

Master's Thesis

**Doble Màster Universitari en Enginyeria Industrial
(MUEI) i Automàtica i Robòtica (MUAR)**

LPV-MPC Control of a Quadrotor

ANNEX

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ETSEIB

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A Annex

A.1 Control approach schemes

A.1.1 Approach 1

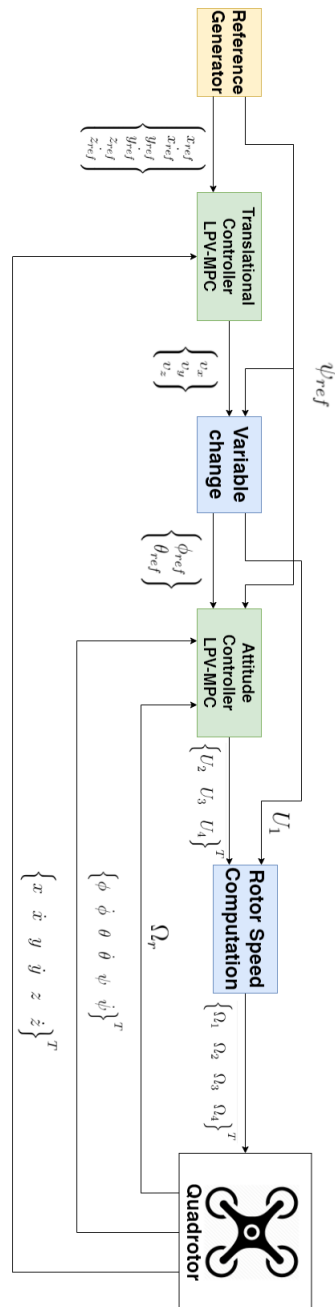


Figure A.1: Control scheme: approach 1 (full size)

A.1.2 Approach 2

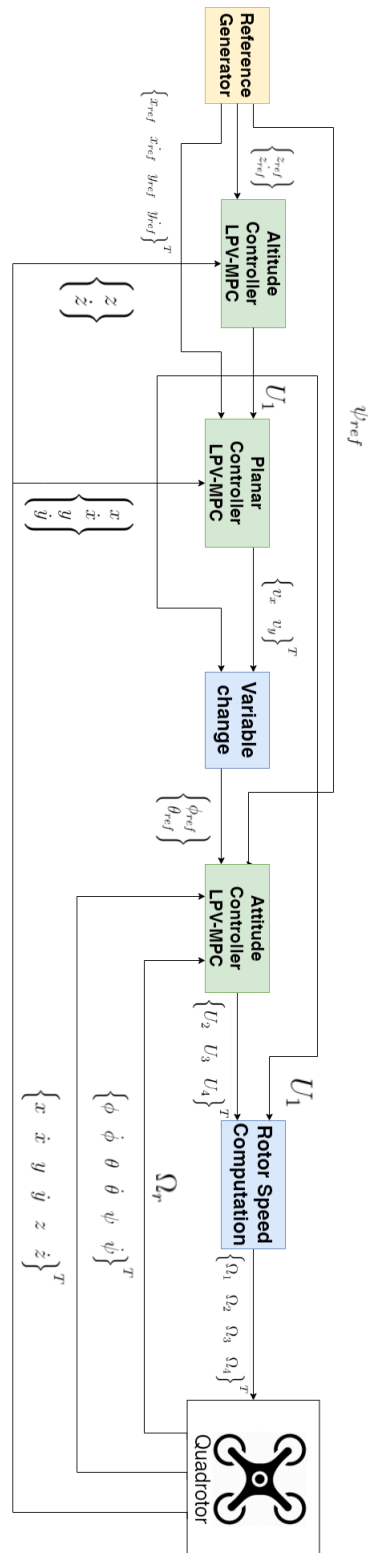


Figure A.2: Control scheme: approach 2 (full size)

A.1.3 Approach 3

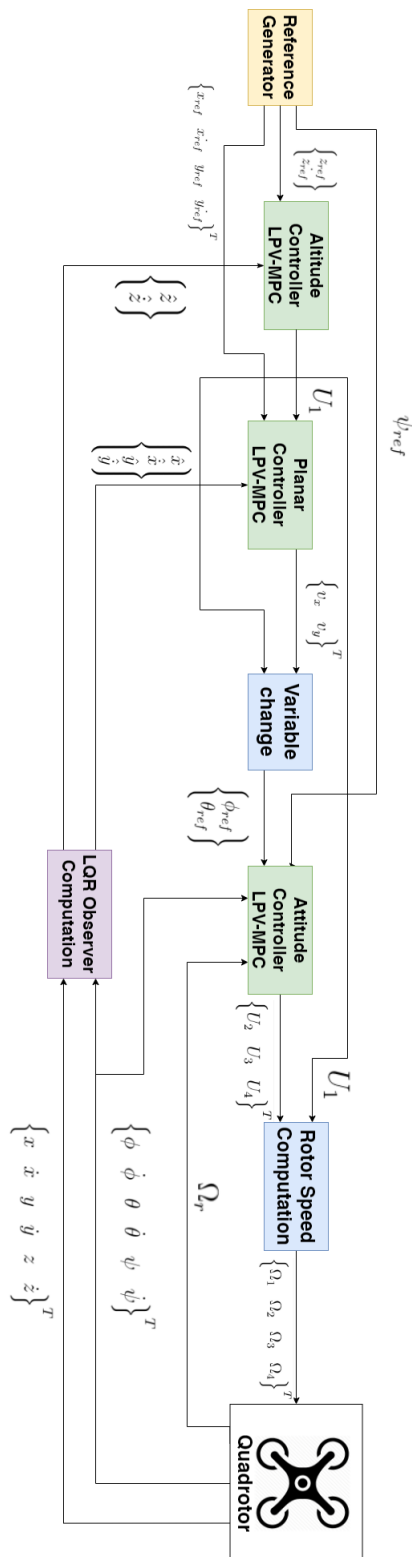


Figure A.3: Control scheme: approach 3 (full size)

A.2 Time planning scheme

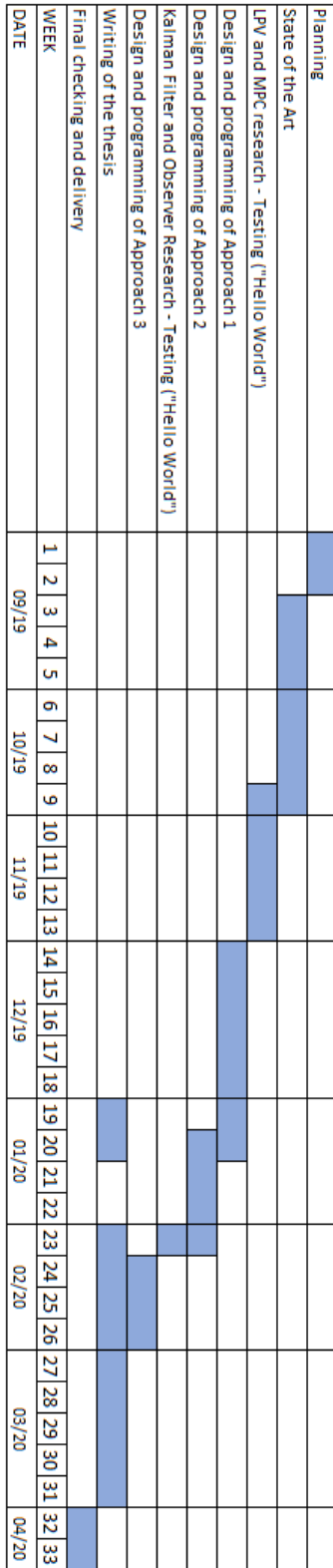


Figure A.4: Gantt Diagram of the project (full size)

