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# Stability of $(A, B)$ -invariant subspaces

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## Context

- Characterization of **stable** invariant subspaces
  - of an **endomorphism**: **done**
  - of a **pair of matrices**: **open problem**

## Notation

$$\mathcal{M} = \left\{ (A, B, W, F) : A \in M_n(\mathbb{F}), B \in M_{n,m}(\mathbb{F}), W \in \text{Gr}_d(\mathbb{F}^n), \right. \\ \left. F \in M_{m,n}(\mathbb{F}), (A + BF)W \subset W \right\}$$

$\cap$

$$\mathcal{N} = M_n(\mathbb{F}) \times M_{n,m}(\mathbb{F}) \times \text{Gr}_d(\mathbb{F}^n) \times M_{m,n}(\mathbb{F})$$

$\text{Gr}_d(\mathbb{F}^n)$  set of  $d$ -dimensional subspaces of  $\mathbb{F}^n$

$\mathbb{F} = \mathbb{R}$  or  $\mathbb{C}$

$\mathcal{P}_d$  set of orthogonal projector operators of rank  $d$ ,

$$\mathcal{P}_d = \left\{ P \in M_n(\mathbb{F}) : P^* = P, P^2 = P, \text{rank } P = d \right\}$$

## Aim

To obtain computable conditions of stability of  $(A,B)$ -invariant subspaces

- Local **coordinate** charts of  $\mathcal{M}$  and  $\mathcal{N}$
- $\mathcal{M}$  is a **manifold**
- **Sufficient condition** of stability

## Endomorphisms

- **A-invariant subspace**

**Definition**  $A \in M_n(\mathbb{F})$ ,  $W \in \text{Gr}_d(\mathbb{F}^n)$

$$A(W) \subset W$$

- **A-stable invariant subspace**

**Definition**  $A \in M_n(\mathbb{F})$ ,  $W \in \text{Gr}_d(\mathbb{F}^n)$  invariant is **stable** if given  $\varepsilon > 0$  there exists a  $\delta > 0$  such that  $\|A' - A\| < \delta$  for a linear map  $A' \in M_n(\mathbb{F})$  implies that  $A'$  has an invariant subspace  $W'$  with  $\Theta(W, W') < \varepsilon$

## Pairs of matrices

- $(A,B)$ -invariant subspace

**Definition**  $A \in M_n(\mathbb{F})$ ,  $B \in M_{n,m}(\mathbb{F})$ ,  $W \in \text{Gr}_d(\mathbb{F}^n)$

$$A(W) \subset W + \text{Im } B$$

- $(A,B)$ -stable invariant subspace

**Definition**  $A \in M_n(\mathbb{F})$ ,  $B \in M_{n,m}(\mathbb{F})$ ,  $W \in \text{Gr}_d(\mathbb{F}^n)$

$(A,B)$ -invariant is  $(A,B)$ -stable if given  $\varepsilon > 0$  there exists a  $\delta > 0$  such that  $\|(A',B') - (A,B)\| < \delta$  for a pair  $A' \in M_n(\mathbb{F})$ ,  $B' \in M_{n,m}(\mathbb{F})$  implies that  $(A',B')$  has an  $(A',B')$ -invariant subspace  $W'$  with  $\Theta(W, W') < \varepsilon$

## Differentiable structure of $\mathcal{M}$

- Suggestion of U. Helmke ( $\mathcal{P}_d$ )
- Preliminary results

### Proposition

- (i)  $\mathcal{P}_d$  submanifold of  $M_n(\mathbb{F})$
- $$\dim \mathcal{P}_d = d(n-d)$$
- (ii)  $T_P \mathcal{P}_d = \{[P, \Omega] : \Omega = -\Omega^*, \Omega \in M_n(\mathbb{F})\}$
- $$[P, \Omega] = P\Omega - \Omega P$$
- (iii)  $\mathcal{P}_d \approx \text{Gr}_d(\mathbb{F}^n)$

### Proposition

$$\mathcal{N} = M_n(\mathbb{F}) \times M_{n,m}(\mathbb{F}) \times \mathcal{P}_d \times M_{m,n}(\mathbb{F})$$

$$\mathcal{M} = \{(A, B, P, F) \in \mathcal{N} : (A + BF)P = P(A + BF)P\}$$



## Differentiable structure of $\mathcal{M}$

- Local coordinate charts of  $\mathcal{M}$  and  $\mathcal{N}$

We consider  $(A_0, B_0, W_0, F_0) \in \mathcal{N}$  such that

$$W_0 = \text{Im} \begin{bmatrix} I_d \\ 0 \end{bmatrix}$$

### Lemma

$$\mathcal{N}_0 = \left\{ (A, B, W, F) : A \in M_n(\mathbb{F}), B \in M_{n,m}(\mathbb{F}), \right. \\ \left. W = \text{Im} \begin{bmatrix} I_d \\ Q \end{bmatrix}, Q \in M_{n-d,d}(\mathbb{F}), F \in M_{m,n}(\mathbb{F}) \right\}$$

is an open set of  $\mathcal{N}$  that contains  $(A_0, B_0, W_0, F_0)$

### Lemma

$$\mathcal{M}_0 = \left\{ \left( \begin{pmatrix} A_1 & A_2 \\ A_3 & A_4 \end{pmatrix}, \begin{bmatrix} B_1 \\ B_2 \end{bmatrix}, \text{Im} \begin{bmatrix} I_d \\ Q \end{bmatrix}, [F_1 \quad F_2] \right) : \right. \\ \left. A_3 = QA_1 - A_4Q + QA_2Q + QB_1F_1 + QB_1F_2Q - B_2F_1 - B_2F_2Q \right\}$$

## Differentiable structure of $\mathcal{M}$

- Local coordinate charts of  $\mathcal{M}$  and  $\mathcal{N}$

**Proposition**  $\gamma : \mathbb{F}^{n^2+d(n-d)+2nm} \rightarrow \mathcal{N}_0$

$$\begin{aligned} \gamma(A_1, A_2, A_3, A_4, B_1, B_2, Q, F_1, F_2) = \\ = \left( \begin{pmatrix} A_1 & A_2 \\ A_3 & A_4 \end{pmatrix}, \begin{bmatrix} B_1 \\ B_2 \end{bmatrix}, \text{Im} \begin{bmatrix} I_d \\ Q \end{bmatrix}, [F_1 \quad F_2] \right) \end{aligned}$$

$(\mathcal{N}_0, \gamma)$  coordinate system of the manifold  $\mathcal{N}$

**Theorem**  $\psi : \mathbb{F}^{n^2+2nm} \rightarrow \mathbb{F}^{n^2+d(n-d)+2nm}$

$$\begin{aligned} \psi(A_1, A_2, A_4, B_1, B_2, Q, F_1, F_2) = (A_1, A_2, QA_1 - A_4Q + QA_2Q + \\ + QB_1F_1 + QB_1F_2Q - B_2F_1 - B_2F_2Q, A_4, B_1, B_2, Q, F_1, F_2) \end{aligned}$$

$$\theta := \gamma \circ \psi$$

$(\mathcal{M}_0, \theta)$  coordinate system of  $\mathcal{M}$

$\Rightarrow \mathcal{M}$  is a manifold,  $\boxed{\dim \mathcal{M} = n^2 + 2nm}$

## Differentiable structure of $\mathcal{M}$

$$\begin{array}{ccc}
 \mathbb{F}^{n^2+d(n-d)+2nm} & \xrightarrow{\gamma} & \mathcal{N}_0 \\
 (A_1, A_2, A_3, A_4, B_1, B_2, Q, F_1, F_2) & & \left( \begin{pmatrix} A_1 & A_2 \\ A_3 & A_4 \end{pmatrix}, \begin{bmatrix} B_1 \\ B_2 \end{bmatrix}, \text{Im} \begin{bmatrix} I_d \\ Q \end{bmatrix}, [F_1 \quad F_2] \right) \\
 (A_1, A_2, QA_1 - A_4Q + QA_2Q + QB_1F_1 + \\
 QB_1F_2Q - B_2F_1 - B_2F_2Q, A_4, B_1, B_2, Q, F_1, F_2) & & \\
 \psi \uparrow & \nearrow \theta = \gamma \circ \psi & \cup \\
 \mathbb{F}^{n^2+2nm} & & \mathcal{M}_0 \\
 (A_1, A_2, A_4, B_1, B_2, Q, F_1, F_2) & & 
 \end{array}$$

**Theorem**  $\mathcal{M}$  submanifold of  $\mathcal{N}$

**Proposition**  $\chi = (A, B, P, F) \in \mathcal{M}$ ,

$$\begin{array}{l}
 T_\chi \mathcal{M} = \{ (\dot{A}, \dot{B}, \dot{P}, \dot{F}) : \dot{A} \in M_n(\mathbb{F}), \dot{B} \in M_{n,m}(\mathbb{F}), \dot{P} \in T_P \mathcal{P}_d, \dot{F} \in M_{m,n}(\mathbb{F}), \\
 (I - P)(A\dot{P} + \dot{A}P + B\dot{F}P + B\dot{F}P + \dot{B}FP) - \dot{P}(A + BF)P = 0 \}
 \end{array}$$

## Differentiable structure of $\mathcal{M}$

**Proof** (Tangent space of  $\mathcal{M}$ )

Smooth map  $\varphi$

$$\varphi : \mathcal{N} \rightarrow M_n(\mathbb{F})$$

$$\chi = (A, B, P, F) \mapsto (A + BF)P - P(A + BF)P$$

$$\mathcal{M} = \varphi^{-1}(0)$$

$$\begin{aligned} d\varphi_\chi(\dot{A}, \dot{B}, \dot{P}, \dot{F}) &= (\dot{A} + \dot{B}F + B\dot{F})P + (A + BF)\dot{P} \\ &\quad - \dot{P}(A + BF)P - P(\dot{A} + \dot{B}F + B\dot{F})P - P(A + BF)\dot{P} \end{aligned}$$

$$\langle X, L^* \rangle = \text{tr}(XL) ; L^* \in \left( \text{Im } d\varphi_\chi \right)^\perp \Leftrightarrow$$

$$\begin{aligned} \text{tr} \left( (\dot{A} + \dot{B}F + B\dot{F})P + (A + BF)\dot{P} - \dot{P}(A + BF)P + \right. \\ \left. + [P, \Omega](L(A + BF) - LP(A + BF) - (A + BF)PL) \right) = 0 \end{aligned}$$

$$\begin{aligned} \forall \dot{A} \in M_n(\mathbb{F}), \forall \dot{B} \in M_{n,m}(\mathbb{F}), \forall \dot{F} \in M_{m,n}(\mathbb{F}), \\ \forall \Omega \in M_n(\mathbb{F}), \Omega = -\Omega^* \end{aligned}$$

## Differentiable structure of $\mathcal{M}$

$$\Leftrightarrow PL(I - P) = 0$$

$$\begin{aligned} (\text{Im } d\varphi_\chi)^\perp &= \{L^* \in M_n(\mathbb{F}) : PL(I - P) = 0\} = \\ &= \{L \in M_n(\mathbb{F}) : (I - P)LP = 0\} \end{aligned}$$

$$P = \begin{pmatrix} I_d & 0 \\ 0 & 0 \end{pmatrix}, L = \begin{pmatrix} L_1 & L_2 \\ L_3 & L_4 \end{pmatrix}$$

$$\Leftrightarrow L_3 = 0$$

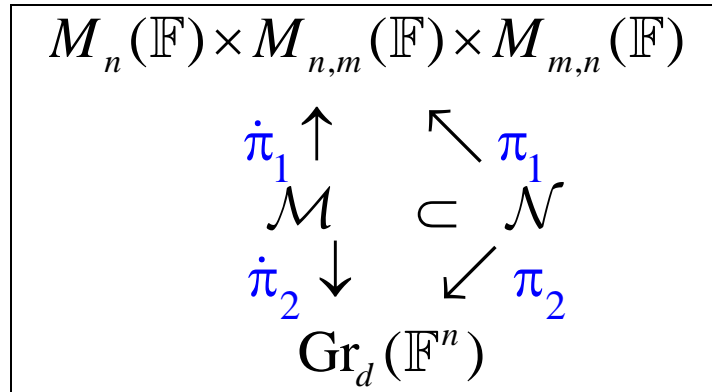
$$\text{rank } d\varphi_\chi = d(n - d)$$

$$\begin{aligned} \dim \mathcal{M} &= \dim \mathcal{N} - \text{rank } d\varphi_\chi = \\ &= (n^2 + d(n - d) + 2nm) - d(n - d) = n^2 + 2nm \end{aligned}$$

$$\dim(\text{Ker } d\varphi_\chi) = \dim(T_\chi \mathcal{M})$$

$$T_\chi \mathcal{M} = \text{Ker } d\varphi_\chi$$

## Stability of $(A,B)$ -invariant subspaces



$$\pi_1(A, B, P, F) = (A, B, F)$$

$$\pi_2(A, B, P, F) = \text{Im } P$$

### • Properties of $\dot{\pi}_2$

### Proposition

- (i)  $\chi = (A, B, P, F) \in \mathcal{M}$ ,  $\boxed{\text{rank } d\dot{\pi}_{2,\chi} = d(n-d)}$
- (ii)  $\dot{\pi}_2 : \mathcal{M} \rightarrow \text{Gr}_d(\mathbb{F}^n)$  is a **submersion**

## Stability of $(A,B)$ -invariant subspaces

- Sufficient condition of stability

**Theorem**  $\chi = (A, B, P, F) \in \mathcal{M}$ ,

$$\boxed{d\pi_{1,\chi} \text{ bijective} \Rightarrow W \text{ } (A, B)\text{-stable}}$$



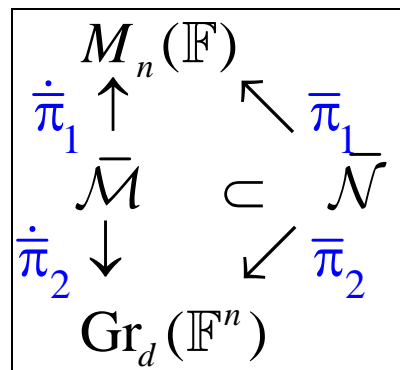
$$\{\dot{P} \in T_P \mathcal{P}_d : (I - P)(A + BF)\dot{P} - \dot{P}(A + BF)P = 0\} = \{0\}$$

## Comparison with stability of $A$ -invariant subspaces

Given an endomorphism,

$$\bar{\mathcal{M}} = \{(A, W) : A \in M_n(\mathbb{F}), W \in \text{Gr}_d(\mathbb{F}^n), A(W) \subset W\}$$

$$\bar{\mathcal{N}} = M_n(\mathbb{F}) \times \text{Gr}_d(\mathbb{F}^n)$$



$$\bar{\pi}_1(A, W) = A$$

$$\bar{\pi}_2(A, W) = W$$

### • Sufficient condition of stability

**Theorem**  $(A, W) \in \bar{\mathcal{M}}$ ,

$$\boxed{d\dot{\pi}_{1,(A,W)} \text{ bijective} \Rightarrow W \text{ } A\text{-stable}}$$

$\Updownarrow$

$$\left\{ \begin{array}{l} -P\Omega AP + \Omega AP - A\Omega P + PA\Omega P = 0 \\ \Omega \in M_n(\mathbb{F}), \Omega = -\Omega^* \end{array} \right\} \Rightarrow P\Omega = \Omega P$$



## References

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- [3] [L. Rodman](#), *Stable Invariant Subspaces Modulo a Subspace*, Operator Theory, Advances and Applications, vol. 19, 399-413, Birkhauser Verlag Bassel (1986).
- [4] [F. Velasco](#), *Stable Subspaces of Matrix Pairs*, Linear Algebra Appl., 301 (1999), p. 15-49.
- [5] [W. Wonham](#), *Linear Multivariable Control: A Geometric Approach*, Springer, New York (1979).