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Influence of the mapping unit for regional Landslide Early  
Warning Systems. Comparison between pixels and  
polygons in Catalonia (NE Spain).

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## Abstract

26 This work presents a prototype Landslide Early Warning System (LEWS) adapted to real-time  
27 performance over the region of Catalonia (NE Spain). The system uses high-resolution rainfall  
28 information obtained from weather radar observations and susceptibility maps to issue a qualitative  
29 warning level at a regional scale. To study the influence of the mapping unit on the LEWS outputs,  
30 susceptibility maps obtained for Catalonia based on (i) pixels of different sizes and (ii) hydrological  
31 subbasins have been compared. The susceptibility has been derived using a simple fuzzy logic  
32 approach combining slope angle and land cover data. The susceptibility maps for the different  
33 mapping units have then been employed to run the LEWS for a period of 7 months (warm season  
34 of 2010). For each configuration, the performance, interpretability of the warnings and,  
35 computational requirements have been compared to assess the suitability of each mapping unit for  
36 their use in the LEWS in real time. The configuration using pixels of 30 m resolution as mapping  
37 units seems to be the best as a compromise between resolution, performance and computational  
38 cost. However, from an end-user's real-time perspective the interpretation of the warnings can be  
39 difficult. Therefore, summarizing and visualizing the warnings, which are computed over the high-  
40 resolution grid, by subbasins is proposed as the best option.

41

42 **KEYWORDS:** Landslides, Early Warning Systems, mapping units, susceptibility analysis.

43

## 44 **1. Introduction**

45        Rainfall-triggered shallow slides and debris flows represent an important hazard that causes  
46 major economic losses and fatalities worldwide (e.g. Jakob and Hungr 2005; Froude and Petley  
47 2018). Although these phenomena are not as widely reported in Catalonia (NE Spain) as they are  
48 in other regions, their hazard is still significant (Gallart and Clotet 1988; Portilla et al. 2010a;  
49 Hürlimann et al. 2014; Palau et al. 2017). Rainfalls that trigger shallow slides and debris flows are  
50 frequently rather short and intense (Guzzetti et al. 2008; Alfieri et al. 2012; Abancó et al. 2016) and  
51 its frequency is expected to increase due to climate change (Gariano and Guzzetti 2016). Building  
52 reliable Early Warning Systems is of key importance to reduce the risk by increasing awareness and  
53 preparedness of communities which may be exposed (Alfieri et al. 2012; UNISDR 2015; Alcántara-  
54 Ayala et al. 2017).

55        In the recent years, regional Landslide Early Warning Systems (LEWS) have been developed  
56 covering multiple areas worldwide; e.g. Japan (Osanai et al. 2010), Hong Kong (Lloyd et al. 2001),  
57 the Chinese Zhejiang province (Yin et al. 2008), Southern California (Baum and Godt 2010), Rio  
58 de Janeiro (Calvello et al. 2014), the Italian regions of Emilia-Romana and Campania (Piciullo et  
59 al. 2017; Segoni et al. 2018), Norway (Krøgli et al. 2018) and the Catalan Pyrenees (Berenguer et al.  
60 2015). These LEWS frequently use susceptibility maps to depict the landslide prone areas and  
61 assess whether a rainfall event might trigger a landslide by means of rainfall thresholds (Aleotti  
62 2004; Baum and Godt 2010; Papa et al. 2013; Berti et al. 2015; Piciullo et al. 2017; Pan et al. 2018).  
63 The quality of both the susceptibility assessment and the rainfall data (as well as the rainfall  
64 Intensity-Duration thresholds) influence significantly the accuracy of the issued warnings.

65        Generally, the rainfall inputs are obtained from rain-gage measurements (Piciullo et al. 2017;  
66 Krøgli et al. 2018; Segoni et al. 2018). But in many cases the density of rain-gage networks is low,  
67 especially in remote mountainous areas, and landslide triggering rainfalls tend to be underestimated  
68 (Marra et al. 2014). For this reason, some large scale (regional or global) LEWS use radar rainfall

69 observations (NOAA-USGS Debris Flow Task Force 2005; Chen et al. 2007; Osanai et al. 2010;  
70 Berenguer et al. 2015) or satellite rainfall products (Rossi et al. 2017; Kirschbaum and Stanley 2018).

71 Susceptibility maps describe the spatial distribution of the likelihood of having a landslide (Fell  
72 et al. 2008). When implemented into a LEWS they are used to identify the locations where future  
73 events are more likely. Susceptibility maps relate landslide occurrence with a number of variables  
74 that control its initiation. However, obtaining high-resolution information of certain geotechnical  
75 variables directly related to landslide occurrence at regional scale is very difficult. As a consequence,  
76 susceptibility is usually characterized using morphological parameters obtained from digital  
77 elevation models (DEMs), and sometimes also include geological and land cover information  
78 (Chevalier et al. 2013; Leopold et al. 2013; Liu et al. 2013; Bregoli et al. 2015; Kirschbaum et al.  
79 2016; Wilde et al. 2018).

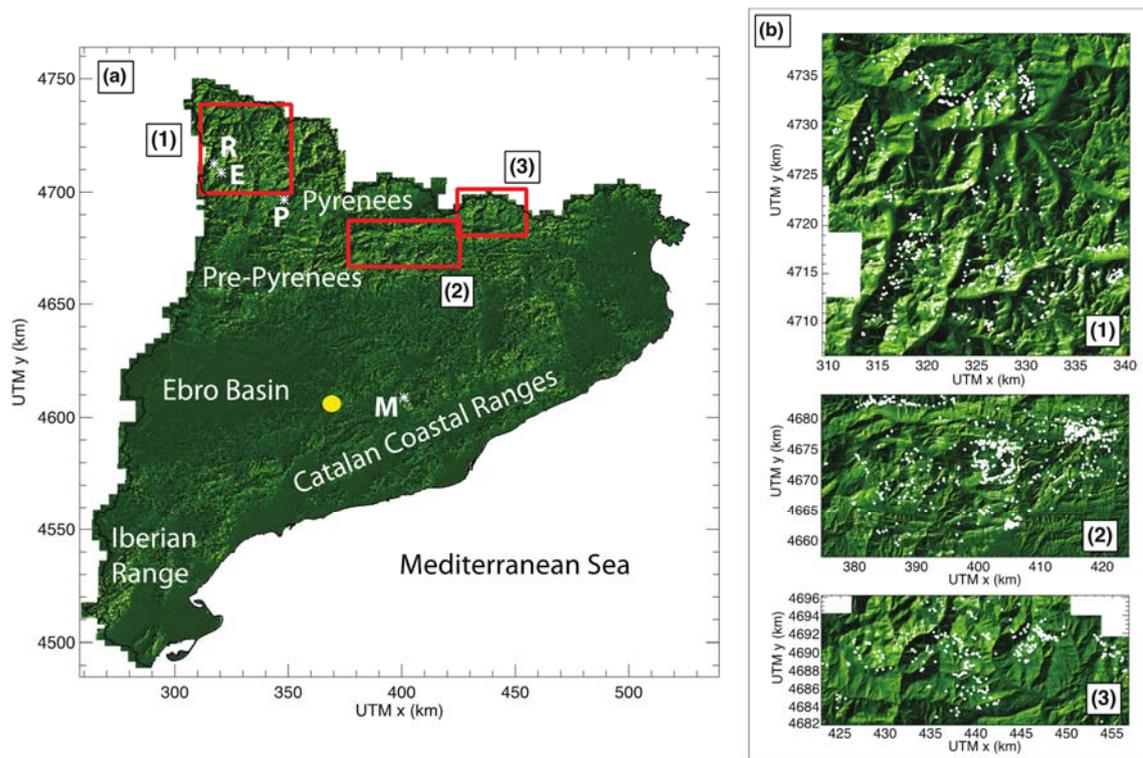
80 Susceptibility zoning is based on the discretization of the study region into homogeneous  
81 mapping units (Hansen 1984). Diverse mapping units have been used to report warnings, for  
82 example polygons (municipalities, catchments...), lines (roads) or pixels (Lloyd et al. 2001; Liao et  
83 al. 2010; Huat et al. 2012; Berenguer et al. 2015; Krøgli et al. 2018; Segoni et al. 2018). Choosing  
84 an appropriate mapping unit for LEWS is not straightforward and requires considering several  
85 factors such as the resolution, the accuracy of the warnings, end-users' interpretability of the results,  
86 and computational cost. In the past, some authors have studied the effect of using polygon or grid-  
87 cell mapping units in the performance of susceptibility assessments (Carrara et al. 2007; Calvello et  
88 al. 2013; Hürlimann et al. 2016). However, there is still no study on its influence on the performance  
89 of a LEWS.

90 The aim of this paper is twofold: (i) assessing the influence of the mapping unit on the outputs  
91 of a regional LEWS, and (ii) selecting the most suitable mapping unit for a regional LEWS for  
92 Catalonia adapted to real-time performance. This has required the retrieval of the susceptibility  
93 map for Catalonia, which is a secondary goal of the presented work.

94 **2. Settings**

95 *2.1. Geographic, Geologic and Climatic Settings*

96 The region of Catalonia is located at the NE of Spain and covers an area of around 32000 km<sup>2</sup>.  
97 Its altitude ranges from sea level to 3143 m in the Pyrenees. From a geological point of view,  
98 Catalonia is located at the Iberian Plate. Its orography is the result of (i) the collisions of the Iberian  
99 Plate, the European Plate and the African Plate during the Paleogene, forming the Pyrenees, the  
100 Catalan Coastal Range and the Iberian Range, (ii) the deposition of its sediments in the Ebro Basin  
101 depressions, and (iii) the reactivation of pre-existing faults in an extensive context during the  
102 Miocene, forming a series of horsts and grabens more or less parallel to the actual coast-line  
103 (Berastegui et al. 2010).



104  
105 **Fig. 1.** (a) Overview map of Catalonia. The red rectangles show the areas where landslide inventories exist in (1) NW-  
106 Catalonia, (2) NC-Catalonia and (3) NE-Catalonia. The yellow circle represents the location of the CDV C-band  
107 weather radar. R, E, P and M show, respectively, the locations of Rebaixader, Erill, Portainé and Santa Maria, where  
108 landslide events were reported during 2010 (see section 5). (b) Inventory of landslide locations in the three areas shown  
109 with the red rectangles in panel a).

110 Catalonia's climate is varied but can be classified as Mediterranean (Mira et al. 2017). Near the  
111 coast the climate is mild and temperate. Inland, the climate is continental, with cold winters and  
112 hot summers. The Pyrenees present a high-altitude climate, with abundant snow and temperatures  
113 below 0°C during winter. The rainiest seasons are generally spring and autumn with the exception  
114 of the Pyrenees where the rainiest season is summer. The majority of the landslides are triggered  
115 by either (i) convective rainfall events with high intensities, which are typical from mid-summer to  
116 early autumn, and (ii) long-lasting rainfalls with moderate intensities, common during spring and  
117 autumn (Corominas et al. 2002; Abancó et al. 2016).

## 118 *2.2. Datasets used*

119 The majority of LEWS methods use susceptibility and rainfall information. Here, we describe  
120 the data that has been used to implement our prototype LEWS. A full description of the method  
121 is presented in in section 3.

122 The rainfall datasets used in this study are radar-based Quantitative Precipitation Estimates  
123 (QPE). Specifically, 30-min rainfall accumulations with a spatial resolution of 1 km. These maps  
124 have been produced with the Integrated Tool for Hydrometeorological Forecasting (EHIMI,  
125 Corral et al. 2009) from the volume scans of the Creu del Vent single-polarization C-band Doppler  
126 radar of the Meteorological Service of Catalonia (SMC). The location of the radar is shown in **Fig.**  
127 **1**. The EHIMI tool includes a chain of correction and quality control algorithms to generate the  
128 QPE products from raw radar observations.

129 To derive the susceptibility maps, the 5 m resolution DEM of Catalonia (ICGC 2013) has  
130 been used. Additionally, information on land use and land cover (LULC) has been obtained from  
131 the Map of Soil Coverage of Catalonia (MCSC-4, CREAM 2009).

132 Information of historic and recent shallow slides and debris flows contained in the inventories  
133 of three zones located in the Pyrenees and the Pre-Pyrenees (**Fig. 1b, Table 1**) has been used for the  
134 susceptibility assessment. The NW-Catalonia inventory is the most recent and accurate and consists

135 of 908 events. These events were principally identified by means of interpretation of aerial photos,  
 136 and both 2D and 3D digital orthophotos (Chevalier 2013; Shu et al. 2019). The NC-Catalonia  
 137 inventory is composed of 1249 landslide events. The majority of these events were triggered by the  
 138 extraordinary rainfall episode of 7-8 November 1982 and were geolocalized on topographic maps  
 139 during field surveys and photointerpretation (Gallart and Clotet 1988). The spatial accuracy of this  
 140 inventory is the lowest. Finally, the NE-Catalonia inventory contains 317 landslides. Many of them  
 141 were triggered by the catastrophic October 1940 rainfall event and the geolocalization of these  
 142 landslides was done by analysis of the 1956-1957 aerial photographs taken by the Spanish Army  
 143 Geographical Service (Portilla Gamboa 2014). Further details about the three inventories and its  
 144 analysis can be found in Hürlimann et al. (2016).

145 **Table 1.** Summary of the characteristics of the three inventory areas

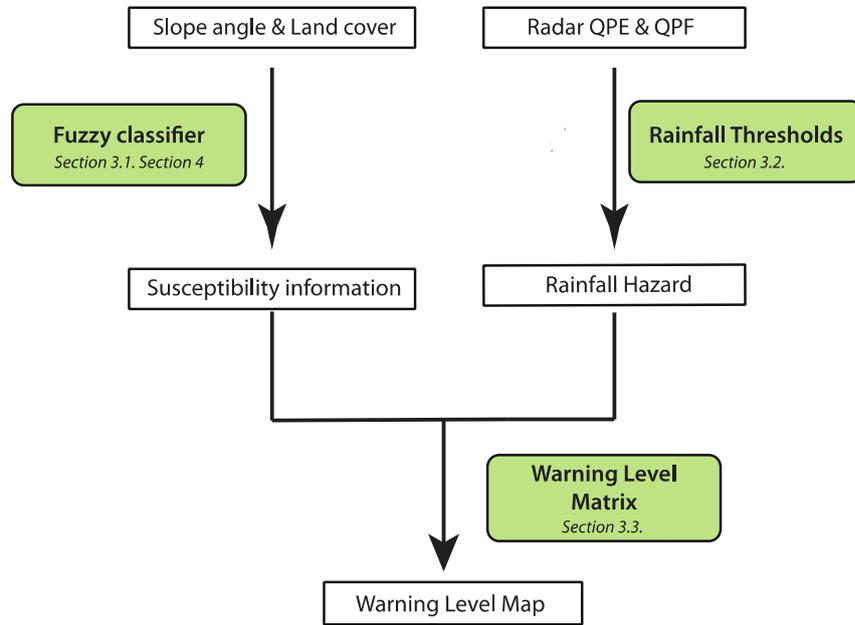
Study Area	Main lithology	Area [km <sup>2</sup> ]	# of landslides	Average density [# of landslides per km <sup>2</sup> ]
NW-Catalonia	Igneous & Metamorphic	1018	908	0.89
NC-Catalonia	Sedimentary	1317	1249	0.95
NE-Catalonia	Igneous & Metamorphic	486	317	0.65

146

### 147 **3. General methodology**

148 The prototype LEWS applied in this study has been designed with the aim of working in  
 149 realtime and has the purpose of issuing warnings to the authorities in charge of managing the risk.  
 150 It is based on the scheme developed by Berenguer et al. (2015), which was applied in two study  
 151 areas in the Catalan Pyrenees. Its inputs are (i) susceptibility information, and (ii) gridded rainfall  
 152 observations. The output of the LEWS is a map showing a qualitative warning level (“very low”,

153 “low”, “moderate” and “high”) for each mapping unit every time new rainfall observations are  
 154 available (in this case every 30 min, see section 2.2). Fig. 2 shows a general scheme of the system.  
 155 Its components are shown in the sections below.



156

157 **Fig. 2.** General flow chart of the prototype LEWS algorithm.

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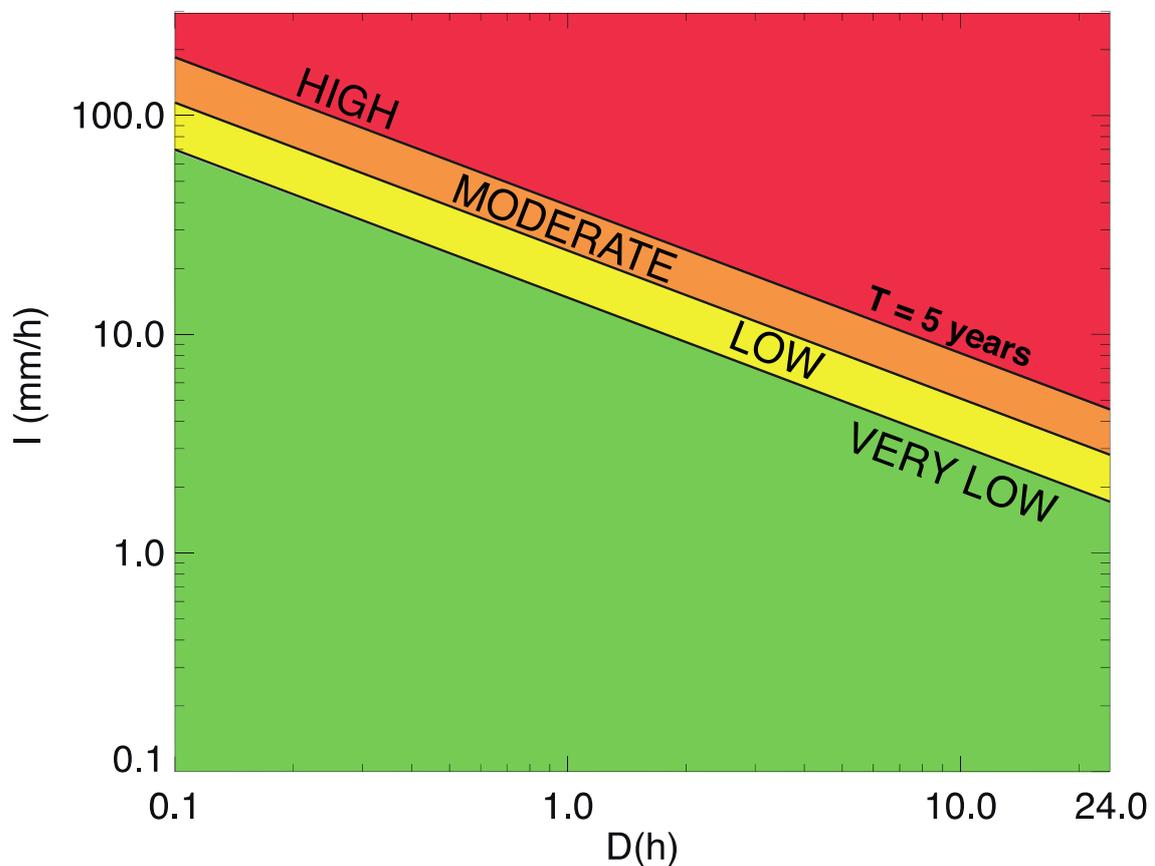
158 *3.1. Susceptibility analysis*

159 A static susceptibility map is used by the LEWS to distinguish landslide-prone areas. The  
 160 susceptibility map for Catalonia has been derived combining the slope angle and land cover. The  
 161 method used for susceptibility mapping (similar to that of Berenguer et al. (2015)) is described in  
 162 detail in section 4. It employs fuzzy logic (Mendel 1995) to classify the susceptibility in four  
 163 categories: “very low”, “low”, “moderate” and “high”.

164 *3.2. Characterization of the rainfall hazard level*

165 Rainfall intensity-Duration (I-D) relationships are widely used in LEWS to assess the hazard  
 166 posed by a rainfall situation. In Catalonia no comprehensive I-D thresholds are available, only  
 167 preliminary rainfall thresholds based on daily rainfall records or thresholds at catchment scale exist  
 168 (e.g., Corominas 2000; Abancó et al. 2016). Thus, to assess the magnitude of rainfall situations in  
 169 the analysis domain, we have used the intensity-duration-frequency (IDF) curves of the Fabra

170 meteorological observatory in Barcelona (Casas et al. 2004) as reference. The IDF curves are the  
 171 base to define four rainfall hazard levels: “very low”, “low”, “moderate” and “high” (Fig. 3). The  
 172 definition of the thresholds has been done empirically with the following criteria: for the high  
 173 rainfall hazard, the I-D curve for a return period of 5 years has been used. In addition, the two  
 174 other thresholds (lower limit of hazard level “moderate” and “low”) were defined as parallel I-D  
 175 curves that are below the two years return period. Although these thresholds do not directly relate  
 176 rainfall with landslide occurrence, their slopes are very similar to the ones of local rainfall thresholds  
 177 obtained for specific sites in Catalonia (e.g. Abancó et al. 2016; Hürlimann et al. 2017).



178

179 **Fig. 3.** Rainfall intensity-duration thresholds. The background green, yellow, orange and red colors represent the four rainfall hazard level  
 180 classes: “very low”, “low”, “moderate” and “high”.

181 *3.3. Definition of the warning level*

182 Combining the susceptibility of the mapping unit and the magnitude of the rainfall event, the  
 183 LEWS issues a warning. While susceptibility is considered to be static (it remains constant in time),

184 rainfall inputs are updated every 30 minutes. The combination of the susceptibility and rainfall  
 185 hazard is done according to the warning level matrix of Fig. 4. The result for each timestep is a  
 186 qualitative warning level for each mapping unit of one of the following four classes: “very low”,  
 187 “low”, “moderate” and “high”.

188 Each warning level class aims at assessing the possibility of having a shallow slide or debris  
 189 flow; i.e. increasing the warning level implies increasing the probability of the expected event.

		<i>Susceptibility</i>			
		<b>Susc Very Low</b>	<b>Susc Low</b>	<b>Susc Moderate</b>	<b>Susc High</b>
<i>Rainfall hazard level</i>	<b>Rain Very Low</b>	VL	VL	VL	L
	<b>Rain Low</b>	VL	L	L	M
	<b>Rain Moderate</b>	VL	L	M	H
	<b>Rain High</b>	L	M	H	H

190

191 **Fig. 4.** Warning level matrix. Rows represent the rainfall hazard level; columns represent the susceptibility degree. “VL”, “L”, “M” and “H”  
 192 stand for “very low”, “low,” “moderate” and “high” warning level respectively.

193 **4. Susceptibility map of Catalonia**

194 One of the requirements to extend the LEWS to Catalonia is mapping the susceptibility over  
 195 the entire region. Up to the date there is no susceptibility assessment spanning the whole region.  
 196 This section first presents the methodology used to derive the susceptibility map with different  
 197 mapping units, and next, the different susceptibility maps are evaluated by (i) visual inspection, and  
 198 (ii) from a quantitative point of view in a validation framework.

199 *4.1. Susceptibility mapping methodology*

200 Chevalier et al. (2013) analyzed the skill of different morphological parameters obtained from

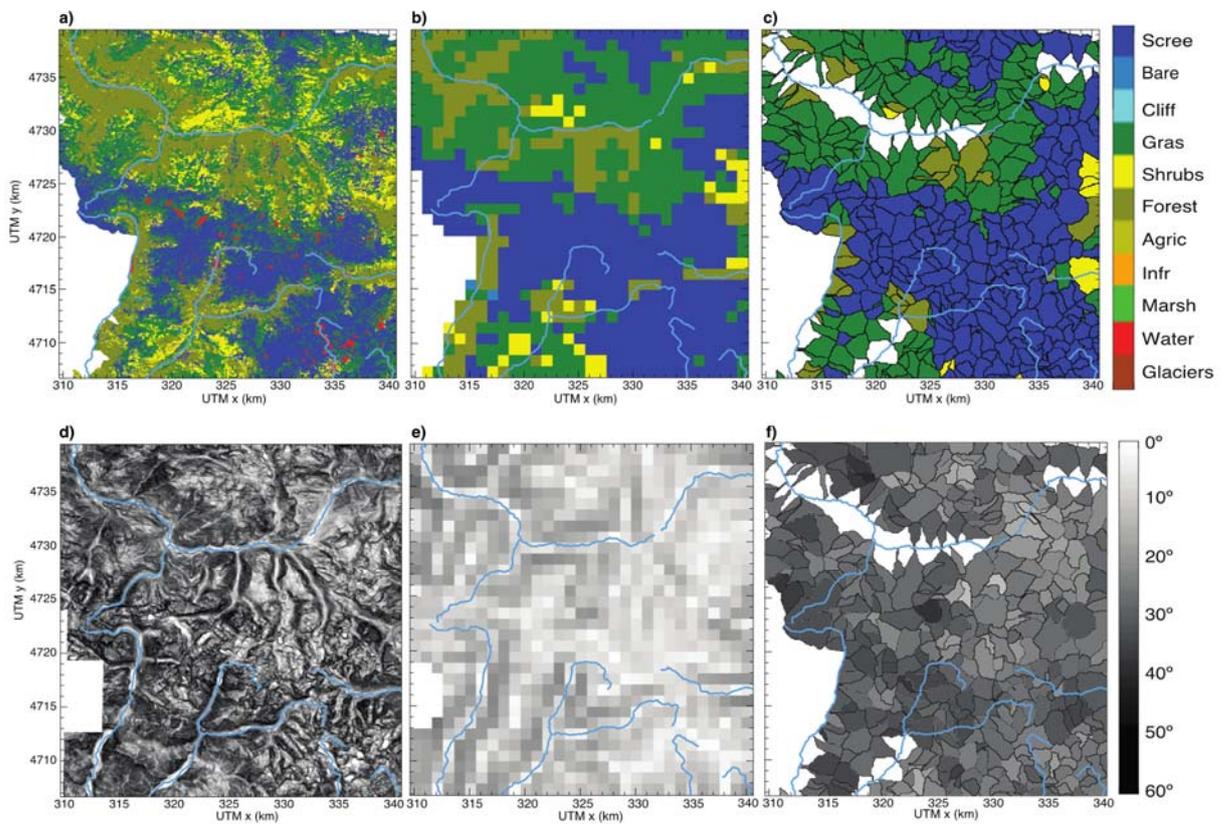
201 the DEM to assess shallow slides and debris flows susceptibility. Their results showed that the  
202 most significant governing factor was the terrain slope angle. Though, they did not include  
203 information associated with the soil layer in their analysis. Some authors (Nadim et al. 2006; Ciurleo  
204 et al. 2016; Wilde et al. 2018) have used information contained in geological maps to assume  
205 geotechnical properties of the soil. However, in Catalonia, the geological map mostly lacks  
206 information on surficial formations. Thus, a reasonable alternative consists in using land use and  
207 land cover (LULC) information, as proposed by several authors (e.g. Hürlimann et al. 2016; Pisano  
208 et al. 2017; Gariano et al. 2018). LULC provide indirect information of sediment availability. In  
209 addition, the vegetation plays an important role in slope stability [e.g. evapotranspiration, suction,  
210 apparent cohesion given by the plant roots (Schmidt et al. 2002; Schwarz et al. 2010)]. The removal  
211 of vegetation generally increases susceptibility (Persichillo et al. 2017; Pisano et al. 2017). For these  
212 reasons, the susceptibility map of Catalonia presented herein has been derived using slope angle  
213 and LULC, which are datasets currently available not only in Catalonia, but also in most countries.

214 Susceptibility maps of two main types have been derived: (i) raster grids of different resolutions  
215 (5 m, 30 m, 200 m and 1 km), and (ii) a subdivision of the analysis domain in hydrological subbasins  
216 (including 1<sup>st</sup>, 2<sup>nd</sup> and 3<sup>rd</sup> order, following the method of Strahler, 1957). The mean area and its  
217 standard deviation of these subbasins are 2.1 km<sup>2</sup> and 1.6 km<sup>2</sup> respectively. For the map based on  
218 raster grids, the 5 m DEM has been upscaled to obtain the DEMs of lower resolutions and the  
219 slope angle of each resulting cell has been computed using GIS tools.

220 The 241 original land cover classes of the LULC map have been reclassified into 11 classes  
221 that were significant in terms of slope stability following the Corine Land Cover Classification  
222 (EEA 1990). As the original land cover map was rasterized at a resolution of 5 m, we had to adopt  
223 a criterion to upscale the information to 30 m, 100 m, 200 m and 1 km resolutions and subbasins.  
224 Finally, we have chosen to assign the most susceptible land cover class to the larger mapping unit,  
225 on the condition that this class is representative enough (it occupies at least 15% of the (larger)  
226 terrain unit). This methodology is quite feasible, but decreases land cover variability with decreasing

227 resolution and biases it towards more susceptible classes as it can be seen in **Fig. 5**.

228 Slope angle and land cover have been combined to retrieve the susceptibility maps using a  
229 fuzzy logic classifier (Mendel 1995). Compared to statistical methods, fuzzy logic has the following  
230 advantages: (i) it is able to model the non-linear behavior of the susceptibility input variables, (ii) it  
231 uses expert criteria to assess the uncertainty of input parameters and landslide inventories, (iii) it is  
232 simple and can be easily adapted to different regions.



233

234 **Fig. 5.** Maps of the NW-Catalonia study area. The upper and the bottom rows show respectively the land cover  
235 maps and the slope angle maps with pixel resolution of (a), (d) 30 m, (b), (e) 1 km and, (c), (f) hydrological subbasins  
236 respectively.

237 The used fuzzy logic classifier requires a weight for each input variable (slope and land cover)  
238 and membership functions for each input variable and each susceptibility class (“very low”, “low”,  
239 “moderate” and “high”). Membership functions measure how realistic it is that a mapping unit  
240 where one variable takes a value  $x$  belongs to a certain susceptibility class. Here, similarly as  
241 Berenguer et al. (2015), the membership functions and weights for the slope angle and the land

242 cover have been designed by an expert using subjective criteria by taking the information of  
243 landslide frequency distributions of a random sub-set containing half of the points of the landslide  
244 inventory as a reference (not shown). Slope angle membership functions have been adapted for all  
245 the different mapping units (Fig. 6a-Fig. 6c). In contrast, land cover landslide frequency  
246 distributions are very similar for all the mapping units; and thus, the same membership functions  
247 set has been adopted for all mapping units (Fig. 6d).

248 From these membership functions, the membership degree to a susceptibility class ( $M_S$ )  
249 assesses the feasibility that a mapping unit belongs to it. Its value ranges from zero to one and has  
250 been computed as follows:

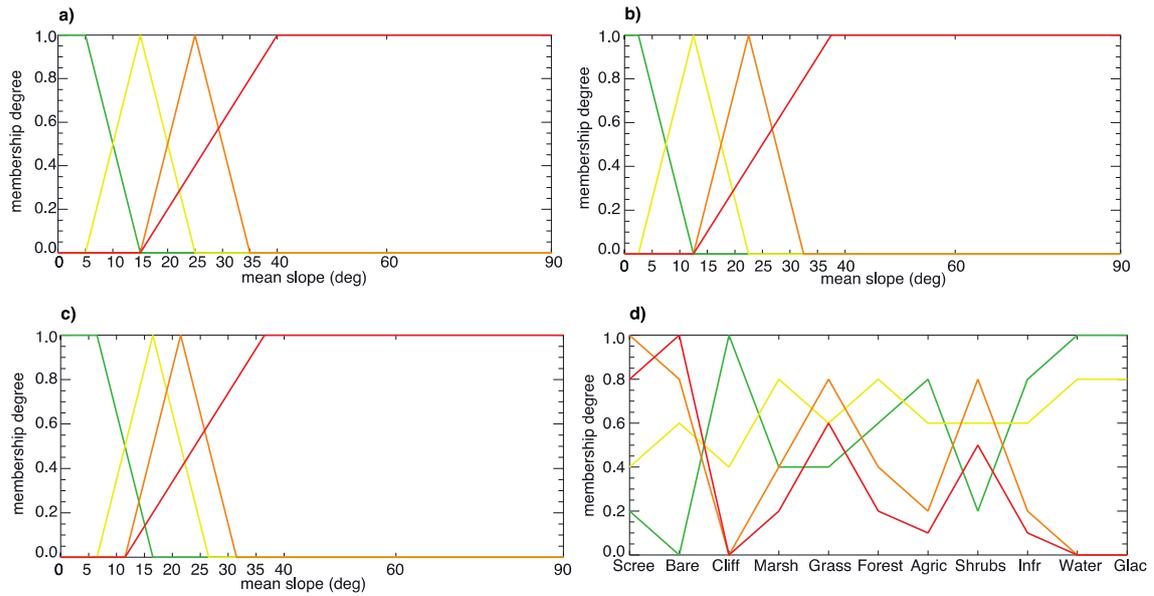
$$251 \quad M_S = w_{sl} \mu_{sl,S} + w_{lc} \mu_{lc,S} \quad (1)$$

252 where  $w_{sl}$  and  $w_{lc}$  are the weights of slope and land cover respectively, and  $\mu_{sl,S}$  is the  
253 membership degree for the slope and for a susceptibility class S,  $\mu_{lc,S}$  is the land cover membership  
254 degree for a susceptibility class S.

255 The susceptibility class having the highest membership degree (i.e. higher possibility of having  
256 landslides) has been assigned to each terrain unit. That is:

$$257 \quad S = \operatorname{argmax} \{M_{VL}, M_L, M_M, M_H\} \quad (2)$$

258 where S states for the susceptibility class, and  $M_{VL}, M_L, M_M, M_H$  for the membership degree  
259 of the classes “very low”, “low”, “moderate” and “high” respectively.



260

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**Fig. 6.** Slope membership functions for pixels with a resolution of (a) 30 m, (b) 200 m, and (c) hydrological catchments. (d) Land cover membership functions. Green, yellow, orange and red lines represent the membership functions of “very low”, “low”, “moderate” and “high” susceptibility.

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#### 4.2. Comparing the different susceptibility maps

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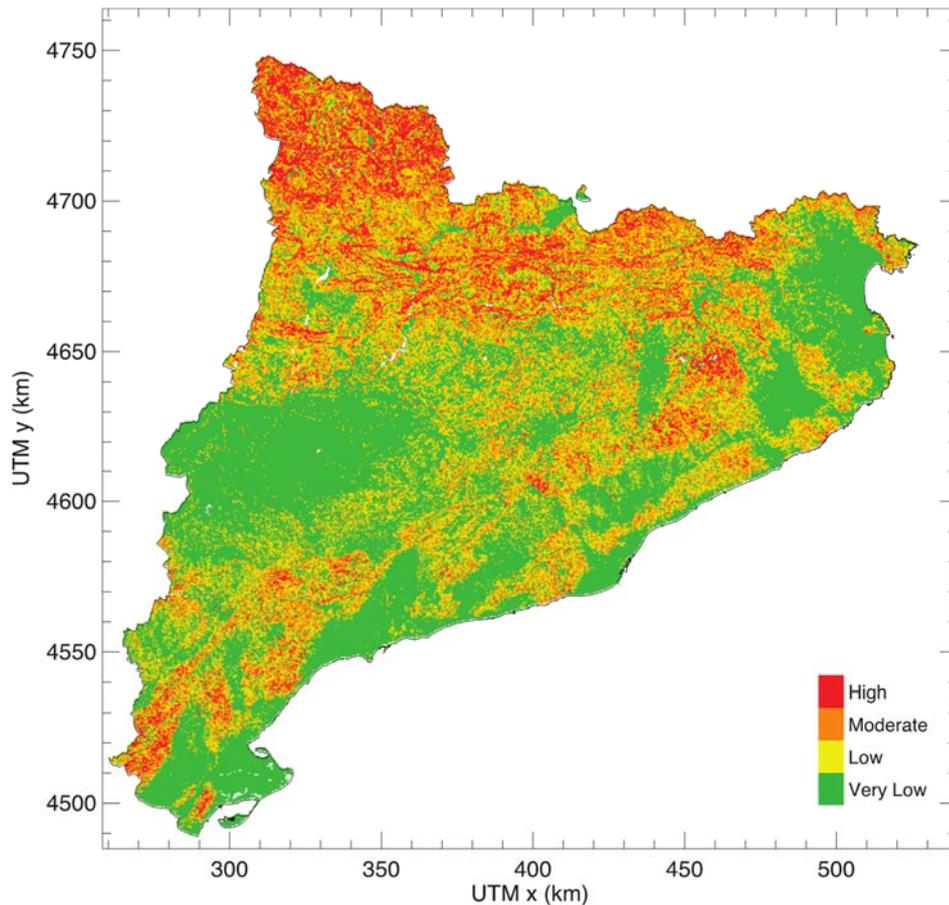
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The fuzzy logic classifier has been applied to create landslide susceptibility maps covering the region of Catalonia using 5 m, 30 m, 100 m, 200 m, 1 km grid-cells, and subbasins as mapping units. The susceptibility map based on 30 m grid-cells shows variability, with the areas having higher susceptibility located in the mountainous regions of the Pyrenees and the Catalan Coastal Ranges (Fig. 7). The flat areas of the low Ebro Basin generally present “very low” susceptibility. The results for the other mapping units (not shown here) are relatively similar.



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272

**Fig. 7.** Susceptibility map of the Catalonia using 30 m grid-cells as mapping units.

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The resulting susceptibility maps based on the different mapping units for the NW-Catalonia zone are shown in **Fig. 8**. In this area located in the Axial Pyrenees, the 5 m, 30 m, 100 m and 200 m pixels susceptibility maps include large parts of “moderate” and “high” susceptibility.

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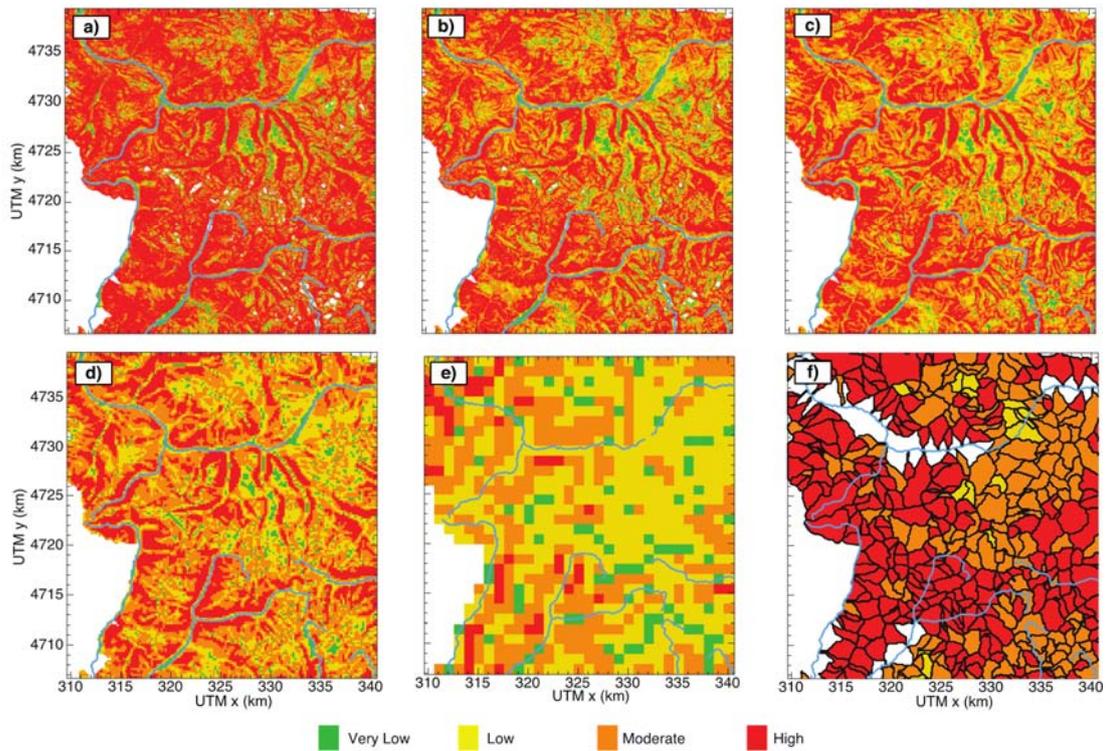
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Unlike pixel-based susceptibility maps, the susceptibility map of hydrological subbasins does not cover the entire domain and classifies almost all the mapping units in the NW-Catalonia zone as “moderate” and “high” susceptibility (**Fig. 8f**). However, the percentage of area occupied by these two classes is similar to the area occupied by the same two classes in the map that uses pixels of 5 m resolution as mapping units (**Table 2**). The main difference relies on the percentage of area classified as “very low” and “low” susceptibility class which is much smaller for the map of subbasins. This can be partly explained because the subbasin map covers mainly the upstream parts of the domain where slope is generally steeper and therefore typically it corresponds to areas that are more susceptible.

285 Regarding the three inventory subdomains (presented in section 2.2 and in Fig. 1), the area  
 286 occupied by moderate and high susceptibility grid cells reduces with decreasing resolution to the  
 287 point that the map of 1 km pixels classifies more than half as “very low” and “low” susceptibility.



288

289 **Fig. 8.** Susceptibility maps of the NW-Catalonia study area. (a) 5m, (b) 30 m, (c) 100 m, (d) 200 m and (e) 1 km  
 290 grid-cells, and (f) hydrological subbasins

291 **Table 2** Area (in km<sup>2</sup>) occupied by each susceptibility class at the NW-Catalonia zone for the susceptibility maps based  
 292 on the different mapping units. The percentage of the NW-Catalonia domain covered by each class is displayed in  
 293 parentheses. Note that the total area occupied by hydrological subbasins is smaller than the area occupied by the rest  
 294 of mapping units.

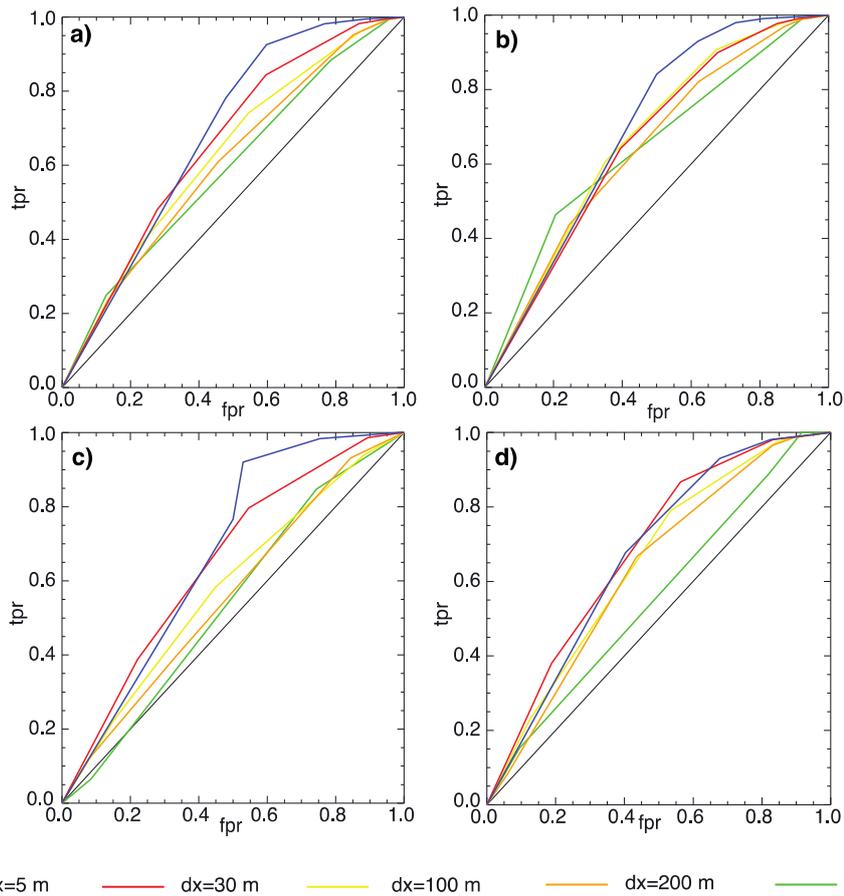
	Subbasins	Pixels 5 m	Pixels 30 m	Pixels 100 m	Pixels 200 m	Pixels 1 km
Very Low	0 (0%)	58 (6%)	64 (7%)	49 (5%)	50 (6%)	91 (10%)
Low	30 (3%)	103 (12%)	171 (18%)	187 (20%)	235 (25%)	463 (50%)
Moderate	319 (34%)	187 (20%)	292 (32%)	340 (37%)	399 (25%)	325 (35%)
High	501 (53%)	575 (62%)	402 (43%)	358 (38%)	253 (42%)	49 (5%)

295

296        *4.3. Validation of the susceptibility maps*

297        The resulting susceptibility maps have been evaluated using the landslide data that were not  
298 used for the calibration (i.e. retrieval of the membership functions and weights). The evaluation  
299 has been done with Receiver Operating Characteristics (ROC) curves (Fawcett 2006): For each  
300 susceptibility class, the false positive rate (fpr) and the true positive rate (tpr) have been computed,  
301 and the area under the curve (AUC) is the metric that has been used to assess the model  
302 performance. The AUC is a measure of how well a susceptibility classifier can distinguish between  
303 mapping units with and without landslide observations. The perfect discriminant is a susceptibility  
304 classifier that achieves an AUC equal to one. The larger the AUC, the better is the classification of  
305 the susceptibility map.

306        Our results show that generally, the AUC of the grid-cell susceptibility maps slightly decreases  
307 with decreasing resolution. Combining the three inventory zones its AUC-values range from 0.59  
308 to 0.67 (**Fig. 9** and **Table 3**). The smallest AUC is obtained for the susceptibility map based on 1  
309 km grid-cells. In general, the results in the NC-Catalonia zone are the worst, with AUC values  
310 ranging from 0.52 to 0.56 (**Fig. 9** and **Table 3**). On the other hand, the region with the highest AUC  
311 values is the NW-Catalonia zone where the most complete and recent inventory is available.



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**Fig. 9.** ROC curves of the 5 m, 30 m, 100 m, 200 m, and 1 km grid-cell based susceptibility maps at (a) NW-Catalonia, (b) NC-Catalonia zone. (c) NE-Catalonia zone and (d) all zones. The horizontal axis represents the false positive rate (fpr), the vertical axis represents the true positive rate (tpr).

The comparison of grid-cell based susceptibility maps that cover all the analyzed domain, and subbasin-based susceptibility maps that cover only part of it is challenging. To do so, pixel-based maps have been clipped with the catchments polygons. The resulting grid-cell susceptibility maps covered the same area as the subbasin susceptibility maps and were validated using ROC analysis. Consistently, the AUC of the clipped grid-cell susceptibility maps decreases with decreasing resolution. The smallest AUCs of the clipped grid-cell and the subbasin-based susceptibility maps are obtained in the NC-Catalonia domain (Table 3). As it can be seen in Fig. 10 and Table 3 the subbasin-based map performance is slightly better than the performance of 100 m grid-cell susceptibility map and it only achieves a smaller AUC in the NW-Catalonia zone.

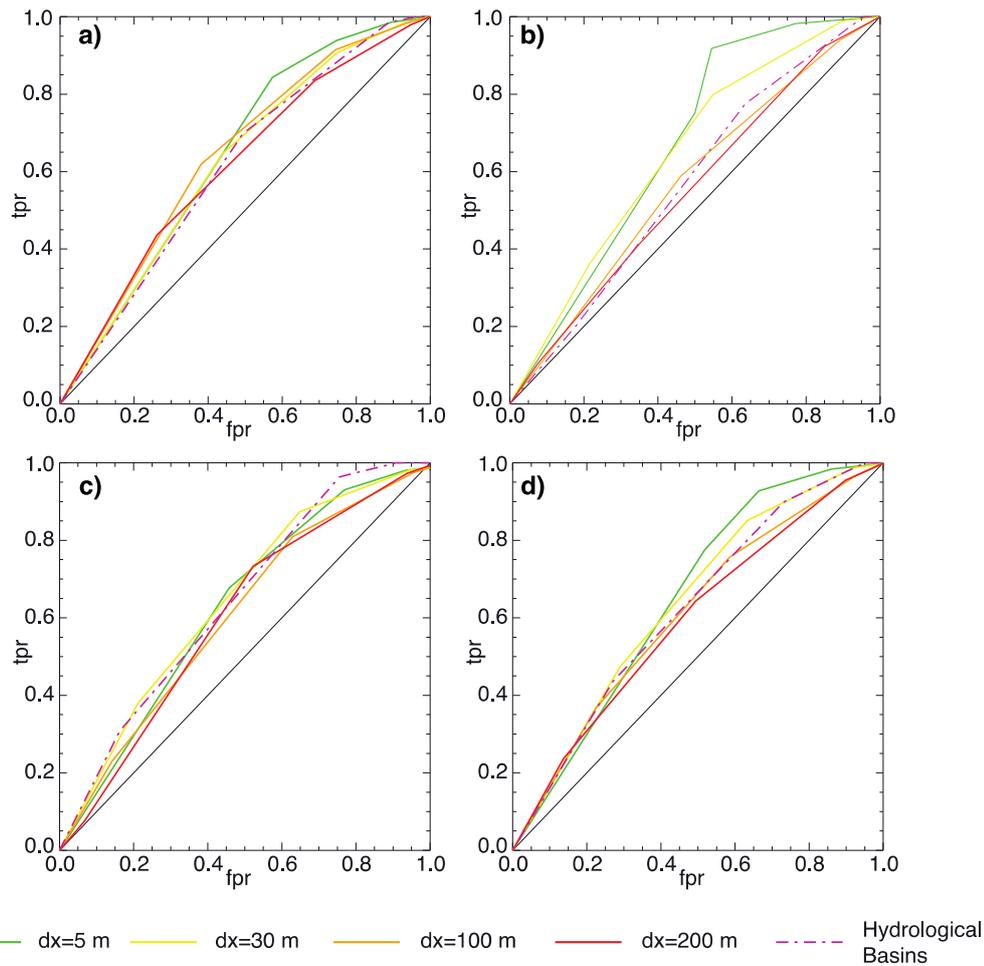
325 **Table 3** AUC values obtained from ROC analysis of the susceptibility maps based on the different mapping units.  
 326 Values in bold are the highest AUC values in each inventory zone.

Pixel size [m]	AUC			
	All Zones	NW-Catalonia	NC-Catalonia	NE-Catalonia
Over the domain defined by grid-cells				
5	<b>0.67</b>	<b>0.68</b>	0.56	0.65
30	0.66	0.64	<b>0.66</b>	<b>0.67</b>
100	0.63	0.65	0.59	0.63
200	0.61	0.63	0.57	0.62
1000	0.59	0.65	0.52	0.55
Over the domain defined by subbasins				
5	<b>0.66</b>	<b>0.67</b>	0.59	0.67
30	0.65	0.64	<b>0.66</b>	0.67
100	0.62	0.66	0.58	0.64
200	0.61	0.63	0.55	0.62
Subbasins	0.63	0.63	0.58	<b>0.69</b>

327

328 Therefore, for both, the domain defined by grid-cells and the domain defined by subbasins,  
 329 the best susceptibility map is the one based on 5 m resolution pixels. The poor results obtained in  
 330 the NC-Catalonia zone can be, at least partly, explained by the lower quality of the landslides  
 331 inventory in this domain (especially in the accuracy of the landslides location). Apart from the map  
 332 based on 1 km grid-cells, the obtained susceptibility maps have an acceptable performance and  
 333 could therefore be used for LEWS.

334



335

336 **Fig. 10.** ROC curves comparing the performance of the susceptibility maps over the area occupied by hydrological  
337 catchments. (a) NW-Catalonia, (b) NC-Catalonia, (c) NE-Catalonia, (d) three inventory zones. The horizontal axis  
338 represents the false positive rate (fpr), the vertical axis represents the true positive rate (tpr).

### 339 5. Performance of the LEWS with the different mapping units

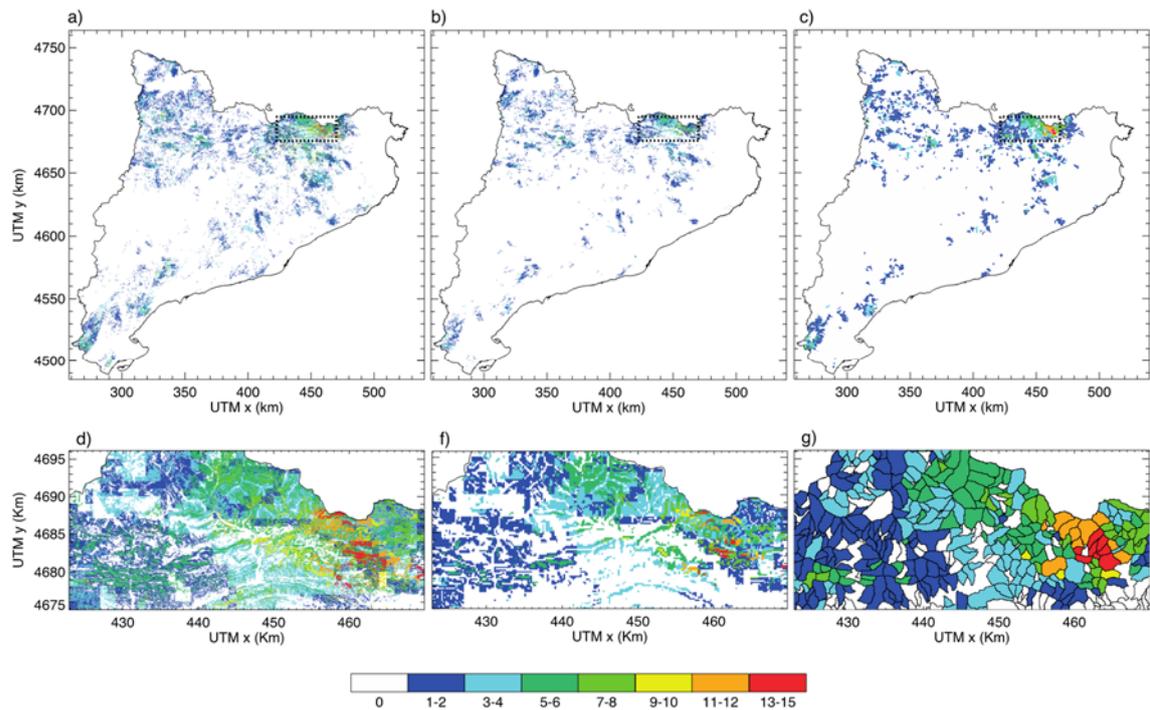
340 In this section, the LEWS presented in Section 3 has been run from April to October 2010 to  
341 analyze the effect of the mapping units on the landslide warnings over Catalonia. With this aim,  
342 the LEWS has been set up using the different mapping units for which the susceptibility maps have  
343 been obtained in section 4. Specifically, the analyzed mapping units are (i) 30 m grid-cells, (ii) 200  
344 m grid-cells, and (iii) hydrological subbasins. Running the LEWS using 5 m grid cells is still  
345 computationally too expensive and this configuration has been discarded in this part of the analysis.  
346 The LEWS time resolution is 30 min for all the tested set-ups.

347 The performance of the LEWS with the different configurations has been analyzed in terms  
348 of (i) the number of days with warnings for the different mapping units, (ii) its ability to identify  
349 the occurrence of specific events that took place during the studied period and for which the exact  
350 or approximate triggering time is known. Finally, some discussion about the computational cost to  
351 run the LEWS with the different mapping units is provided.

#### 352 *5.1. Number of warnings during the studied period*

353 The total number of days during which “moderate” or “high” warning levels were issued at  
354 least once for each mapping unit is summarized in **Fig. 11**. The results show that the areas where  
355 these warnings were issued coincide with the zones of “high” susceptibility mostly located in the  
356 Pyrenees and Pre-Pyrenees.

357 The 30 m grid-cells configuration issued a “moderate” or “high” warning level during more  
358 than six days in over 0.09 % of Catalonia (**Table 4**). This percentage of area is higher for the setup  
359 using hydrological subbasins (0.36 %). On the other hand, the 200 m resolution grid-cells  
360 configuration issues “moderate” or “high” warning level only in around 0.01 % of Catalonia.



361

362 **Fig. 11.** Number of days of the period April-October 2010 during which “moderate” and “high” warning levels  
 363 where issued (at least for a 30-minutes time step of the day). (a) pixels of 30 m, (b) pixels of 200 m, and (c) subbasins.  
 364 A zoom into the area enclosed by the black dashed rectangle is portrayed in (d), (e) and (f) for the 30 m, 200 m and  
 365 subbasins mapping units respectively.

366 **Table 4.** Percentage of Catalonia with 1 to 2, 3 to 5, 6 to 10 and more than 11 days with “moderate” or “high” warning  
 367 level for three different mapping units.

	Domain Area [km <sup>2</sup> ]	Percentage of Catalonia area with Moderate or High warning level			
		1-2 days	3-5 days	6-10 days	11 days or more
dx = 30 m	32030	7.52	1.59	0.09	0.01
dx = 200 m	32248	2.54	0.37	0.01	0.00
Subbasins	23048	13.99	3.12	0.36	0.01

368

369 The validation of the results of the LEWS in Catalonia is challenging because the areas with a  
 370 large number of days with warning are mainly located in highly inaccessible mountainous regions.  
 371 When an event occurs, it is hardly reported because typically no infrastructures, buildings or roads  
 372 are affected, and no multi-temporal landslides inventories are available.

373 The number of days with warnings is a qualitative result that gives an idea that the number of  
374 false positives is reasonable: warnings are generally located in the most susceptible areas that were  
375 affected by important rainfall amounts and, are issued at most 15 days of the 214 days that comprise  
376 the analyzed period. Alternatively, to evaluate the LEWS results using the different mapping units,  
377 we have focused on some specific catchments where landslide reports were available during the  
378 analyzed period.

### 379 *5.2. Validation in specific sites*

380 The performance of the LEWS with the different setups has been analyzed in two catchments  
381 where debris flows have been detected during the analyzed period of 2010. These two monitored  
382 catchments (Rebaixader and Erill) are both located in the NW-part of Catalonia (**Fig. 1**).

383 Although the Rebaixader catchment is relatively small (0.80 km<sup>2</sup>), it is one of the most active  
384 torrents in the Catalan Pyrenees and has been monitored since 2009 (Hürlimann et al. 2014). The  
385 debris-flows initiation zone is located in a steep scarp in a lateral moraine. The catchment sediment  
386 supply is assumed to be almost unlimited. During the analyzed period, the monitoring system  
387 recorded the second largest debris flow since 2009 (on 11 July 2010, with an estimated volume of  
388 12500 m<sup>3</sup>) and also two debris floods that mobilized smaller volumes (on 21 July and 9 October  
389 2010).

390 The Erill catchment, with a drainage area of 3.30 km<sup>2</sup>, is close to the Rebaixader and the  
391 outcropping material is similar. A monitoring station was installed in 2005 (Raïmat Quintana 2018)  
392 and detected one debris flow during the studied period (on 22 July 2010).

393 The LEWS outputs show that the events reported during the 7-month period in the two  
394 catchments mentioned above are generally associated with “moderate” or “high” warning levels  
395 (the results are summarized in **Table 5****Fig. 12** and **Fig. 12****Table 5**).

396 In the Rebaixader catchment, the three recorded events were triggered by rather intense  
397 rainfall episodes. All the LEWS configurations determine “moderate” or “high” warning levels, for

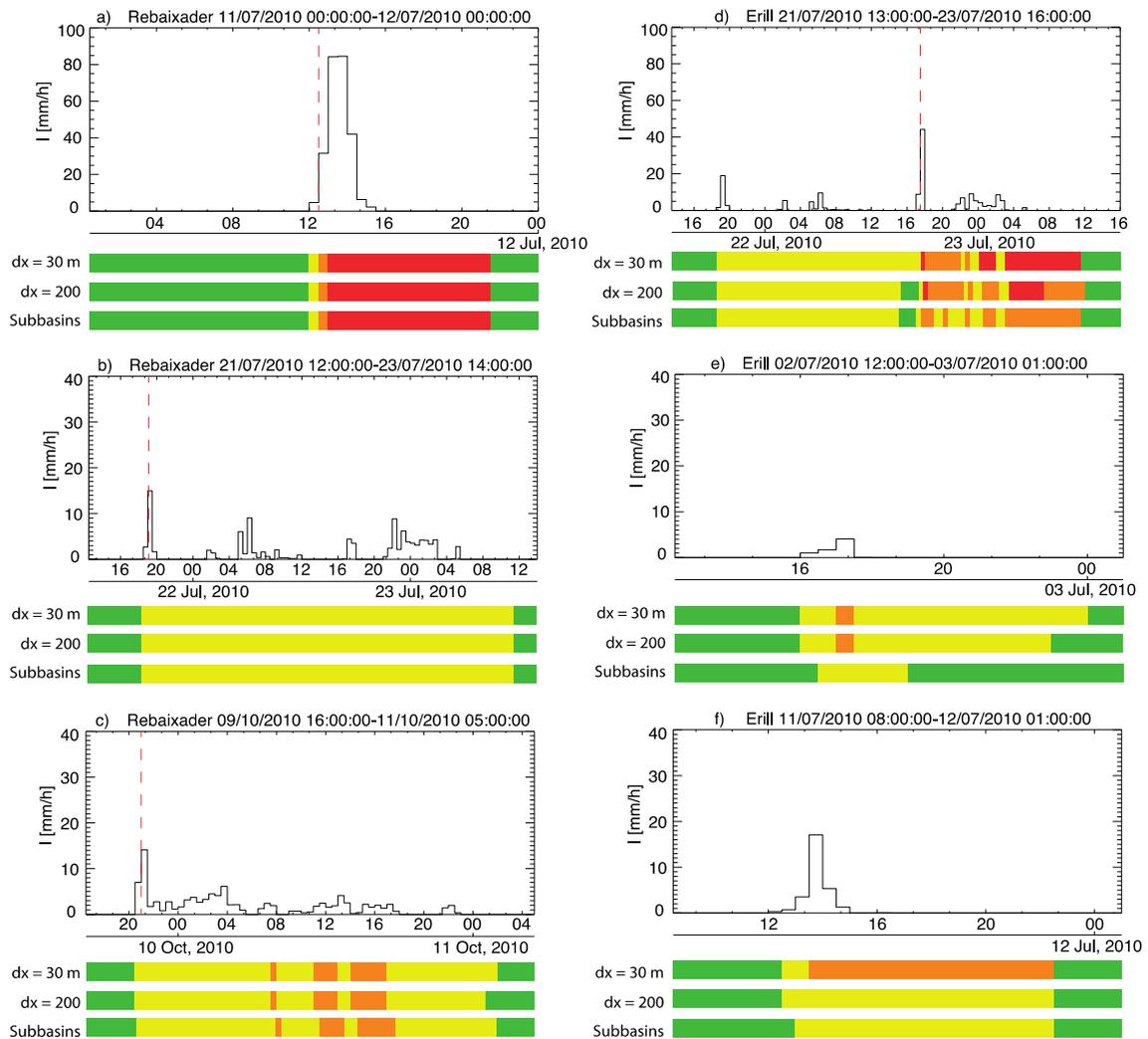
398 the 11 July 2010 debris flow and the 9 October 2010 debris flood (Table 5 and Fig. 12a, and c).  
 399 However, the LEWS was not able to issue a warning for the 21 July 2010 rainfall event, when a  
 400 small debris flood was detected (Table 5 and Fig. 12b), because the rainfall intensities were just  
 401 below the “very low”- “low” threshold.

402 Similarly, in the Erill catchment the recorded debris flow was triggered by intense rainfall. The  
 403 LEWS results show that both grid-cell configurations identify the event with a “high” warning level  
 404 and the subbasins configuration identifies it with a “moderate” warning level (Fig. 12d and Table  
 405 5).

406 **Table 5** Reported debris flows and/or debris floods at the Rebaixader and Erill catchments and maximum warning  
 407 level issued by the LEWS during each of the rainfall episodes.

Subbasin	Subbasin susceptibility class	Reported events	Type of event	Maximum Warning Level		
				dx= 30 m	dx= 200 m	Subbasins
Rebaixader	High	11 July 2010	Debris flow	High	High	High
		21 July 2010	Debris flood	Low	Low	Low
		09 October 2010	Debris flood	Low	Moderate	Moderate
Erill	High	22 July 2010	Debris flow	High	High	Moderate

408



409

410 **Fig. 12.** Site-specific validation of the LEWS. At the Rebaixader monitoring site: (a) 11 July 2010 debris flow, (b) 11  
 411 July 2010 debris flood, (c) 9 October 2010 debris flood. At Erill: (d) 22 July debris flow; and the two rainfall events  
 412 that did not turn on the monitoring system and (e) 2 July 2010 (f) 11 July 2010. The black line represents the 30-  
 413 min rainfall intensity observed by the weather radar. The horizontal color bars show the maximum warning level  
 414 time series observed within the catchment for the analyzed mapping units. Green, yellow, orange and red represent  
 415 warning levels “very low”, “low”, “moderate” and “high”, respectively. The red dashed line indicates the time when  
 416 the debris flow or debris flood was detected by the monitoring station.

417 The number of recorded events at Rebaixader and Erill have been compared with the number  
 418 of days that achieved a maximum warning level of “moderate” or “high” classes (Table 6). The  
 419 LEWS performance at these two specific catchments has been assessed by calculating the true  
 420 positives, false positives, and misses, using the subbasin where the sensors were installed as the  
 421 mapping unit for evaluation. True positives are defined as the number of rainfall events during  
 422 which the monitoring systems detect a debris flow or debris flood and the LEWS issues a

423 “moderate” or “high” warning level within the catchment. False positives are rainfall events with a  
 424 “moderate” or “high” warning within the catchment, but during which no landslide event is  
 425 detected. Misses are rainfall events during which the monitoring systems record a debris flow or  
 426 debris flood, but the LEWS is not switching into a moderate or high warning in any mapping unit.

427 In the analyzed catchments all the tested configurations have the same number of true  
 428 positives and misses. However, the number of false positives seems to increase with the resolution  
 429 of the mapping unit, particularly in Erill (**Table 6**). The difference in the number of false positives  
 430 between both 30 m and 200 m grid-cell mapping units are due to the larger area classified as  
 431 “highly” susceptible in the 30 m grid-cell map at the the Erill catchment (**Fig. 13a** and **Fig. 13b**).

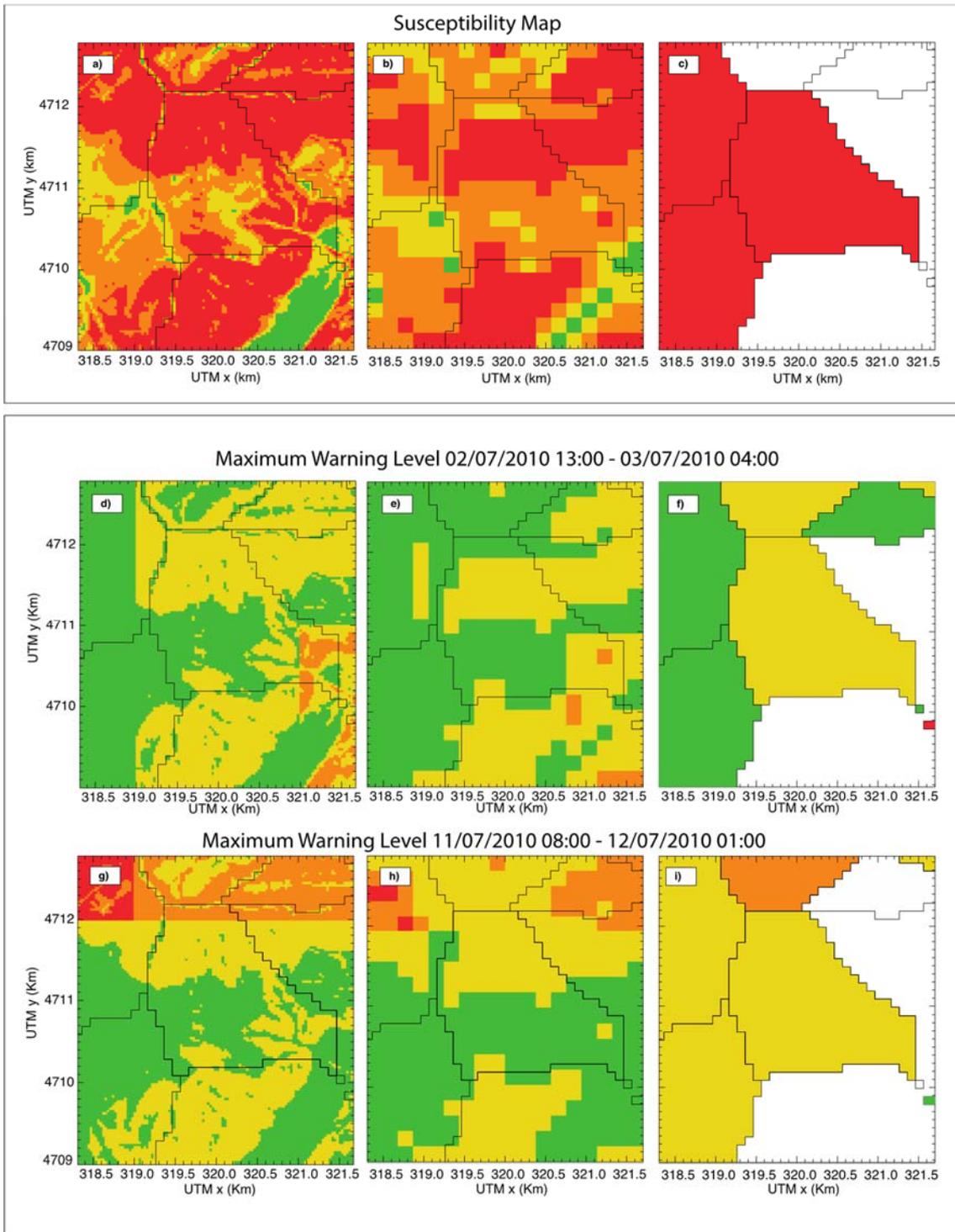
432 **Table 6** Evaluation of the performance of the LEWS for the Rebaixader and Erill monitored sites. The number of  
 433 recorded debris flows and debris floods can be compared with the number of days with maximum warning level  
 434 “moderate” or “high”. True positives are rainfall events with correct warnings, false positives are rainfall events with  
 435 “moderate” or “high” warnings but no detected landslide, debris flow or debris flood event. Misses are rainfall events  
 436 with landslides, debris flows or debris floods but no “moderate” or “high” warnings.

Monitoring site	Mapping Unit	# of days with maximum warning level				#events detected	True Positives	False Positives	Misses
		Very Low	Low	Moderate	High				
Rebaixader	dx = 30 m	148	64	1	1	3	2	0	1
	dx = 200 m	150	62	1	1		2	0	1
	Subbasins	150	62	1	1		2	0	1
Erill	dx = 30 m	146	66	2	2	1	1	2	0
	dx = 200 m	146	66	1	2		1	1	0
	Subbasins	152	60	2	0		1	0	0

437 The false positives at Erill have been further examined. Our analysis shows that the  
 438 significance of the false positives depends on the area (number of pixels) of the subbasin where a  
 439 “moderate” or “high” warning level is issued and its location. Since the monitoring station is  
 440 located at the catchment outlet, small landslides or debris flows happening near the headwaters and

441 traveling short distances are perhaps not detected. Therefore, false positives due to a few  
442 headwaters' pixels with "moderate" or "high" warnings are not very significant. In contrast, a false  
443 positive is more relevant if pixels with "moderate" or "high" warnings are located close to the  
444 outlet or affect a large portion of the catchment.

445 During the analyzed period, a false positive with low significance was issued for the 11 July  
446 2010 event by the 30 m grid-cell configuration at the Erill (**Fig. 12 f**), when a moderate warning was  
447 released. However, the moderate warning was caused by a very small area (4 % of the entire basin)  
448 located in the highest part of the catchment, where the radar recorded larger amounts of rain (**Fig.**  
449 **13 g**). In addition, the grid-cell configurations issued another false positive that affected a portion  
450 of the Erill catchment near the outlet (**Fig. 13 d and e**) during the event of the 2 July 2010. However,  
451 the area over which both configurations issued the warning was different. On the one hand, the  
452 200 m grid-cell set-up issued "moderate" warnings over only a 1.3 % of the catchment area,  
453 therefore its significance was low. On the other hand, the 30 m grid-cell set-up issued "moderate"  
454 warnings over a larger area (4.8 % of the subbasin), therefore its significance was larger.



455

456 **Fig. 13.** Analysis of false positive warning issues at Erill. The top panel displays the susceptibility map based on (a)  
 457 30 m, (b) 200 m grid-cells, and (c) subbasin mapping units. Middle panel shows the maximum warning level for the  
 458 three mapping units at Erill during the 2 July 2010 rainfall event. Bottom panel presents the maximum warning level  
 459 for the three configurations during the July 11 July2010 rainfall. See text for detailed explanations.

460 Additionally, the outputs of the three LEWS configurations have also been checked for the  
 461 reported events in two supplementary unmonitored catchments, where three events were reported:

462 Portainé and Santa Maria (**Fig. 1**). The Portainé catchment has an area of 2.50 km<sup>2</sup>. Two debris  
 463 flow events affected a secondary road and a small dam located downstream, one occurred on the  
 464 22 of July 2010 with a mobilized volume of 25000 m<sup>3</sup>, and a smaller one on 12 August 2010 (Palau  
 465 et al. 2017). The Santa Maria is a 1.70 km<sup>2</sup> catchment located in the mountain of Montserrat.  
 466 Shallow slides and debris flows were reported there by road and railway managing authorities  
 467 during the night of 10 October 2010.

468 The 30 m gridded setup was able to correctly issue a “moderate” or “high” warning level  
 469 coinciding with the approximate time of the events in Portainé and Santa Maria (**Table 7**). On the  
 470 other hand, the 200 m setup failed to issue a warning for the Portainé 22 July 2010 debris flow, and  
 471 the subbasin setup missed both events at Portainé. The computation of the total number of true  
 472 positives, false positives and misses has not been possible for these two sites because only the  
 473 events that affected important infrastructures were reported.

474 **Table 7** Reported debris flows, debris floods and/or shallow slides at the Portainé and Santa Maria catchments and  
 475 maximum warning level issued by the LEWS during each of the rainfall episodes.

Subbasin	Subbasin susceptibility class	Reported events	Type of event	Maximum Warning Level		
				dx= 30 m	dx= 200 m	Subbasins
Portainé	Moderate	22 July 2010	Debris flow	Moderate	Low	Low
		12 August 2010	Debris flow	High	Moderate	Very Low
Santa Maria	High	10 October 2010	Debris flow & shallow slides	High	Moderate	Moderate

476 In summary, the results obtained with the different configurations of the LEWS are quite similar  
 477 and show coherence. The main difference is the lower number of false positives obtained with the  
 478 subbasin setup. However, the 200 m grid-cell and the subbasin configurations also present  
 479 additional misses at Portainé (**Table 7**). It is worth noticing though, that one of the 30 m grid-cell

480 configuration false positives is issued over a very small area at the catchments headwaters and  
481 therefore its significance is low.

### 482 *5.3. Computational requirements*

483 One of the criteria that strongly influences the feasibility to apply the LEWS in real time at  
484 regional scale is the computational cost, which should allow us to update the warning level every  
485 time new rainfall observations are available within a short time. Herein, we have analyzed the  
486 computational cost to run one time step over Catalonia with the different configurations analyzed  
487 in this section 5.

488 To fulfill the computations, we have used a server with two 12-cores 3.5 GHz CPUs and 48  
489 GB of RAM. With the current version of the code, the time needed to fulfill one time step over  
490 the entire Catalonia is around 1.5 min, 2.9 s, and 0.7 s for the case of 30 m, 200 m grid-cells and  
491 subbasins respectively. The computational cost increases with the area of the domain covered by  
492 rain. In either case, the three mapping units could be used to compute warnings operationally. In  
493 section 4 we have decided that it is not yet feasible to run the 5 m grid over Catalonia because with  
494 the current version of the codes completing the calculation of one time-step through Catalonia  
495 requires around 50 min, still far from real-time requirements.

## 496 **6. Discussion and conclusions**

497 This study assesses the influence of the mapping unit into the outputs of a regional scale  
498 LEWS with the aim of selecting the most suitable mapping unit for a real-time LEWS for Catalonia.  
499 Susceptibility maps covering Catalonia have been obtained combining the maps of slope and land  
500 cover with a fuzzy logic approach. This simple methodology has been applied to obtain and  
501 compare susceptibility maps based on different mapping units (pixels of several resolutions and  
502 hydrological subbasins), which have been applied to run a LEWS method in the region of Catalonia  
503 during seven months of 2010.

504 The evaluation of the susceptibility maps has been done using part of the inventory available  
505 in three subdomains in the Catalan Pyrenees and Pre-Pyrenees. The results show that for the  
506 gridded susceptibility maps, its quality decreases with resolution, whereas the one obtained on a  
507 subbasin division performs slightly better than the map based on pixels of 100 m resolution.

508 The analysis of the performance of the LEWS with the studied mapping units shows that  
509 landslide warnings were generally located at susceptible areas affected by large rainfall amounts.  
510 Results show that the area where the warnings were issued increases with the mapping unit  
511 resolution for the grid-cell set-ups but is higher for the subbasins configuration. Due to the lack of  
512 systematic landslide reports, the evaluation of the performance remains a challenge and has been  
513 done for specific locations with reported shallow slides and debris flow events. The subbasin setup  
514 has failed to issue a warning for three landslides that were recorded at the selected sites. The  
515 number of misses decreases with the resolution. While the 200 m grid-cell configuration misses  
516 two landslide events, the 30 m grid-cell setup misses only a debris flood but has an additional false  
517 positive. However, its significance is rather low.

518 Regarding the computational cost, as expected, the high resolution configurations are more  
519 demanding than the coarser configurations. Regardless of that, with the exception of 5 m grid-cells,  
520 all the studied configurations could be applied in real time.

521 Choosing the most appropriate mapping unit for operational LEWS purposes is not trivial. It  
522 must include a compromise between performance, resolution and computational cost, whereas it  
523 must also consider the end-users' interpretability of the warnings. In this sense, at a regional scale  
524 the interpretation of the warnings is much easier for the subbasins configuration. However, grid-  
525 cell configurations have a higher resolution and display the possible landslide initiation zones with  
526 more detail.

527 Based on the results obtained for the analyzed period and monitored sites (a more extensive  
528 evaluation over longer periods of time and with a larger number of landslide reports would be

529 required to make the results more conclusive), the best option may be working with 30-m grid cells  
530 to compute the warnings and present them in subbasins displaying the maximum warning level of  
531 the enclosed pixels. This approach simplifies the assessment at regional scale without losing the  
532 extra information contained in the pixel data. If a warning is issued for a given catchment, detailed  
533 information on the possible landslide triggering areas can be displayed when zooming into it. Thus,  
534 this solution enhances the understanding of the situation and enables to allocate the available  
535 resources in the most problematic places. A similar solution has been adopted in the SIGMA model  
536 (Segoni et al. 2018) where three types of mapping units are used (alert zones, municipalities and  
537 100 m grid-cells).

538 One aspect that is fundamental to guarantee the performance of the LEWS is the quality of  
539 the rainfall inputs. In this regard, the use of radar QPE has clear advantages (i.e. good depiction of  
540 the variability of the rainfall field at high spatio-temporal resolutions), but it also needs careful  
541 processing of radar observations to guarantee the quantitative value of the rainfall products (e.g.  
542 Zawadzki 1984; Corral et al. 2009; Borga et al. 2014), since global or local biases of the rainfall field  
543 have a direct effect on the performance of the LEWS (it may lead to false positives and misses). It  
544 is also worth noting that the spatial resolution of the rainfall inputs (1 km) is much coarser than  
545 that of the LEWS (which matches the resolution of the susceptibility map). This difference, which  
546 can be seen in **Fig. 13**, implies that the small-scale variability of the rainfall field cannot be resolved  
547 and an adds uncertainty in the performance of the LEWS.

548 A limitation of the current LEWS methodology is the lack of well-established rainfall  
549 thresholds in Catalonia. Therefore, IDF-curves of a meteorological station were used to determine  
550 the rainfall hazard level. However, future advances on critical rainfall conditions in Catalonia would  
551 certainly improve the performance of the LEWS. An additional drawback is that the current  
552 thresholds account for neither the antecedent rainfall nor soil moisture conditions. Using regional  
553 rainfall thresholds for landslides, as well as including antecedent rainfall or soil moisture

554 information could help reducing the number of false positives and therefore improve the  
555 performance of the LEWS (Mirus et al. 2018; Bogaard and Greco 2018).

556 Another important factor that could help improve the performance of the LEWS would be  
557 the distinction between weathering limited and sediment unlimited catchments. Weathering limited  
558 catchments require a certain period between debris-flow events to recharge the available sediment.  
559 Currently the input susceptibility maps are static, and therefore, this condition is not considered by  
560 the LEWS

561 Additionally, since most shallow slides and debris flows happen during or shortly after the  
562 triggering rainfall event to issue effective early warnings the presented methodology should be  
563 implemented in real-time using rainfall forecasts (Alfieri et al. 2012), for instance based on radar  
564 nowcasts (e.g. Berenguer et al. 2011) or high-resolution numerical weather prediction.

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571

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