

# Matching random colored points with rectangles

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## Abstract

Let  $S \subset [0, 1]^2$  be a set of  $n$  points, randomly and uniformly selected. Let  $R \cup B$  be a random partition, or coloring, of  $S$  in which each point of  $S$  is included in  $R$  uniformly at random with probability  $1/2$ . We study the random number  $M(n)$  of points of  $S$  that are covered by the rectangles of a maximum strong matching of  $S$  with axis-aligned rectangles. The matching consists of closed rectangles that cover exactly two points of  $S$  of the same color. A matching is strong if all its rectangles are pairwise disjoint. We prove that almost surely  $M(n) \geq 0.83n$  for  $n$  large enough. Our approach is based on modeling a deterministic greedy matching algorithm, that runs over the random point set, as a Markov chain.

## 1 Introduction

Given a point set  $S \subset \mathbb{R}^2$  of  $n$  points, and a class  $\mathcal{C}$  of geometric objects, a *geometric matching* of  $S$  is a set  $M \subseteq \mathcal{C}$  such that each element of  $M$  contains exactly two points of  $S$  and every point of  $S$  lies in at most one element of  $M$ . A geometric matching is *strong* if the geometric objects are pairwise disjoint, and *perfect* if every point of  $S$  belongs to (or is covered by) some element of  $M$ . This type of geometric matching problems was considered by Ábrego et al. [1], who studied the existence and properties of matchings for point sets in the plane when  $\mathcal{C}$  is the class of axis-aligned squares, or the class of disks.

Let  $S = R \cup B \subset \mathbb{R}^2$  be a set of  $n$  colored points in the plane, each point colored red or blue, where

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$R$  and  $B$  are the sets of red and blue points, respectively. A geometric matching of  $S$  is called *monochromatic* if all matching objects cover points of the same color, and *bichromatic* if all matching objects cover points of different colors. For example, monochromatic matchings of two-colored point sets in the plane with straight segments have been studied [4, 5]. In the case of bichromatic matchings with straight segments, a classical result in discrete geometry asserts that for any planar point set  $S$  consisting of  $n$  red points and  $n$  blue points in general position (i.e., no three points of  $S$  are collinear) there exists a perfect, strong bichromatic matching of  $S$  with straight segments.

In this paper, we consider strong monochromatic matchings with axis-aligned rectangles. Every rectangle will be axis-aligned and a closed set.

Caraballo et al. [2] studied monochromatic strong matchings of  $S$  with rectangles from the algorithmic point of view. That is, the problem of finding a monochromatic strong matching of  $S$  with the maximum number of rectangles; proving that the problem is NP-hard and giving a polynomial-time 4-approximation algorithm. As noted by Caraballo et al., this problem is a special case of the Maximum Independent Set of Rectangles problem (MISR): Given a finite set  $\mathcal{R}$  of rectangles in the plane, find a subset  $\mathcal{R}' \subseteq \mathcal{R}$  of maximum cardinality, denoted  $\alpha(\mathcal{R})$ , such that every pair of rectangles in  $\mathcal{R}'$  are disjoint.

Indeed, suppose that we want to find a monochromatic matching of  $S$  with the maximum number of rectangles. For every distinct  $p, q \in \mathbb{R}^2$ , let  $D(p, q)$  be the minimum axis-aligned rectangle that encloses  $p$  and  $q$ . Let  $\mathcal{R}(S)$  be the set of all rectangles  $D(p, q)$  such that  $p, q \in S$ ,  $p$  and  $q$  have the same color, and  $D(p, q)$  contains no points of  $S$  different from  $p$  and  $q$ . Finding a monochromatic strong matching of  $S$  with the maximum number of rectangles is equivalent to finding in  $\mathcal{R}(S)$  a maximum subset of pairwise disjoint rectangles, whose size is  $\alpha(\mathcal{R}(S))$ . That is, to solving the MISR problem in  $\mathcal{R}(S)$ .

We study monochromatic strong matchings of  $S$  with rectangles from the combinatorial point of view, and from this point forward, every rectangle will cover precisely two points of  $S$ . Point sets  $S = R \cup B$  exist

in which no matching rectangle is possible (e.g.,  $S$  is a color-alternating sequence of points on the line  $y = x$ ), and point sets in which a perfect strong matching with rectangles exists (e.g., an even number of red points in the negative part of the line  $y = x$ , and an even number of blue points in the positive part). These two extreme cases show that it is not worth studying the number  $\alpha(\mathcal{R}(S))$  for fixed, or given, colored point sets  $S$ . Instead, we want to study  $\alpha(\mathcal{R}(S))$  when  $S$  is a random point set in the square  $[0, 1]^2$ , in which the positions of the  $n$  points of  $S$  are random and the color of each point of  $S$  is also random. Formally:

Let  $n > 0$ , and let  $S \subset [0, 1]^2$  be a set of  $n$  points, randomly and uniformly selected. Let  $R \cup B$  be a random partition (i.e., coloring) of  $S$  in which each point of  $S$  is included in  $R$  uniformly at random with probability  $1/2$ . We study the random variable  $M(n) = 2 \cdot \alpha(\mathcal{R}(S))$  equal to the number of points of  $S$  that are covered by the rectangles of a maximum monochromatic strong matching of  $S$  with rectangles.

Given a set  $S$  of  $n$  points, randomly and uniformly selected in the square  $[0, 1]^2$ , Chen et al. [3] studied a similar variable: the random variable  $\alpha(D(S))$ , where  $D(S)$  is the random graph with vertex set  $S$  and two points  $p, q \in S$  define an edge if and only if  $D(p, q) \cap S = \{p, q\}$ . Here,  $\alpha(D(S))$  denotes the size of a maximum independent set of  $D(S)$ .

One result of Chen et al. [3, Theorem 1] states that if  $n$  tends to infinity, then we have  $\alpha(D(S)) = O(n(\log^2 \log n) / \log n)$  with probability tending to 1. This result implies that if  $C(n)$  denotes the number of points of  $S$  that are covered by a maximum monochromatic matching of  $S$  with rectangles, where the rectangles may overlap (i.e., the matching is not necessarily strong), then  $C(n) = n - o(n)$  with probability tending to 1. In fact, let  $M'$  be a maximum monochromatic matching of  $S$  with rectangles, where  $M'$  is not necessarily strong, and let  $S' \subset S$  be the points not covered by  $M'$ . Note that at least  $|S'|/2$  points of  $S'$  have the same color, and they form an independent set in the graph  $D(S)$ . Then, with probability tending to 1, we have that  $M'$  covers at least  $n - |S'| = n - O(n(\log^2 \log n) / \log n) = n - o(n)$  points.

## 2 Preliminaries

Since for matching  $S$  with rectangles, only the left-to-right and bottom-to-top orders of  $S$  are relevant, and since the probability that two points of  $S$  are in the same vertical or horizontal line is zero, we consider  $S$  equal to the point set  $S_\pi = \{(i, \pi(i)) \mid i = 1, 2, \dots, n\}$ , where  $\pi : \{1, 2, \dots, n\} \rightarrow \{1, 2, \dots, n\}$  is a randomly and uniformly selected permutation. This assumption was also done by Chen et al. [3].

We have implemented a program that, given  $n$ , generates a uniform random permutation  $\pi$ , and selects the color of each  $p \in S_\pi$  (red or blue) randomly and

$k$	$n = 1000$		$n = 10000$	
	mean	sdev	mean	sdev
1	0.6653	0.0175	0.6673	0.0052
2	0.7948	0.0104	0.7934	0.0036
3	0.8301	0.0097	0.8304	0.0034
4	0.8555	0.0094	0.8562	0.0028
5	0.8727	0.0090	0.8736	0.0026
6	0.8860	0.0087	0.8864	0.0026
$\infty$	0.9724	0.0062	0.9780	0.0022

Table 1: The experimental results obtained when running the greedy matching algorithm for  $n \in \{1000, 10000\}$ , parameterized with  $k \in [1..6]$ , or not parameterized ( $k = \infty$ ). For each combination  $n, k$ , we run the algorithm 100 times, and measured the mean and standard deviation of the ratio between the total number of matched points and  $n$ .

uniformly. The program then runs a deterministic algorithm on  $S_\pi = R \cup B$  that greedily finds a maximum independent subset of rectangles in  $\mathcal{R}(S_\pi)$ . The algorithm iterates the points of  $S_\pi$  from left to right, and for each point  $p$  in the iteration, it performs the following action: If  $p$  is not matched with any point prior to  $p$  in the iteration, it finds the first point  $q$  to the right of  $p$  such that  $D(p, q) \in \mathcal{R}(S_\pi)$  and  $D(p, q)$  has empty intersection with all matching rectangles already reported. If  $q$  exists, the algorithm reports  $D(p, q)$  as a matching rectangle. In any case, regardless of whether  $q$  exists, the algorithm continues the iteration to the next unmatched point  $p$ .

For large  $n$ , say  $n = 10000$ , the implemented algorithm reports a matching covering approximately  $\frac{97}{100}n$  of the points. Then, it seems that  $M(n) \geq \frac{97}{100}n$  for  $n$  large enough and probability close to 1. Analyzing the algorithm, when run over the random  $S_\pi$ , seems to be a good approach for obtaining a high lower bound for  $M(n)$ . One way to analyze the algorithm is to consider a parameterized version of it, with a parameter  $k$ , such that each unmatched point  $p$  finds its match point  $q$  among only the next  $k$  points of  $S_\pi$  to the right of  $p$ . Let  $\mathcal{A}_k$  denote this parameterized algorithm. For experimental results, see Table 1.

We show how to model (an adaptation of)  $\mathcal{A}_k$  as a Markov chain, for any  $k \in \{1, 2, \dots\}$ . Then, we show that  $\mathcal{A}_3$  almost surely guarantees  $M(n) \geq \frac{83}{100}n$ , for  $n$  large enough, by computing the stationary distribution of the Markov chain and applying the Ergodic theorem. See [6] for the theory on Markov chains.

## 3 The Markov chains

We consider  $S = S_\pi$ , and whenever we say point  $i$ , for  $i \in \{1, 2, \dots, n\}$ , or just  $i$  when it is clear from the context, we are referring to the point  $p_i := (i, \pi(i)) \in S$ . Let  $\text{color}(i) \in \{R, B\}$  denote the color of point  $i$ .

Let  $k \in \{1, 2, 3, \dots\}$  be a constant, and let  $\tilde{\mathcal{A}}_k$  be the following adaptation of algorithm  $\mathcal{A}_k$ , consisting

in the next idea: Suppose that  $\mathcal{A}_k$  matches points  $i$  and  $j$ , with  $i < j \leq i + k$ , when the iteration of  $S_\pi$  is on point  $i$ .  $\tilde{\mathcal{A}}_k$  iterates  $S_\pi$  from left to right, and will also match  $i$  and  $j$  but, in contrast with  $\mathcal{A}_k$ , when the iteration is on  $j$ , or on a point to the right of  $j$ . Using  $\tilde{\mathcal{A}}_k$  instead of  $\mathcal{A}_k$ , allows us to describe in a more compact way the states of the memory of the algorithm during the iteration of the elements of  $S_\pi$ .

Let  $E(j)$  be the data structure associated with point  $j \in \{1, 2, \dots, n\}$ , that is maintained by  $\tilde{\mathcal{A}}_k$  during the iteration of  $S_\pi$ . For any  $j$ , let  $i = i(j)$  be the smallest element in the set  $\{\max(1, j - (k - 1)), \dots, j\}$  such that the point  $i$  is not matched, and each point in  $\{i + 1, \dots, j\}$  is matched with a point to the left of  $i$  or is not yet matched. If  $i$  exists, then  $E(j)$  consists of the following elements:

- The set  $U(j) \subseteq \{i, i + 1, \dots, j\}$  of the points that are not matched, with  $i \in U(j)$ .
- The set  $\text{Rect}(j)$  of the (pairwise disjoint) rectangles that match the points in  $\{i + 1, \dots, j\} \setminus U(j)$  with points to the left of  $i$ .
- The number  $f(j)$  of points of  $S_\pi$  that are matched while the iteration is at point  $j$ .

If  $i$  does not exist, then  $E(j)$  consists of the same three above elements with  $U(j) = \emptyset$  and  $\text{Rect}(j) = \emptyset$ .

For  $j = 1$ , we have  $U(1) = \{1\}$ ,  $\text{Rect}(1) = \emptyset$ , and  $f(1) = 0$ . We show now how to obtain  $E(j + 1)$  from  $E(j)$ , for any  $j \in \{1, \dots, n - 1\}$ . First, we match points  $i$  and  $j + 1$  if and only if  $j + 1 \leq i + k$ ,  $\text{color}(i) = \text{color}(j + 1)$ , and the rectangle  $D(p_i, p_{j+1})$  does not overlap any rectangle in  $\text{Rect}(j)$ . After that, we match other points in  $(U(j) \setminus \{i\}) \cup \{j + 1\}$  if and only if  $i$  was matched in the previous step, or we have finished with point  $i$ . We say that we have *finished* with point  $i$  if there do not exist more chances for point  $i$  to be matched, which is equivalent to  $i + k \leq j + 1$ . This final matching procedure consists in running the original algorithm  $\mathcal{A}_k$  with input the points  $\{i + 1, \dots, j, j + 1\}$ , but with the extra condition that the algorithm terminates if the current point  $t$  on the iteration of  $\{i + 1, \dots, j, j + 1\}$  from left to right, cannot be matched with any other one to its right. This is because  $t$  must find its match among the points in  $\{j + 2, \dots, t + k\}$ , before any matching between points in  $\{t + 1, \dots, j + 1\}$  occurs. We set  $f(j + 1)$  equal to the total number of points matched in the above steps. Obtaining  $U(j + 1)$  and  $\text{Rect}(j + 1)$  is straightforward.

Let  $j \in \{1, 2, \dots, n\}$ . The *state* of  $E(j)$  is the 2-tuple formed by: As first component, (a certificate of) the relative positions between the points of  $U(j)$  and the rectangles of  $\text{Rect}(j)$ , together with the color of each point of  $U(j)$ . If the leftmost point is blue, then we switch the color of every point such that the leftmost one is always red. As second component,  $f(j)$ . We say that two states  $e$  and  $e'$  are *equal* (i.e.,  $e = e'$ )

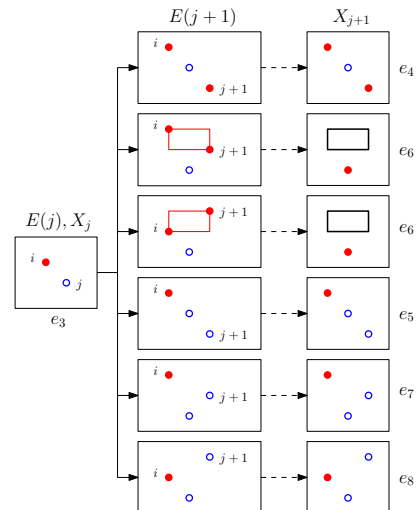


Figure 1: Example of the data structure  $E(j)$ , its state  $X_j = e_3$ , and the states in the neighborhood  $N(e_3) = \{e_4, e_5, e_6, e_6, e_7, e_8\}$  corresponding to  $E(j + 1)$ , for each position and color of point  $j + 1$ . Note that  $f(e_6) = 2$ , and  $f(e) = 0$  for all  $e \in \{e_4, e_5, e_7, e_8\}$ .

if: (i) the first components are equal, or one first component is symmetric to the other in the vertical direction, and (ii) the second components are equal.

Let  $\mathcal{E} = \{e_1, e_2, \dots, e_N\}$  be the set of all possible states of  $E(j)$ , which is a finite set, and let  $X_j \in \mathcal{E}$  be the random variable equal to the state of  $E(j)$ . Let  $e \in \mathcal{E}$  be a state, and assume that  $e$  is the state of  $E(j)$  for some  $j$ . Let  $f(e) = f(j)$  (with abuse of notation), and let  $N(e)$  be the *neighborhood* of  $e$ , which is the multiset consisting of the state of  $E(j + 1)$  for every color and every different relative position, with respect to the elements of both  $U(j)$  and  $\text{Rect}(j)$ , of point  $j + 1$ . See for example Figure 1.

**Lemma 1** Let  $e, e' \in \mathcal{E}$  be two states. For every  $j \geq 2$ , we have:

$$\text{Prob}(X_{j+1} = e' \mid X_j = e) = \frac{m}{2(|U(j)| + 2|\text{Rect}(j)| + 1)},$$

where  $m$  is the multiplicity of  $e'$  in  $N(e)$ .

**Proof.** Through each point of  $U(j)$  draw a horizontal line, and for each rectangle of  $\text{Rect}(j)$  draw a horizontal line through the top side and a horizontal line through the bottom side. Each of these  $K = |U(j)| + 2|\text{Rect}(j)|$  lines goes through a different element of  $S_\pi$ , subdividing the plane into  $K + 1$  strips. Since the point  $j + 1$  is to the right of every point of  $U(j)$  and every rectangle of  $\text{Rect}(j)$ , its relative position w.r.t. the elements of  $U(j)$  and  $\text{Rect}(j)$  is to be in one of these strips, and this happens with probability  $1/(K + 1)$ . Furthermore, the color of point  $j + 1$  is given with probability  $1/2$ . The lemma follows.  $\square$

Note that  $\text{Prob}(X_{j+1} = x_{j+1} \mid X_j = x_j, \dots, X_1 = x_1) = \text{Prob}(X_{j+1} = x_{j+1} \mid X_j = x_j)$  for all

$x_1, \dots, x_{j+1} \in \mathcal{E}$  such that  $\text{Prob}(X_j = x_j, \dots, X_1 = x_1) > 0$ . Thus,  $(X_n)_{n \geq 1}$  is a Markov chain, denoted  $\mathcal{C}_k$ , over the set  $\mathcal{E} = \{e_1, e_2, \dots, e_N\}$  of states. Let  $P$  be the transition matrix, of dimensions  $N \times N$ , such that  $P_{i,j} = \text{Prob}(X_{\ell+1} = e_j \mid X_\ell = e_i)$ . The key observation is that the total number of points matched by  $\tilde{\mathcal{A}}_k$  is precisely  $M_k(n) := \sum_{j=1}^n f(X_j)$ .

A Markov chain is *irreducible* if with positive probability any state can be reached from any other state [6]. It can be proved that  $\mathcal{C}_k$  is irreducible. Since  $\mathcal{C}_k$  has a finite state set, it has a unique stationary distribution  $s = (s_1, s_2, \dots, s_N)$ , which is the solution of the system  $s = s \cdot P$ ,  $s_1 + s_2 + \dots + s_N = 1$  of linear equations [6]. Furthermore, since  $f(e) \in \{0, 2, 4, \dots, 2\lceil \frac{k+1}{2} \rceil\}$  for all  $e \in \mathcal{E}$ , the function  $f$  is bounded and then the Ergodic theorem ensures

$$\lim_{n \rightarrow \infty} \frac{M_k(n)}{n} = \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{j=1}^n f(X_j) = \sum_{i=1}^N s_i f(e_i),$$

almost surely [6]. Let  $\alpha_k = \sum_{i=1}^N s_i f(e_i)$ . We then arrive to the main result of this paper:

**Theorem 2** *Let  $\pi : \{1, 2, \dots, n\} \rightarrow \{1, 2, \dots, n\}$  be a uniform random permutation. Let  $S_\pi = \{(i, \pi(i)) \mid i = 1, 2, \dots, n\}$  be a random point set, where the color (red or blue) of each point of  $S_\pi$  is selected randomly and uniformly with probability 1/2. Let  $k \in \{1, 2, 3, \dots\}$  be a constant. For all constant  $\varepsilon > 0$  and  $n$  large enough, almost surely the number  $M_k(n)$  of points of  $S_\pi$  that are matched by the algorithm  $\tilde{\mathcal{A}}_k$  satisfies  $M_k(n) \geq (\alpha_k - \varepsilon)n$ .*

#### 4 The Markov chain for $k = 3$

Using algorithm  $\tilde{\mathcal{A}}_3$ , we give a precise value for  $\alpha_3$ . In Table 2, we describe the states, and the transitions between the states, of the Markov chain  $\mathcal{C}_3$ . Since  $f(e) = 2$  for all  $e \in \{e_2, e_6, e_9, e_{10}, e_{16}, e_{17}, e_{18}\}$ ,  $f(e_{11}) = 4$ ,  $f(e) = 0$  for all other state  $e$ , and the stationary distribution  $s = (s_1, \dots, s_{18})$  satisfies

$$s_2 = \frac{167959}{816233}, s_6 = \frac{69640}{816233}, s_9 = \frac{6800}{816233}, s_{10} = \frac{58650}{816233},$$

$$s_{11} = \frac{13600}{816233}, s_{16} = \frac{5950}{816233}, s_{17} = \frac{1360}{816233}, s_{18} = \frac{1190}{816233},$$

we obtain

$$\alpha_3 = 2(s_2 + s_6 + s_9 + s_{10} + s_{16} + s_{17} + s_{18}) + 4s_{11} = \frac{677498}{816233} \approx 0.830030151.$$

By Theorem 2, taking  $\varepsilon = \alpha_3 - 0.83 > 0$ , for  $n$  large enough we have almost surely that  $M(n) \geq M_3(n) \geq 0.83n$ . It can be noted in Table 1 that in practice this lower bound is satisfied.

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$e_i$	elem. of $e_i$	$f(e_i)$	neighbors of $e_i$
$e_1$		0	$(e_2, 1/2), (e_3, 1/2)$
$e_2$		2	$(e_1, 1)$
$e_3$		0	$(e_4, 1/6), (e_5, 1/6), (e_6, 1/3), (e_7, 1/6), (e_8, 1/6)$
$e_4$		0	$(e_4, 1/8), (e_5, 1/8), (e_6, 3/8), (e_7, 1/8), (e_9, 1/4)$
$e_5$		0	$(e_{10}, 3/4), (e_{11}, 1/4)$
$e_6$		2	$(e_2, 1/4), (e_{12}, 1/8), (e_{13}, 1/8), (e_{14}, 1/4), (e_{15}, 1/4)$
$e_7$		0	$(e_{10}, 3/4), (e_{11}, 1/4)$
$e_8$		0	$(e_{10}, 3/4), (e_{16}, 1/4)$
$e_9$		2	$(e_2, 3/10), (e_{12}, 1/10), (e_{14}, 1/5), (e_{15}, 1/5), (e_{17}, 1/5)$
$e_{10}$		2	$(e_2, 1/2), (e_3, 1/2)$
$e_{11}$		4	$(e_1, 1)$
$e_{12}$		0	$(e_2, 1/2), (e_3, 3/10), (e_6, 1/5)$
$e_{13}$		0	$(e_2, 1/2), (e_3, 3/10), (e_6, 1/5)$
$e_{14}$		0	$(e_2, 3/10), (e_3, 1/2), (e_6, 1/5)$
$e_{15}$		0	$(e_2, 1/2), (e_3, 3/10), (e_6, 1/5)$
$e_{16}$		2	$(e_2, 1/5), (e_{12}, 1/10), (e_{13}, 1/10), (e_{14}, 1/10), (e_{15}, 3/10), (e_{18}, 1/5)$
$e_{17}$		2	$(e_1, 5/6), (e_2, 1/6)$
$e_{18}$		2	$(e_1, 5/6), (e_2, 1/6)$

Table 2: The 18 states of the Markov chain for  $k = 3$ . In the 2nd column we show the first component of  $e_i$ , and in the 3rd column the second component  $f(e_i)$ . In the last column we show the neighbor states of  $e_i$  as a list of tuples of the form  $(e_j, P_{i,j})$ , where  $P_{i,j} = \text{Prob}(X_{\ell+1} = e_j \mid X_\ell = e_i) > 0$  is the transition probability from  $e_i$  to  $e_j$ .

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