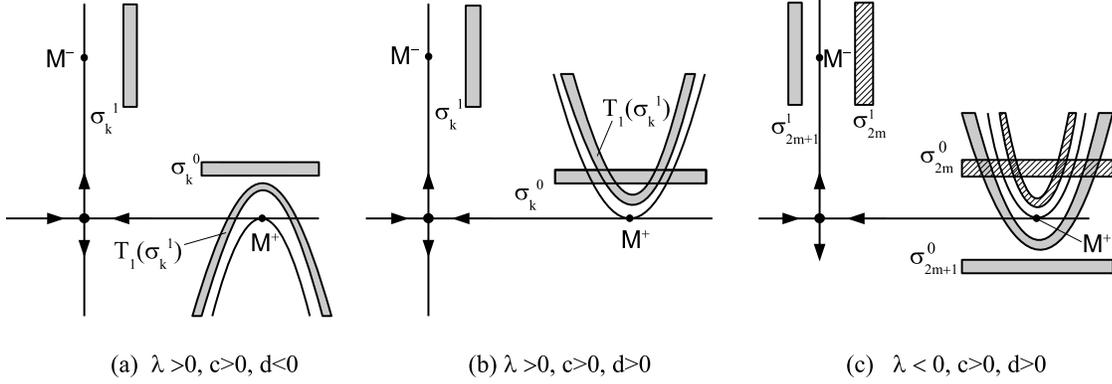


Figure 4: Types of APMs with a homoclinic tangency for $c > 0$.

structure, the most important being, [13, 14, 28],

$$\alpha = \frac{cx^+}{y^-} - 1. \quad (11)$$

First of all, notice that the sign of α is very important. For example, in Figure 5 it is shown the reciprocal position of the strips σ_j^0 and horseshoes $T_1(\sigma_j^1)$ (with sufficiently large j) for various values of α for the case $\lambda > 0, c > 0, d > 0$. Thus, we can see that⁵

- if $\alpha < 0$, then f_0 has infinitely many horseshoes Ω_j ;
- if $\alpha > 0$, then there exists a neighborhood $U(O \cap \Gamma_0)$ in which the dynamics of f_0 is trivial: only orbits O and Γ_0 do not leave U under iterations of f_0 .

Thus, $\alpha = 0$ is a bifurcation value, since infinitely many horseshoes appear (disappear) when varying α near zero (even without splitting the initial tangency).

⁵These results can be easily explained by using the geometry of Figure 2. Thus, if $c\lambda^k x^+ > \lambda^k y^-$, i.e., $\alpha > 0$, the top of the horseshoe is above the strip σ_k^0 . This means that f_0 has no horseshoes and the dynamics is trivial. However, if $c\lambda^k x^+ < \lambda^k y^-$, i.e., $\alpha < 0$, the top of the horseshoe is below the strip σ_k^0 . Geometrically, it means that f_0 has infinitely many horseshoes (for every sufficiently large k). A rigorous proof requires quite elaborate analytical considerations which are not presented here, see e.g. [8, 11, 12, 14].

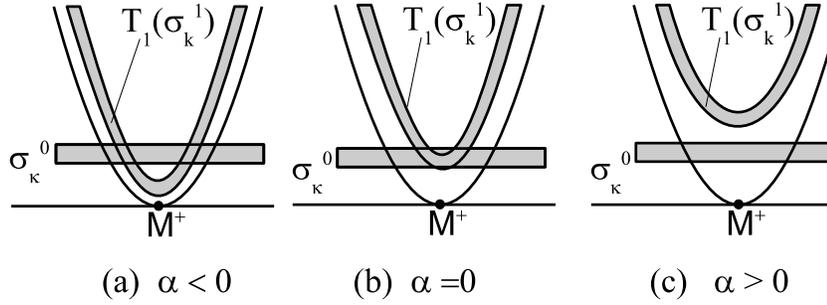


Figure 5: A horseshoe geometry of symplectic maps with a homoclinic tangency in the case $\lambda > 0, c > 0, d > 0$ for various α .

Thus, we can draw the following conclusions:

- 1) the cases of homoclinic tangencies with $c < 0$ or with $\alpha \neq 0$ at $c > 0$ are “ordinary” and it is sufficient to study bifurcations of single-round periodic orbits only within the framework of one parameter general families (with the parameter μ);
- 2) the cases of homoclinic tangencies with $\alpha = 0$ at $c > 0$ are “special” and it is necessary to consider at least two parameter general unfoldings (for example, with parameters μ and α).

In this paper we adhere to this approach and present the following three theorems as our main results in the case under consideration (APMs on non-orientable surfaces).

Theorem 1. *Let f_0 be an APM satisfying conditions A, B and D and f_μ be a one parameter family of APMs that unfolds generally (under condition C) at $\mu = 0$ the quadratic homoclinic tangency. Then for any interval $(-\mu_0, \mu_0)$ of values of μ , there exists a positive integer \bar{k} such that the following holds:*

1. *All APMs close to f_0 have no single-round elliptic periodic orbits, while there exist intervals $\mathbf{e}_k^2 \subset I_\varepsilon$, $k = \bar{k}, \bar{k} + 1, \dots$, such that the map f_μ has at $\mu \in \mathbf{e}_k^2$ a double-round elliptic periodic orbit, of period $2(k + n_0)$, which corresponds to a 2-periodic point of the first return map T_k .*
2. *The intervals \mathbf{e}_k^2 accumulate at $\mu = 0$ as $k \rightarrow \infty$ and do not intersect for sufficiently large and different integer k if $c < 0$, or $\alpha \neq 0$ in the case $c > 0$.*
3. *Any interval \mathbf{e}_k^2 has border points $\mu = \mu_k^{2+}$ and $\mu = \mu_k^{2-}$ where the map f_μ has a single-round periodic orbit (of period $(k + n_0)$) with multipliers $+1$ and -1 at $\mu = \mu_k^{2+}$ and a double-round periodic orbit (of period $2(k + n_0)$) with double multiplier -1 at $\mu = \mu_k^{2-}$. See Figure 6.*
4. *The angular argument φ of the multipliers $e^{\pm i\varphi}$ of the elliptic periodic orbits for $\mu \in \mathbf{e}_k^2$ depends monotonically on μ and the elliptic orbit is generic (KAM-stable) for all such μ , except for those $\varphi = \varphi(\mu)$ such that $\varphi(\mu) = \frac{\pi}{2}, \frac{2\pi}{3}, \arccos(-\frac{1}{4})$.*

Note that Theorem 1 does not give answer to the question of the mutual position of the intervals \mathbf{e}_k^2 in the critical case $\alpha = 0$. But this value of α is quite important, since it is related to the coexistence of elliptic orbits of different periods. Therefore, we assume now that f_0 is a map satisfying conditions A, B and D with $\alpha = 0$ and consider a two parameter family $\{f_{\mu,\alpha}\}$ which is a general unfolding for the initial tangency with $\alpha = 0$. Let D_ε be a sufficiently small neighborhood (of diameter $\varepsilon > 0$) of the origin in the parameter plane (μ, α) . Then the following result holds.

Theorem 2. *In D_ε , for any $\varepsilon > 0$, there exist infinitely many open domains E_k^2 (strips) such that if $(\mu, \alpha) \in E_k^2$, then the map $f_{\mu,\alpha}$ has a double-round elliptic orbit of period $2(k + n_0)$ (corresponding*

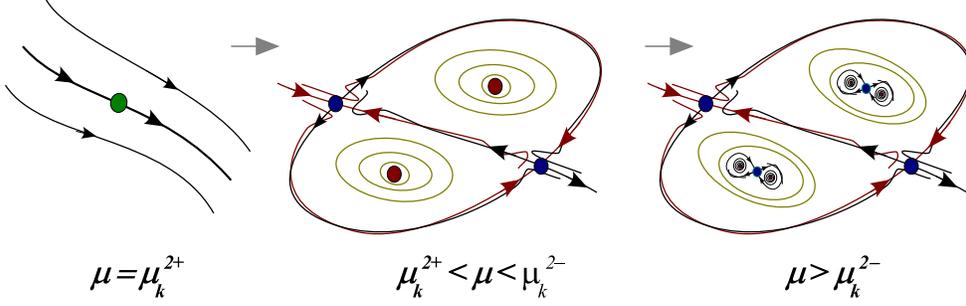


Figure 6: Bifurcation scenarios in the first return maps T_k according to item 3 of Theorem 1. We show here that the birth of the elliptic 2-periodic point takes place when increasing μ , while for some types of homoclinic tangencies it can occur at decreasing μ . Since T_k is a non-orientable map, then the value $\mu = \mu_k^{2+}$ corresponds to the appearance of a fixed point with multipliers $+1$ and -1 . This point bifurcates into four points, two saddle fixed ones and other two points forming an elliptic 2-periodic orbit, when $\mu \in e_k^2$. The value $\mu = \mu_k^{2-}$ corresponds to the period doubling bifurcation of this elliptic 2-periodic orbit.

to a elliptic 2-periodic orbit of the first return map T_k). The domains E_k^2 accumulate at the axis $\mu = 0$ as $k \rightarrow \infty$, all of them are mutually crossed and intersect the axis $\mu = 0$. Every domain E_k^2 has two smooth boundaries, the bifurcation curves L_k^{2+} and L_k^{2-} , which correspond, respectively, to the existence of a single-round nondegenerate periodic orbit with double multipliers $+1$ and a double-round nondegenerate periodic orbit with double multipliers -1 .

In Figure 7 some qualitative illustrations to Theorem 2 are shown for the cases where (a) $\lambda > 0, c > 0, d > 0$ and (b) $\lambda < 0, c > 0, d > 0$.

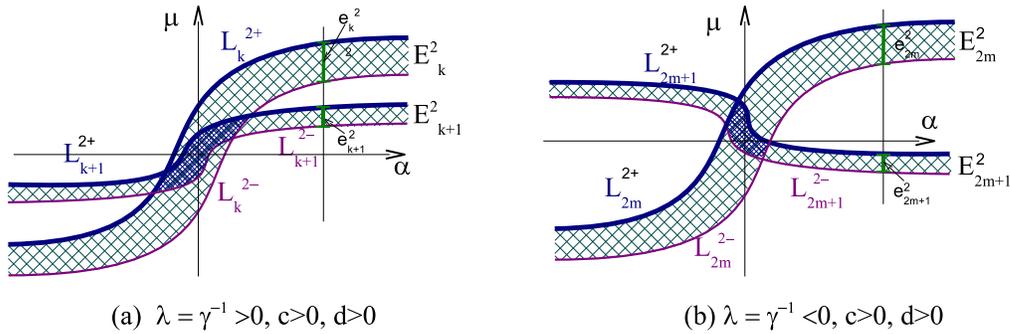


Figure 7: Elements of the bifurcation diagrams for the families $f_{\mu, \alpha}$.

We introduce now the following quantity

$$s_0 = dx^+(ac + f_{20}x^+) - \frac{1}{4}(f_{11}x^+)^2, \quad (12)$$

which is calculated through the coefficients of the global map T_1 , see formula (8), and plays an important role in the global dynamics of the map f_0 with $\alpha = 0$.

Theorem 2 shows that elliptic (double-round) periodic orbits of different periods can coexist when values of μ and α vary near zero. Moreover, infinitely many such orbits can coexist, in principle, at the global resonance $\mu = 0, \alpha = 0$. The following theorem give us sufficient conditions for this phenomenon.

Theorem 3. *Let f_0 be an APM satisfying conditions A, B and D. We assume also that the resonant condition $\alpha = 0$ takes place for f_0 . Then, if s_0 (see formula (12)) is such that $-1 < s_0 < 0$, then there exists a positive integer \bar{k} such that f_0 has infinitely many double-round elliptic periodic orbits of all successive even periods $2(k + n_0)$, where $k \geq \bar{k}$. Moreover, if $s_0 \neq -\frac{1}{2}; -\frac{1}{\sqrt{2}}; -\frac{5}{8}$, all these elliptic periodic orbits are generic (KAM-stable).*

In the rest part of the paper we prove these and related results.

3 Rescaling Lemma.

In principle, for the study of bifurcations in the first return map $T_k = T_1 T_0^k$ we could write it in the initial coordinates using formulas (8) and (3) for the maps T_1 and T_0^k , respectively, and, after, work with the obtained formulas. However, there is a more effective way for studying bifurcations. Namely, we can bring maps T_k to some unified form for all large k using the so-called rescaling method as it has been done in many papers.⁶ After this, we can study (one time) bifurcations in the unified map and “project” the obtained results onto the first return maps T_k for various k . This “universal” map is deduced in the following lemma.

Lemma 1. *Let f_ε be the family under consideration satisfying conditions A–D. Then, for every sufficiently large k , the first return map $T_k : \sigma_k^0 \rightarrow \sigma_k^0$ can be brought, by a linear transformation of coordinates and parameters, to the following form*

$$\begin{aligned} \bar{X} &= Y, \\ \bar{Y} &= M + X - Y^2 + \frac{f_{03}}{d^2} \lambda^k Y^3 + k \lambda^{2k} \varepsilon_k(Y, M). \end{aligned} \quad (13)$$

Map (13) is defined on some asymptotically large domain covering in the limit $k \rightarrow +\infty$ all finite values of X, Y and M , the function $\varepsilon_k(Y, M)$ is uniformly bounded in k jointly with all their derivatives up to order $(r - 4)$, and the following formula takes place for M :

$$M = -d(1 + \nu_k^1) \lambda^{-2k} (\mu + \lambda^k (cx^+ - y^-)(1 + k\beta_1 \lambda^k x^+ y^-)) - s_0 + \nu_k^2; \quad (14)$$

with the coefficient s_0 satisfying (12) and where $\nu_k^1 = O(\lambda^k), \nu_k^2 = O(k\lambda^k)$ are some asymptotically small coefficients.

Proof. We will use the representation of the symplectic map T_0 in the “second normal form”, i.e., in form (2) for $n = 2$.⁷ Then the map $T_0^k : \sigma_k^0 \rightarrow \sigma_k^1$, for all sufficiently large k , can be written in the following form

$$x_k = \lambda^k x_0 (1 + \beta_1 k \lambda^k x_0 y_k) + O(k^2 \lambda^{3k}), \quad y_0 = \lambda^k y_k (1 + \beta_1 k \lambda^k x_0 y_k) + O(k^2 \lambda^{3k}). \quad (15)$$

⁶see e.g. the papers [10, 7, 11, 5, 30, 12, 14] where the rescaling method was applied for the conservative case.

⁷Clearly, we lose a little in a smoothness, since the second order normal form is C^{r-2} only, see Lemma 1. However, we get more important information on form of the first return maps. On the other hand, our considerations cover also the C^∞ and real analytical cases.

Then, using formulae (8) and (15), we can write the first return map $T_k : \sigma_k^0 \rightarrow \sigma_k^0$ in the following form

$$\begin{aligned} \bar{x} - x^+ &= a\lambda^k x + b(y - y^-) + e_{02}(y - y^-)^2 + \\ &\quad + O(k|\lambda|^{2k}|x| + |y - y^-|^3 + |\lambda|^k|x||y - y^-|), \\ \lambda^k \bar{y} (1 + k\lambda^k \beta_1 \bar{x} \bar{y}) + k\lambda^{3k} O(|\bar{x}| + |\bar{y}|) &= \\ &= \mu + c\lambda^k x (1 + k\lambda^k \beta_1 xy) + d(y - y^-)^2 + \lambda^{2k} f_{02} x^2 + \\ + \lambda^k f_{11} (1 + k\lambda^k \beta_1 xy) x (y - y^-) + \lambda^k f_{12} x (y - y^-)^2 + f_{03} (y - y^-)^3 + \\ &\quad + O((y - y^-)^4 + \lambda^{2k}|x||y - y^-| + k|\lambda|^{3k}|x| + k\lambda^{2k}|x||y - y^-|^2), \end{aligned} \quad (16)$$

where $x = x_0, y = y_k$.

Below, we will denote by $\alpha_k^i, i = 1, 2, \dots$, some coefficients asymptotically small in k such that $\alpha_k^i = O(k\lambda^k)$. Now we shift the coordinates

$$\eta = y - y^-, \quad \xi = x - x^+ - \lambda^k x^+ (a + \alpha_k^1),$$

in order to cancel the constant term (independent of coordinates) in the first equation of (16). Thus, (16) is recast as follows

$$\begin{aligned} \bar{\xi} &= a\lambda^k \xi + b\eta + e_{02}\eta^2 + O(k\lambda^{2k}|\xi| + |\eta|^3 + |\lambda|^k O(|\xi||\eta|)), \\ \lambda^k \bar{\eta} (1 + \alpha_k^2) + k\lambda^{2k} O(|\bar{\xi}| + \bar{\eta}^2) + k\lambda^{3k} O(|\bar{\eta}|) &= \\ &= M_1 + c\lambda^k \xi (1 + \alpha_k^3) + \eta^2 (d + \lambda^k f_{12} x^+) + \lambda^k \eta (f_{11} x^+ + \alpha_k^4) + \lambda^k f_{11} \xi \eta + f_{03} \eta^3 + \\ &\quad + O(\eta^4 + k|\lambda|^{3k}|\xi| + k\lambda^{2k}(\xi^2 + \eta^2) + \lambda^k |\xi| \eta^2), \end{aligned} \quad (17)$$

where

$$M_1 = \mu + \lambda^k (cx^+ - y^-) (1 + k\lambda^k \beta_1 x^+ y^-) + \lambda^{2k} x^+ (ac + f_{02} x^+) + O(k\lambda^{3k}). \quad (18)$$

Now, we rescale the variables:

$$\xi = -\frac{b(1 + \alpha_k^2)}{d + \lambda^k f_{12} x^+} \lambda^k u, \quad \eta = -\frac{1 + \alpha_k^2}{d + \lambda^k f_{12} x^+} \lambda^k v. \quad (19)$$

System (17) in coordinates (u, v) is rewritten in the following form

$$\begin{aligned} \bar{u} &= v + a\lambda^k u - \frac{e_{02}}{bd} \lambda^k v^2 + O(k\lambda^{2k}), \\ \bar{v} &= M_2 + u(1 + \alpha_k^5) - v^2 + \\ &\quad + v(f_{11} x^+ + \alpha_k^6) - \frac{f_{11} b}{d} \lambda^k uv + \frac{f_{03}}{d^2} \lambda^k v^3 + O(k\lambda^{2k}), \end{aligned} \quad (20)$$

where

$$M_2 = -\frac{d + \lambda^k f_{12} x^+}{1 + \alpha_k^2} \lambda^{-2k} M_1.$$

The following shift of coordinates (we remove the terms linear in v from the second equation)

$$u_{new} = u - \frac{1}{2} (f_{11} x^+ + \alpha_k^6), \quad v_{new} = v - \frac{1}{2} (f_{11} x^+ + \alpha_k^6),$$

brings map (20) to the following form

$$\begin{aligned}\bar{u} &= v + a\lambda^k u - \frac{e_{02}}{bd}\lambda^k v^2 + O(k\lambda^{2k}), \\ \bar{v} &= M_3 + u - v^2 - \frac{f_{11}b}{d}\lambda^k uv + \frac{f_{03}}{d^2}\lambda^k v^3 + O(k\lambda^{2k}),\end{aligned}\tag{21}$$

where

$$M_3 = M_2 + \frac{(f_{11}x^+)^2}{4}.$$

Now, we make the following linear change of coordinates

$$x = u + \tilde{v}_k^1 v, \quad y = v - \tilde{v}_k^2 u,\tag{22}$$

where

$$\tilde{v}_k^1 = -\frac{e_{02}}{bd}\lambda^k, \quad \tilde{v}_k^2 = -\frac{e_{02}}{bd}\lambda^k - a\lambda^k.\tag{23}$$

Then, system (21) is rewritten as

$$\begin{aligned}\bar{x} &= y + M_3 \tilde{v}_k^1 + O(k\lambda^{2k}), \\ \bar{y} &= M_3 + x - y^2 + a\lambda^k y - \tilde{R}\lambda^k xy + \frac{f_{03}}{d^2}\lambda^k y^3 + O(k\lambda^{2k}),\end{aligned}\tag{24}$$

where $\tilde{R} = (2a + 2e_{02}/bd - bf_{11}/d) \equiv 0$ by (10). Hence, map (24) has the following form

$$\begin{aligned}\bar{x} &= y + M_3 \tilde{v}_k^1 + O(k\lambda^{2k}), \\ \bar{y} &= M_3 + x - y^2 + a\lambda^k y + \frac{f_{03}}{d^2}\lambda^k y^3 + O(k\lambda^{2k}),\end{aligned}\tag{25}$$

Finally, we make one more shift of coordinates

$$X = x - \frac{1}{2}a\lambda^k - \tilde{v}_k^1 M_3, \quad Y = y - \frac{1}{2}a\lambda^k,$$

in order to cancel in (25) the constant term in the first equation and the term linear in y in the second equation. After this, we obtain the final form (13) of map T_k in the rescaled coordinates where formula (14) takes place for the parameter M . \square

4 Proofs of the main results.

The bifurcations in the first return maps T_k can be studied now by using their normal forms deduced from the rescaling Lemma 1. Since these normal forms coincide up to asymptotically small terms as $k \rightarrow \infty$ with the non-orientable conservative Hénon map, we recall in the next section some necessary results on bifurcations of fixed points in one parameter families of conservative Hénon map in the non-orientable case.

4.1 On bifurcations of fixed points in the conservative non-orientable Hénon maps.

The rescaling Lemma 1 shows that the unified limit form for the first return maps T_k is the non-orientable and conservative Hénon map

$$\bar{x} = y, \quad \bar{y} = M + x - y^2, \quad (26)$$

with Jacobian $J = -1$. Bifurcations of fixed points in the conservative Hénon family are well known.

Since the Hénon map (26) is not orientable, it cannot have elliptic fixed points. However, there exist elliptic 2-periodic orbits for $M \in (0, 1)$. The map has no fixed points for $M < 0$, it has one fixed point $\bar{O}(0, 0)$ with multipliers $\nu_1 = +1, \nu_2 = -1$ at $M = 0$ and two saddle fixed points $(\bar{O}_1(-\sqrt{M}, -\sqrt{M})$ and $\bar{O}_2(\sqrt{M}, \sqrt{M}))$ at $M > 0$. Besides, an elliptic 2-periodic orbit exists for $0 < M < 1$, consisting of the two points $p_1 = (-\sqrt{M}, \sqrt{M})$ and $p_2 = (\sqrt{M}, -\sqrt{M})$; the value $M = 1$ corresponds to a period doubling bifurcation of this orbit. Note that the elliptic 2-periodic orbit is generic for all $M \in (0, 1)$ except for $M = \frac{1}{2}$ and $M = \frac{3}{4}$ which correspond to the strong resonances $1 : 4$ and $1 : 3$, respectively, and $M = \frac{5}{8}$ which corresponds to the cancellation of the first Birkhoff coefficient at the cycle $\{p_1, p_2\}$, see [23].

It is also known (see, e.g., [31, 32]) that if $M > 5 + 2\sqrt{5}$ (this is only a sufficient condition), then the nonwandering set of map (26) is a Smale horseshoe which is non-orientable for this case.

4.2 Proof of Theorem 1.

The proof is deduced from the rescaling lemma 1. Indeed, since the bifurcations of fixed points of the Hénon map (26) are known, we can use this information directly to recover the bifurcations of the single-round periodic orbits in the family f_μ . We only need to know the relations between the parameters of the rescaled map (13) and the initial parameters (i.e., in fact, between M and μ).

In the case under consideration, the relations between M and μ are given by formula (14) from which we find μ as follows

$$\mu = -\lambda^k y^- \alpha (1 + k\beta_1 \lambda^k x^+ y^-) - \frac{1}{d} (M + s_0 + \hat{\rho}_k^1) \lambda^{2k}, \quad (27)$$

where $\hat{\rho}_k^1 = O(k\lambda^k)$ is some small coefficient and $\alpha = \frac{cx^+}{y^-} - 1$ (see formula (11)).

As it follows from Lemma 1, the conservative non-orientable Hénon map $\bar{x} = y, \quad \bar{y} = M + x - y^2$, where M satisfies (14), is the normal (rescaled) form for the first return maps T_k with all sufficiently large k . This Hénon map has no elliptic fixed points, however, there exists an elliptic 2-periodic orbit for $0 < M < 1$. Thus, we obtain, by (14), that the first return map T_k has a fixed point with multipliers $\nu_1 = +1, \nu_2 = -1$ (i.e., when $M = 0$) if

$$\mu = \mu_k^\pm = -\lambda^k y^- \alpha (1 + k\beta_1 \lambda^k x^+ y^-) - \frac{1}{d} (s_0 + \hat{\rho}_k) \lambda^{2k}, \quad (28)$$

and a 2-periodic orbit with multipliers $\nu_1 = \nu_2 = -1$ (i.e., when $M = 1$) if

$$\mu = \mu_k^{2-} = -\lambda^k y^- \alpha (1 + k\beta_1 \lambda^k x^+ y^-) - \frac{1}{d} (s_0 + 1 + \hat{\rho}_k) \lambda^{2k}. \quad (29)$$

Thus, the first return map T_k has in this case an elliptic 2-periodic orbit when $\mu \in \mathbf{e}_k^2$, where \mathbf{e}_k^2 is the interval of values of μ with border points $\mu = \mu_k^\pm$ and $\mu = \mu_k^{2-}$. Evidently, if $\alpha \neq 0$, the intervals \mathbf{e}_k^2 with sufficiently large and different k do not intersect. \square

4.3 Proofs of Theorems 2 and 3.

Proof of Theorem 2. By (28) and (29), the equations of the bifurcation curves L_k^{2+} and L_k^{2-} , which are boundaries of the domain E_k^2 , can be written as follows

$$L_k^{2+} : \mu = -\lambda^k y^- \left(\frac{cx^+}{y^-} - 1 \right) (1 + k\beta_1 \lambda^k x^+ y^-) - \frac{s_0 + \dots}{d} \lambda^{2k}, \quad (30)$$

$$L_k^{2-} : \mu - \lambda^k y^- \left(\frac{cx^+}{y^-} - 1 \right) (1 + k\beta_1 \lambda^k x^+ y^-) - \frac{1 + s_0 + \dots}{d} \lambda^{2k}. \quad (31)$$

Since $\lambda^{2k} \ll \lambda^k$, the domains E_k^2 with sufficiently large k do not mutually intersect and do not intersect the axis $\mu = 0$, if $cx^+ \neq y^-$. Thus, the domains do not always intersect in the cases with $c < 0$. However, at the global resonance $\alpha = (cx^+/y^- - 1) = 0$ (which is possible only when $c > 0$), as it follows from (30) and (31), all the domains E_k^2 with sufficiently large k do mutually intersect and all of them intersect the axis $\mu = 0$ (as in Figure 7). \square

Proof of Theorem 3. Assume, for more definiteness, that $d > 0$ for all the cases under consideration. The case $d < 0$ is treated in the same way. Assume that f_0 satisfies conditions A, B and D and that the resonant condition $\alpha = 0$ takes place for f_0 . Then, for the one parameter family f_μ with fixed $\alpha = 0$, the intervals e_k^2 have, by (28)–(29), the form

$$e_k^2 = (-1 - s_0, -s_0) \frac{\lambda^{2k}}{d}.$$

Evidently, if $-1 < s_0 < 0$, these intervals will be nested and containing $\mu = 0$. This implies that the diffeomorphism f_0 has infinitely many double-round elliptic periodic orbits.

As follows from Lemma 1, all the first return maps T_k (with sufficiently large k) are reduced to the same rescaled normal form — the non-orientable Hénon map $\bar{x} = y$, $\bar{y} = -s_0 + x - y^2$. It is well known that, for $-1 < s_0 < 0$, the elliptic 2-periodic orbit of this map is generic if $s_0 \neq -\frac{1}{2}; -\frac{3}{4}; -\frac{5}{8}$. These exceptional cases are related, respectively, to the resonances $1 : 4$, $1 : 3$ and to an elliptic point (at $s_0 = -\frac{5}{8}$) whose first Birkhoff coefficient is zero. \square

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