

Effects of gravity level on bubble detachment, rise, and bouncing with a free surface

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ABSTRACT

Bubble detachment, rise, and bouncing upon impact with a free surface is studied experimentally in variable gravity conditions. Previous investigations focused on the effects of fluid properties such as viscosity or surface tension on the rise and bouncing dynamics. Gravity force is a crucial factor in the detachment, rise and bouncing processes. However, the effect of different gravity levels has never been studied experimentally. In this paper we analyze the role of gravity in the detachment, rise velocity and bouncing motion of millimetric bubbles colliding with a free surface. Single air bubbles in ethanol are detached from a nozzle by the buoyancy force. After reaching a terminal velocity, the rising bubble interacts with the free surface in a bouncing process prior to coalescence. The equivalent bubble diameter at detachment decreases as the gravity level increases, in agreement with the theoretical prediction. An expression for the terminal velocity as a function of gravity is proposed. The terminal velocity is found to increase with the gravity level, although bubbles are smaller at higher values of gravity. The bouncing process has been modelled by a damped oscillator, in which the free surface acts as an elastic membrane. An expression for the frequency of bouncing as a function of gravity has been obtained, showing a good agreement with the experimental results. The motion of the bubble during the bouncing process can be approximated by an underdamped oscillator even if viscosity is negligible. Therefore, viscosity is not the main responsible for damping, which is probably due to energy transfer from the bubble to the fluid in the form of vortex and surface waves generation.

keywords: bubble detachment; bubble rise; bubble shape; bubble bouncing; free surface; hypergravity.

I. INTRODUCTION

Many industrial applications require the use of bubbly flows with controlled dynamics. Hence, the enhancement of the understanding of bubble dynamics is essential in order to improve the operation of such applications. In particular, the collision of bubbles with a gas-liquid interface is a common phenomenon in bubbly flows. The dynamics of these interactions are a key aspect to determine whether the collision will result in the formation of foams, flotation aggregates or bubble coalescences.

The collision of a bubble with a free interface depends on the characteristics of the bubble rise before impact, which in turn depends on the process of detachment from a nozzle. The bubble diameter at detachment determines its terminal rise velocity, which determines the coalescence or bouncing after the collision with the free interface.

In the present case of study, a millimetric gas bubble is released from a nozzle and it rises until it collides with a free surface. The overall process can be divided into four stages: (i) detachment from the nozzle, (ii) bubble rise, (iii) bouncing with the free surface and (iv) bubble coalescence.

Bubble formation and detachment from a nozzle have been studied by many authors over the years. The reader may refer to [Kulkarni and Joshi \(2005\)](#) for a detailed review of the existing models. [Carrera et al. \(2006\)](#) studied the bubble formation in microgravity conditions, reporting that at low gas

flow rates the bubble size is not uniform and the frequency of bubble generation is very difficult to control.

Many attempts to model the bubble shape and terminal velocity in the steady rise have been carried out ([Moore, 1965](#), [Tomiya et al., 1998](#), [Bozzano and Dente, 2001](#), [Rodrigue, 2001](#), [de Vries et al., 2002](#), [Kulkarni and Joshi, 2005](#), [Loth, 2008](#), [Sanada et al., 2008](#), [Legendre et al., 2012](#), [Maldonado et al., 2013](#), [Suñol and González-Cinca, 2015](#)). However, due to the complexity of the problem, most of the predictions are largely in terms of empirical correlations which are for the most part based on specific test conditions. The application of these correlations to other test conditions may not be valid, in particular when the gravity level is changed.

Most of the studies on bubble bouncing carried out up to date consider the collision of a gas bubble with a solid wall ([Tsao and Koch, 1997](#), [Klaseboer et al., 2001](#), [Legendre et al., 2005](#), [Malysa et al., 2005](#), [Legendre et al., 2006](#), [Zenit and Legendre, 2009](#), [Manica et al., 2014](#), [Klaseboer et al., 2014](#)). In this configuration the bubble bouncing is due uniquely to bubble surface deformations upon impact with the solid wall. However, the collision of a bubble with a free surface is a more complex bouncing process characterized by the deformation of both the bubble shape and the free surface. [Sanada et al. \(2005\)](#) and [Suñol and González-Cinca \(2010\)](#) reported that there is a critical threshold determined by the bubble characteristics that separates the bouncing and non-

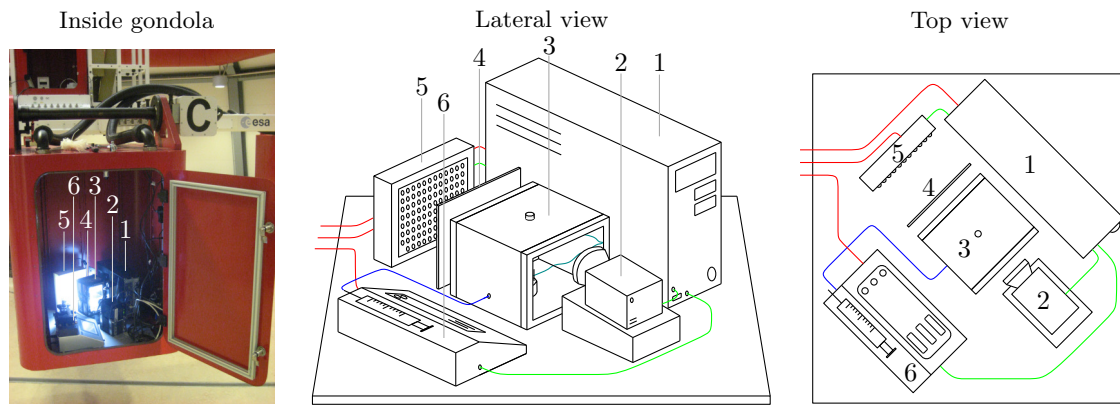


Figure 1. Experimental setup. Red lines: power connections. Blue line: gas connection. Green line: control connections. 1: Computer; 2: High-speed camera; 3: Test cell; 4: Diffuser sheet; 5: LED Matrix; 6: Syringe pump.

53 bouncing regimes of the interaction: the bubble may bounce
 54 a few times before coalescing, or the bubble may coalesce
 55 soon as it reaches the free surface. Air bubbles in ethanol show
 56 two distinct behaviors when they impact with a free surface
 57 in normal gravity conditions: bubbles with diameter $d < 0.47$
 58 mm coalesce with the free surface immediately after impact,
 59 while bubbles with $d > 0.47$ mm bounce a few times before
 60 coalescence.

61 Zawala et al. (2011, 2013) and Kosior et al. (2014) stud-
 62 ied the bouncing process in resting and vibrating surfaces,
 63 concluding that highly deformed bubbles, which is related to
 64 fluid properties, bounce because the liquid film separating the
 65 gas phases has a large thickness, so that the bubble-interface
 66 contact time is shorter than the time needed for the film to
 67 drain.

68 The dynamics of the bouncing process of a bubble upon
 69 impact with a free surface has been properly modelled by
 70 Sato et al. (2011) using a coupled mass-spring approximation.
 71 In this model, two springs connected in series are considered.
 72 One spring corresponds to the bubble shape deformation while
 73 the other one corresponds to the deformation of the free
 74 surface. The model contains two parameters that must be
 75 empirically determined for particular experimental conditions.
 76 Although the bouncing of a bubble impacting at a solid wall or
 77 a free surface is a highly dissipative process (Tsao and Koch,
 78 1997), the model by Sato et al. (2011) does not contain any
 79 dissipative terms.

80 Zawala and Malysa (2011) studied the influence of the
 81 impact velocity and the size of the water film formed in the
 82 coalescence of a bubble with a free surface, showing that the
 83 bubble bounces when the thinning film does not reach its
 84 rupture thickness during the collision time. The film formed
 85 by the colliding bubble ruptured for radius smaller than 0.28
 86 mm. Pigeonneau and Sellier (2011) numerically investigated
 87 the evolution of both the bubble and the free surface shape by
 88 means of a boundary-integral method. For weakly deformed
 89 interfaces (corresponding to high values of the surface tension
 90 force), the film drainage time was found to be faster than for
 91 large interface deformations.

92 Other investigations on the bubble bouncing process were

mainly focused on the effects of viscosity in the bouncing
 dynamics (Sanada et al., 2005), or the effects of salt concen-
 tration and velocity of approach (Del Castillo et al., 2011).
 The gravity level is one of the main parameters governing
 the dynamics of the bubble from its detachment from the
 nozzle until its coalescence with the free surface. In spite
 of the importance of gravity in the whole phenomenon, no
 experimental studies have been carried out up until to analyze
 its effects.

The main objective of this work is to study the effects of
 gravity on the bubble detachment diameter, terminal velocity
 and drag coefficient, and to find a relation between the fre-
 quency of bouncing and the gravity level. The bubble bouncing
 with a free surface is modelled as a damped oscillator, in which
 the free surface acts as an elastic membrane and the bubble
 shape is approximated to be constant.

In Sec. II, the experimental setup and procedure are pre-
 sented. Results on the bubble detachment, bubble steady rise,
 and the bouncing process are presented in Sec. III. Sec. IV
 contains the conclusions of this work.

II. EXPERIMENTAL SETUP AND PROCEDURE

In order to study the effects of the gravity level on the
 bouncing of a bubble impacting at a free surface, we designed
 an experimental setup and run it at the ESA Large Diameter
 Centrifuge (LDC) of the European Space Agency in ESTEC
 (Noordwijk, The Netherlands). This platform allows to explore
 hypergravity levels from $1g_0$ up to $20g_0$, where $g_0 = 9.81$
 m/s^2 is the acceleration due to gravity at sea level. The LDC
 allows to reach $g = 20g_0$ only at the bottom of the capsule
 (“gondola”).

The experimental setup integrated in the gondola consists
 of a test cell, a bubble injection system, and a data acquisition
 system (Fig 1). The test cell is a tank with a rectangular
 prism shape of dimensions $140 \times 60 \times 90 \text{ mm}^3$ (height \times
 width \times length), with aluminium and methacrylate walls filled
 with ethanol up to 100 mm. A nozzle (Hamilton RN Needle
 with inner diameter $d_c = 0.15 \text{ mm}$ and outer diameter
 $d_o = 0.8 \text{ mm}$) is placed in the direction of gravity at the
 center of the tank. The distance between the nozzle tip and the

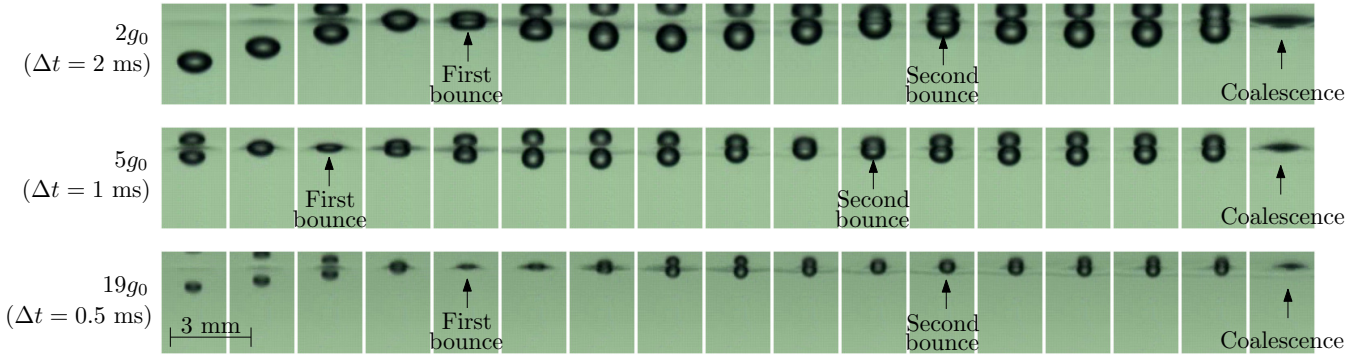


Figure 2. Sequence of snapshots of the bubble bouncing process at $2g_0$ (top row), $5g_0$ (middle row), and $19g_0$ (bottom row).

free surface is 22 mm. This distance was chosen as the result of the balance between reaching the bubble terminal velocity and obtaining a rectilinear vertical path. On the one hand, if the distance is smaller than 2 cm, bubbles may not reach the terminal velocity before the impact with the free surface. On the other hand, if the distance is higher than a few centimeters, the Coriolis force can trigger a path instability and bubbles can undergo a zig-zag or helical path (Suñol and González-Cinca, 2015), breaking the axisymmetry of the collision. The tip of the nozzle is at 14 cm from the bottom of the gondola. Since $g = 20g_0$ is only reached at the bottom of the capsule, we decided to change the resulting artificial gravity level from $1g_0$ to $19g_0$ (at the nozzle tip). Air is injected into the tank through the nozzle using a syringe pump (KDS Legato 180). When a steady flow rate of approximately one bubble every five seconds is reached (inertial forces are negligible at this flow rate), the data acquisition starts. A gas outlet is placed at the top of the tank in order to avoid any overpressure.

The data acquisition system consists of a high-speed video camera, a matrix of 140 ultrabright LED and a diffuser sheet. The tank has two methacrylate windows to allow the illumination of the inside of the cell from one window and the recording of the phenomena of study from the other window. LED was chosen as lighting candidate with the aim to avoid temperature along the series of experiments, which were conducted at room temperature. The high-speed camera (RedLake Motion Xtra HG-SE) records the detachment, rising, bouncing and coalescence processes at 2000 frames per second. The spatial resolution of the images is 0.03 mm/pixel. The high-speed camera is placed at a height slightly below the free surface and tilted an angle of 5° . This is necessary to avoid blurred images of the free surface, and allows the recording of both real and mirrored images of the bubble when it is near the free surface.

The high-speed camera and the syringe pump are controlled by a fanless computer. An ethernet connection between the ground workstation and the computer allowed to remotely control the experiment using VNC and LabView software.

Once the desired artificial gravity level is achieved in the LDC, the experimental procedure consists in the following steps:

- 1) Switching on the illumination and the video camera.
- 2) Bubble injection from the nozzle.

3) Video recording of bubble detachment, rise, and bouncing.

4) Transfer of the recorded video to the computer.

The total required time for these steps is between 5 and 8 min. Most of this time is employed for the transfer of the high-speed movie to the computer. The procedure is carried out for each gravity level.

III. RESULTS AND DISCUSSION

In our experiments, a millimetric gas bubble is injected from the nozzle and rises until it collides with the free surface. The whole process can be divided into four stages: bubble detachment from the nozzle, bubble rise, bubble bouncing with the free surface, and bubble coalescence. We focus our study on the three first stages. Fig. 2 shows a sequence of snapshots of the bubble bouncing and coalescence process. The top row corresponds to a bubble bouncing at $g = 2g_0$, and consecutive frames are separated by a time interval of $\Delta t = 2$ ms. The middle row shows a bubble bouncing at $g = 5g_0$, with consecutive frames separated by $\Delta t = 1$ ms. In the bottom row, the gravity level is $g = 19g_0$ and consecutive frames are separated by $\Delta t = 0.5$ ms. In these three cases, the bubble bounces twice before coalescing with the free surface.

The number of bounces of each bubble could be predicted if the energy dissipation at each collision was known. Coalescence involves the existence of a drainage time T_d of the liquid film formed between the bubble and the free surface. For $T_c < T_d$ (where T_c is the contact time between the bubble and the free surface), the bubble will bounce, while for $T_c > T_d$, the bubble will coalesce with the free surface. T_c is usually defined as $T_c = d/v_a$, where v_a is the approach velocity of the bubble to the free surface, and d is the bubble diameter. The bouncing of a bubble with a free surface is a dissipative process. As a consequence, the energy associated with the bubble motion diminishes and the approach velocity v_a decreases at every bounce until $d/v_a > T_d$, which results in bubble coalescence with the free surface. The shape and size of the bubble also play a determining role on the coalescence process (Suñol and González-Cinca, 2010, Zawala and Malysa, 2011, Pigeonneau and Sellier, 2011). The drainage time and the approach velocity are closely related to the size and shape of the bubble. The drainage time increases

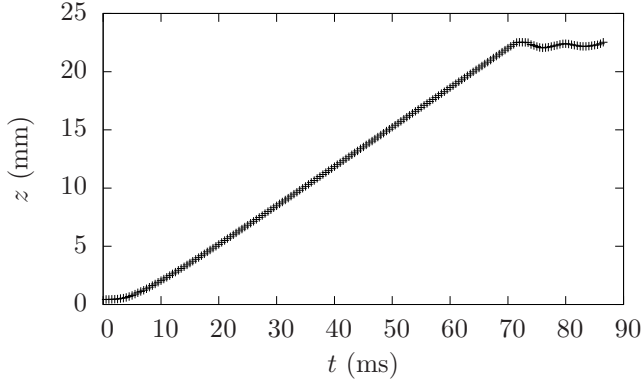


Figure 3. Bubble center position as a function of time.

for larger bubbles, and decreases if the difference between the curvatures of the bubble and the free surface is high. Our study is focussed on the bubble detachment and rise, and on the dynamics of the bouncing process prior to coalescence, rather than on the coalescence itself.

Pictures in Fig. 2 show a decrease in the bubble diameter as the gravity level is increased. This is due to the fact that the buoyancy force is higher at higher gravity levels, while the surface tension force is constant. The bubble detaches from the nozzle when buoyancy equals the surface tension force, hence the bubble is smaller at higher gravity levels.

Fig. 3 shows the position of the bubble center as a function of time for $g = 5g_0$. The time needed for the bubble to reach a steady rise is approximately 10 ms after the detachment. From this time the bubble rises with a constant terminal velocity until it collides with the free surface. After the collision, the bubble bounces twice before coalescence occurs.

A. Bubble detachment

While the syringe is pumping air, a bubble grows attached to the nozzle until it detaches when the forces directed downwards equal the forces directed upwards. In our experiments, the drag and inertial terms were negligible since air was injected at a very low flow rate (approximately 1 bubble every 5 seconds). A competition takes place between the surface tension force, F_σ , which keeps the bubble attached to the nozzle, and the buoyancy force F_b , which pushes the bubble upwards. The buoyancy force is proportional to the bubble volume, which increases linearly in time, while the surface tension force is constant. Bubble detaches when $F_b = F_\sigma$:

$$\Delta\rho g \frac{\pi d^3}{6} = \pi\sigma d_c, \quad (1)$$

where $\Delta\rho = \rho - \rho_a = 789 - 1.2 = 787.8 \text{ kg/m}^3$ is the density difference between the liquid and the air, g is the gravity level, d is the bubble equivalent diameter, $\sigma = 0.0224 \text{ N/m}$ is the surface tension, and $d_c = 0.15 \text{ mm}$ is the nozzle inner diameter. The bubble diameter as a function of the gravity level is given by

$$d = 2 \left(\frac{d_c}{4} \frac{3\sigma}{\Delta\rho g} \right)^{\frac{1}{3}}. \quad (2)$$

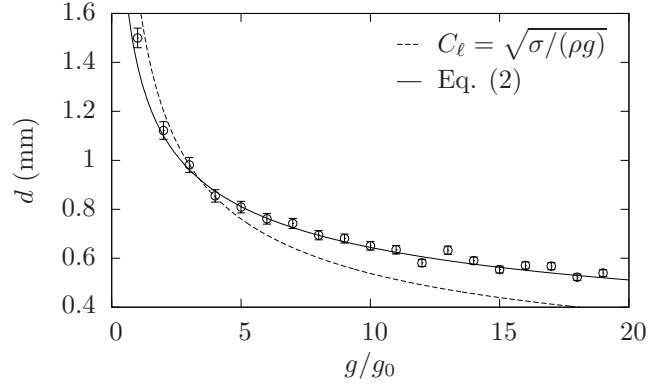


Figure 4. Bubble equivalent diameter as a function of the normalized gravity level. Dots: experimental data. Solid line: Eq. 2. Dashed line: capillary length C_ℓ .

It should be noted that Eq. 2 gives accurate results only if the needle used for bubble formation is completely wetted by a liquid and the bubble is formed at the inner diameter d_c .

In order to obtain experimentally the bubble equivalent diameter, we approximated the bubble shape as an axisymmetric ellipsoid with vertical diameter d_v and horizontal diameter d_h , where d_v and d_h can be measured from the images recorded in the steady rise. Since the bubble equivalent diameter is, by definition, the diameter of a spherical bubble containing the same volume as the ellipsoid ($\pi d^3/6 = \pi d_h^2 d_v/6$), it can be expressed as

$$d = (d_h^2 d_v)^{\frac{1}{3}}. \quad (3)$$

Fig. 4 shows the bubble diameter as a function of the normalized gravity level. The capillary length $C_\ell = \sqrt{\sigma/(\rho g)}$ is also plotted for comparison. A very good agreement between the experimental data and the prediction of Eq. 2 is obtained. This confirms that neglecting drag and inertial forces is a reasonable approximation for the current configuration.

B. Bubble rise

Once the bubble is detached from the nozzle, it starts to accelerate vertically until the drag force F_d equals the buoyancy force F_b . At this moment a steady state is attained and the bubble properties remain constant. The main parameters governing the bouncing/coalescence processes with the free surface are the bubble approach velocity (terminal velocity) and the shape of the bubble and the interface.

1) *Terminal velocity*: A relation between the terminal velocity and the gravity level can be obtained from the analysis of forces in the bubble rise. During the steady rise, the drag force counteracts buoyancy, $F_d = F_b$:

$$\frac{1}{2} \rho v_T^2 C_d \frac{\pi d^2}{4} = \Delta\rho g \frac{\pi d^3}{6}, \quad (4)$$

where v_T is the terminal velocity and C_d is the drag coefficient. Solving for the terminal velocity, we obtain:

$$v_T^2 = \frac{4\Delta\rho g d}{3\rho C_d}. \quad (5)$$

282 Multiplying both sides by $(\rho d/\mu)^2$, μ being the liquid viscos-
 283 ity, Eq. 5 can be written in terms of dimensionless numbers
 284 as

$$\text{Re}^2 = \frac{4}{3C_d} \sqrt{\frac{\text{Eo}^3}{M}}, \quad (6)$$

285 where $\text{Re} = \rho d v_T / \mu$ is the Reynolds number, $\text{Eo} = \Delta \rho g d^2 / \sigma$
 286 is the Eötvös number, and $M = \Delta \rho g \mu^4 / (\rho^2 \sigma^3)$ is the Morton
 287 number.

288 In order to obtain C_d as a function of the gravity level,
 289 we can use the approach by Mendelson (1967) and Tomiyama
 290 et al. (1998), in which the existence of the bubble is considered
 291 as a disturbance on the gas-liquid interface. Neglecting the
 292 viscosity of the liquid ($160 \leq \text{Re} \leq 237$ in our experiments),
 293 the disturbance propagates through the liquid in the form of a
 294 capillary-gravity wave with a phase velocity (Lamb, 1932)

$$v_p^2 = \frac{2\pi\sigma}{\rho\lambda} + \frac{\Delta\rho g\lambda}{2\pi\rho}, \quad (7)$$

295 where λ is the wavelength. Defining θ as the angle between
 296 the vertical direction and any point in the bubble interface, the
 297 velocity component normal to the interface v_N is a sinusoidal
 298 function of θ , with period 2π . As a result, one can regard the
 299 bubble as a source of a wave with wavelength $\lambda = \pi d$. This is
 300 valid even for non-spherical bubbles. Postulating that the phase
 301 velocity is equal to the terminal velocity in inviscid conditions
 302 (see Tomiyama et al. (1998) for a physical argumentation of
 303 this postulate), the wavelength relation introduced in Eq. 7
 304 yields to

$$v_T^2 = \frac{2\sigma}{\rho d} + \frac{\Delta\rho g d}{2\rho}. \quad (8)$$

305 The combination of Eq. 2 and Eq. 8, gives rise to an explicit
 306 relation between the terminal velocity and the gravity level.

307 Lehrer (1976) argued that during rise, the potential
 308 energy of the bubble is converted into kinetic energy followed
 309 by its dissipation in the wake, which results in a slightly
 310 different expression for the terminal velocity in the capillary-
 311 gravity approach (Lehrer, 1976, Kulkarni and Joshi, 2005):

$$v_T^2 = \frac{3\sigma}{\rho d} + \frac{\Delta\rho g d}{2\rho}. \quad (9)$$

312 Eq. 8 can be written in terms of dimensionless numbers as

$$\text{Re}^2 = \frac{1}{2} \sqrt{\frac{\text{Eo}}{M}} (\text{Eo} + 4). \quad (10)$$

313 Comparing Eq. 10 with Eq. 6 yields to

$$C_d = \frac{8}{3} \frac{\text{Eo}}{\text{Eo} + 4}. \quad (11)$$

314 Similarly, Eq. 9 can be rewritten in terms of dimensionless
 315 numbers as

$$\text{Re}^2 = \frac{1}{2} \sqrt{\frac{\text{Eo}}{M}} (\text{Eo} + 6), \quad (12)$$

316 which, combining with Eq. 6, gives rise to

$$C_d = \frac{8}{3} \frac{\text{Eo}}{\text{Eo} + 6}. \quad (13)$$

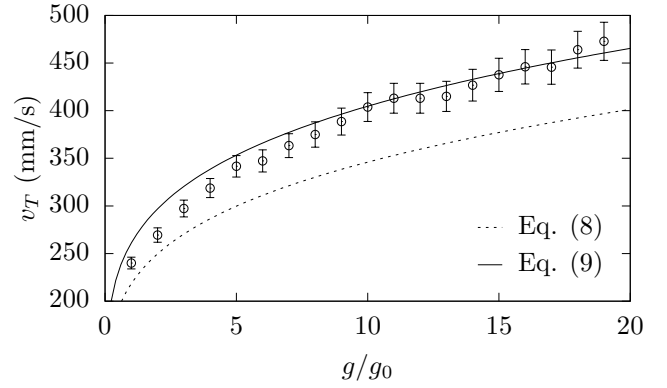


Figure 5. Bubble terminal velocity as a function of normalized the gravity level. Dots: experimental data. Dashed line: Eq. 8. Solid line: Eq. 9.

317 Eqs. 11 and 13 contain the required relation between the
 318 drag coefficient and the gravity level.

319 In order to experimentally obtain the bubble terminal veloc-
 320 ity, we have measured the time interval t needed for a bubble
 321 to rise a given number of pixels z , in the steady rise region.

322 Fig. 5 shows the bubble terminal velocity as a function of
 323 the normalized gravity level. The terminal velocity is found to
 324 increase as the gravity level is increased. This is the expected
 325 behavior for a fixed bubble size, but we must keep in mind
 326 that in our experiments the size of the bubble decreases as the
 327 gravity level is increased. As a consequence, the behavior of
 328 the terminal velocity as a function of gravity for bubble size
 329 determined by natural detachment is a priori unknown.

330 The experimental measurements are slightly above the theo-
 331 retical prediction of Eq. 8. Lehrer's (Lehrer, 1976) modifica-
 332 tion of Eq. 8 by energy balance arguments, resulting in Eq. 9,
 333 becomes a better prediction of the obtained data. Experimental
 334 results show a good agreement with Eq. 9 for $g > 10g_0$.
 335 However, for lower gravity values there is a deviation between
 336 the experimental data and the theoretical prediction of Eq. 9.
 337 This could be due to the fact that the conversion from potential
 338 to kinetic energy in Lehrer's argumentation is somehow more
 339 efficient at higher bubble terminal velocities. Therefore, the
 340 prediction for $g < 10g_0$ could be a combination between
 341 Eqs. 8 and 9, which has not been developed theoretically up
 342 to date.

343 Solving for the drag coefficient in Eq. 5, one can obtain its
 344 experimental values by measuring the bubble diameter and the
 345 bubble terminal velocity.

346 Fig. 6 shows the drag coefficient as a function of the Eötvös
 347 number. It can be noted that Eq. 13 is a better fit to the
 348 experimental data than Eq. 11. This behavior can be expected
 349 from Fig. 5, since Eq. 9 (and correspondingly, Eq. 13), shows
 350 a better prediction for the terminal velocity.

351 2) *Bubble shape*: The bubble shape in the steady rise region
 352 is determined from the competition between inertial forces
 353 and surface tension forces. Hence, the Weber number (defined
 354 as $\text{We} = \rho d v_T^2 / \sigma$) becomes an appropriate dimensionless
 355 number to characterize the bubble shape. The bubble aspect
 356 ratio $\epsilon = d_h / d_v$ is plotted as a function of gravity in Fig. 7.
 357 The effects of gravity on the bubble aspect ratio do not reflect

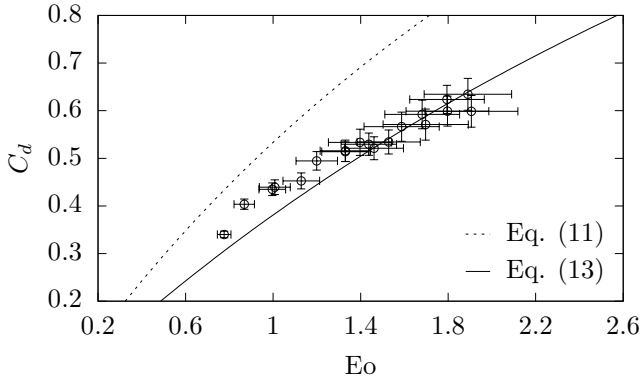


Figure 6. Drag coefficient as a function of the Eötvös number. Dots: experimental data. Dashed line: Eq. 11. Solid line: Eq. 13.

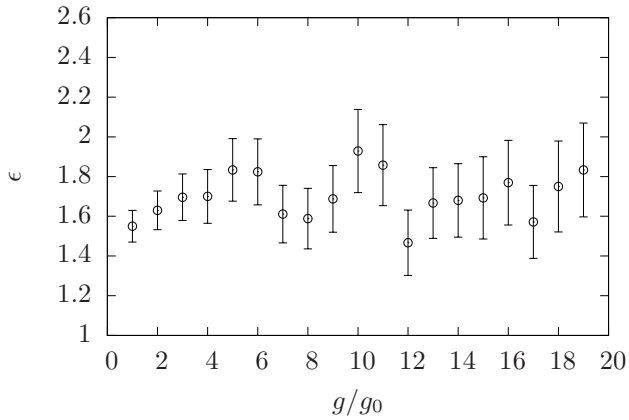


Figure 7. Bubble aspect ratio as a function of the normalized gravity level.

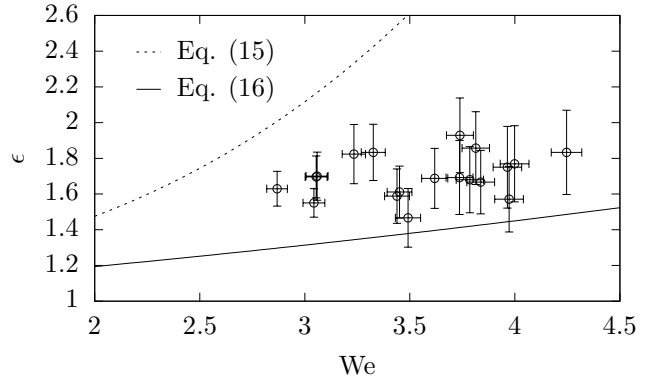


Figure 8. Bubble aspect ratio as a function of the Weber number. Dots: experimental data. Dashed line: Eq. 15. Solid line: Eq. 16.

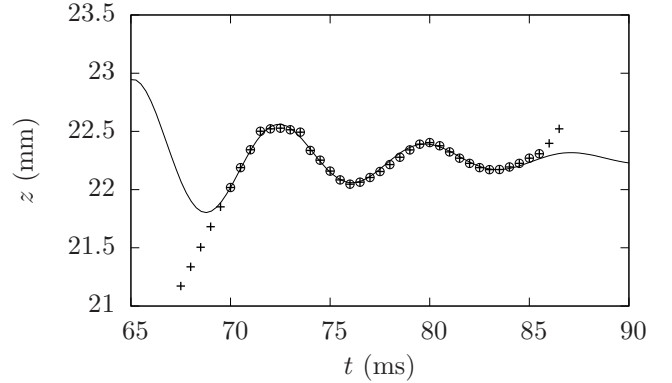


Figure 9. Bubble center position as a function of time. Solid line corresponds to a fit by Eq. 20. Circled-crossed points are used for the fit, the rest are excluded.

any clear tendency. One must take into account that the points plotted in Fig. 7 correspond to bubbles of decreasing size as the normalized gravity level increases. In case the bubbles had the same size in all gravity levels, we would have expected the aspect ratio to increase with g/g_0 (flatter bubbles at larger gravity levels).

By employing a potential flow solution over an ellipsoid, an implicit relation between the aspect ratio and the Weber number for clean bubbles (slip condition at the interface) can be obtained (Moore, 1965):

$$We = 4\epsilon^{-4/3} (\epsilon^3 + \epsilon - 2) \frac{(\sqrt{\epsilon^2 - 1} - \epsilon^2 \sec^{-1} \epsilon)^2}{(\epsilon^2 - 1)^3}, \quad (14)$$

which, for moderate deformations ($\epsilon < 2$), can be approximated as (Loth, 2008)

$$\epsilon \approx 1 + \frac{9}{64} We - 0.0089 We^2 + 0.0287 We^3. \quad (15)$$

The following expression was obtained for contaminated bubbles (no-slip condition) Loth (2008):

$$\epsilon = [1 - 0.75 \tanh(0.11 We)]^{-1}. \quad (16)$$

Dots in Fig. 8 correspond to the measured aspect ratio as a function of the Weber number. The experimental data show a poor agreement with the prediction of Eq. 15 (dashed

line) and Eq. 16 (solid line). This disagreement could be explained in a similar way as in Fig. 7. Eqs. 15 and 16 are only applicable to bubbles of the same size and different aspect ratio. Furthermore, the discrepancies could be caused by the unknown hydrodynamic boundary conditions at the bubble surface. As reported recently, the bubble surface in the considered system can be partially or even completely slip (Basarová et al., 2018).

From the examination of the above results, we are not able to make any clear statement about the effects of the gravity level on the bubble shape.

C. Bubble bouncing

Fig. 9 shows the position of the bubble center as a function of time for $g = 5g_0$ during the bouncing process. The time interval between the first impact and the final coalescence is approximately 15 ms.

When a bubble bounces upon impact with a free surface, both the bubble and the free surface become deformed. Sato et al. (2011) modelled this process by means of a mass-spring approximation consisting in two springs connected in series. One spring with stiffness K_1 accounts for the bubble deformation, and the other spring with stiffness K_2 corresponds to the free surface deformation. Two limiting cases can be considered.

On the one hand, the limit $K_1 \ll K_2$ corresponds to a deformable bubble colliding with a solid wall. In this case, the frequency of the bubble bouncing can be approximated by the frequency of the second mode of an oscillating bubble in an unbounded fluid (Lamb, 1932):

$$\omega = 4\sqrt{\frac{6\sigma}{\rho d^3}}. \quad (17)$$

This frequency of bubble bouncing coincides with the frequency of a drop bouncing on a wall in a liquid (Legendre et al., 2005).

On the other hand, the limit $K_1 \gg K_2$ corresponds to a bubble with an arbitrary shape colliding with a deformable free surface, which acts as an elastic membrane.

The model used by Sato et al. (2011) does not contain any dissipative terms. However, the process of bubble bouncing with a solid wall or a free surface is a highly dissipative process (Tsao and Koch, 1997). Therefore, the process of bubble bouncing with a free surface can be approximated as a collision between a bubble with an arbitrary shape and an elastic membrane (which corresponds to the second limiting case), with a dissipative term. Our approximation is then related to a forced damped oscillator model:

$$m \frac{d^2 z}{dt^2} + c \frac{dz}{dt} + Kz = F_b, \quad (18)$$

where m is the added mass of the bubble, c is a damping coefficient (proportional to the fluid viscosity), K is the stiffness of the free surface (proportional to the surface tension), and F_b is the buoyancy force. Since the added mass and the buoyancy force are proportional to the bubble volume, we can rewrite Eq. 18 in the form

$$\ddot{z} + 2\zeta\omega_0\dot{z} + \omega_0^2 z = \chi, \quad (19)$$

where χ is a constant acceleration due to buoyancy, ζ is a dissipative term, and ω_0 is the natural frequency of the harmonic oscillator. The solution of Eq. 19 in the underdamped case is

$$z(t) = z_0 + h_0 \exp(-\omega_0\zeta t) \sin(\omega t + \varphi), \quad (20)$$

where $\omega = \omega_0\sqrt{1-\zeta^2}$ is the frequency of the bubble bouncing and $h_0 \exp(-\omega_0\zeta t)$ is the amplitude. Eq. 20 will be used to obtain the experimental values of ω and h_n (where h_n is the amplitude of the n^{th} bounce), with z_0 , h_0 , $\omega_0\zeta$, ω and φ as fitting parameters.

Eq. 20 will be used to obtain the experimental values of bouncing frequency (ω) and amplitude h_n (where h_n is the amplitude of the n^{th} bounce), with z_0 , h_0 , $\omega_0\zeta$, ω and φ as fitting parameters.

1) *Frequency of bouncing:* In order to obtain a theoretical prediction for the frequency of bouncing, we assume that the free surface acts as an elastic membrane driven by capillary and gravity forces. Taking into account the effects of viscosity, the general dispersion relation for a capillary-gravity driven wave can be written as a complex equation (Lamb, 1932, Behroozi et al., 2011):

$$\left(i\omega + \frac{2\mu}{\rho}k^2\right)^2 + gk + \frac{\sigma}{\rho}k^3 = \frac{4\mu^2}{\rho^2}k^3\sqrt{k^2 + i\frac{\rho}{\mu}\omega}. \quad (21)$$

where k is the wavenumber. In the capillary wave regime ($\rho\omega \gg \mu k^2$), Eq. 21 can be approximated as Behroozi et al. (2011)

$$\omega^2 = gk + \left(\frac{\sigma}{\rho} + \frac{4\mu^2}{\rho^2}k - \sqrt{\frac{8\mu^3}{\rho^3}\omega}\right)k^3, \quad (22)$$

which is an implicit relation between the frequency and the wavenumber $k = 2\pi/\lambda$. Using the wavelength relation $\lambda = \pi d$ (Section III-B) in Eq. 22, an implicit relation between the frequency and the bubble diameter can be written as

$$\omega^2 = \frac{2g}{d} + \frac{8\sigma}{\rho d^3} + \frac{64\mu^2}{\rho^2 d^3} - \frac{16}{d^3}\sqrt{\frac{2\mu^3}{\rho^3}\omega}. \quad (23)$$

Introducing Eq. 2 into Eq. 23, we obtain an implicit relation between the bouncing frequency and the gravity level. The numerical solution of this relation is plotted in Fig. 10.

An explicit relation between ω and g can be obtained in the inviscid case. Neglecting the viscosity, the dispersion relation in Eq. 22 can be written as

$$\omega^2 = gk + \frac{\sigma}{\rho}k^3. \quad (24)$$

Substituting the wavelength relation into Eq. 24 yields to

$$\omega = \sqrt{\frac{2g}{d} + \frac{8\sigma}{\rho d^3}}. \quad (25)$$

Eq. 25 together with Eq. 2 results in an explicit relation between the frequency of bouncing and the gravity level.

Note that from Eq. 24, the definition of the phase velocity $v_p = \omega/k$, and the relation $k = 2\pi/\lambda = 2/d$, we recover the result for the terminal velocity obtained by Mendelson (1967):

$$v_T^2 = \frac{gd}{2} + \frac{2\sigma}{\rho d}, \quad (26)$$

which is very similar to Eq. 8, except for the factor $\Delta\rho/\rho$ multiplying the gravitational term.

If we consider the terminal velocity obtained by Lehrer Lehrer (1976) (Eq. 9), the frequency of bouncing becomes

$$\omega = \sqrt{\frac{2\Delta\rho g}{\rho d} + \frac{12\sigma}{\rho d^3}}. \quad (27)$$

Extending this result to the viscous case, we obtain the implicit dispersion relation

$$\omega^2 = gk + \left(\frac{3\sigma}{2\rho} + \frac{4\mu^2}{\rho^2}k - \sqrt{\frac{8\mu^3}{\rho^3}\omega}\right)k^3, \quad (28)$$

which has been solved numerically, together with the relation $k = 2\pi/\lambda = 2/d$ and Eq. 2. The result is also plotted in Fig. 10.

The experiments analyzed here are in a region of low Reynolds number ($160 \leq \text{Re} \leq 237$), hence, in the inviscid regime. This is clearly manifested in Fig. 10, in which the plot of Eq. 23 and Eq. 25 obtained from our data overlap, as happens with the plot of Eq. 27 and Eq. 28.

Dots in Fig. 10 show the experimental frequency of bouncing as a function of gravity level. The following procedure has been followed to obtain the data: (i) For $g \leq 7g_0$, experimental

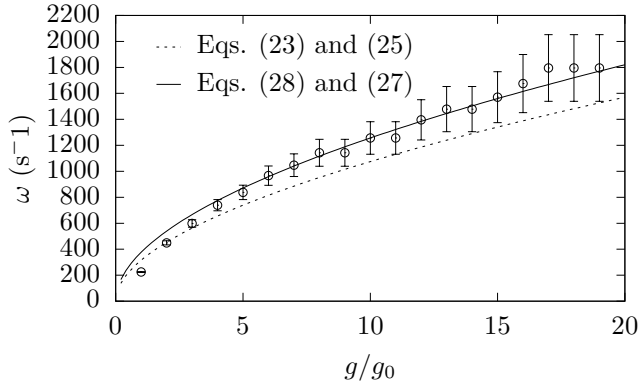


Figure 10. Frequency of bouncing as a function of the gravity level. Dots: experimental data. Dashed line: Eq. 23 and Eq. 25. Solid line: Eq. 28 and Eq. 27.

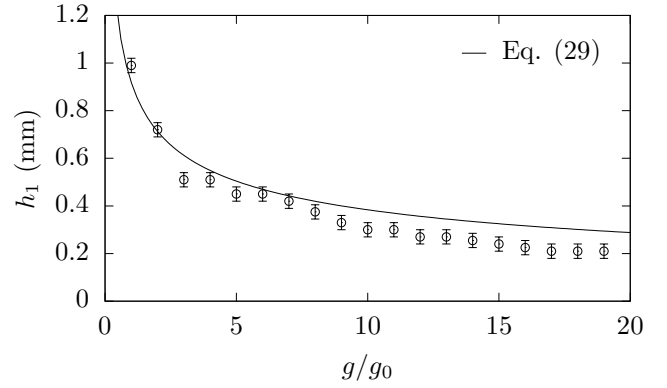


Figure 11. Amplitude of the first bounce as a function of the gravity level. Dots: experimental data. Solid line: Eq. 29.

481 data have been fitted to Eq. 20, with z_0 , h_0 , $\omega_0\zeta$, ω and φ as
 482 fitting parameters. The data used for the fit are the circled-
 483 crossed points in Fig. 9. The rest of the points have been
 484 excluded to the fit since they are in the steady rise region
 485 or in the coalescence region. (ii) For $g > 8g_0$, there are not
 486 enough data points to make a reliable fit. Therefore, ω has
 487 been obtained from the time t that a bubble needs to complete
 488 a period, $\omega = 2\pi/t$. The experimental frequency of buoyancy
 489 fits better in Eqs. 27 and 28 than in Eqs. 23 and 25. This
 490 confirms, as was obtained in Fig. 5, that the terminal velocity
 491 in Eq. 9 predicts better the experimental behavior than the
 492 prediction of Eq. 8, for $g > 10g_0$.

493 In summary, viscosity does not affect the frequency of
 494 bouncing. Moreover, the bubble trajectory can be approxi-
 495 mated by an underdamped oscillator, although damping is
 496 not caused by viscosity. Damping could be caused by energy
 497 transfer from the bubble to the fluid in form of vortex gen-
 498 eration and surface waves. Particle Image Velocimetry (PIV)
 499 measurements would be of interest to support this hypothesis.

500 2) *Amplitude of bouncing*: The amplitude damping in our
 501 model is characterized by the coefficient $\omega_0\zeta$ (Eq. 20). Experi-
 502 mental data are fitted to the model only for $g \leq 7g_0$ due to the
 503 lack of sufficient data for $g > 8g_0$. The damping coefficient is
 504 one of the fitting parameters. No conclusive effect of gravity
 505 on the damping coefficient has been found for the considered
 506 range of gravity level. Presumably, the damping coefficient
 507 only depends on the fluid properties (unless some kind of
 508 energy transfer to the fluid occurs), hence it is independent
 509 of the gravity level.

510 After the first bounce, the bubble velocity becomes negative
 511 until the bubble center reaches its lowest position before
 512 rising again. In this second rise phase, the bubble reaches an
 513 approach velocity lower than the terminal velocity, $v_a < v_T$.
 514 The amplitude of the first bounce, h_1 , is given by the position
 515 of the bubble center at its lowest point after the first bounce.
 516 [Suñol and González-Cinca \(2010\)](#), measured in normal gravity
 517 conditions the amplitude of the first bounce as a function of the
 518 bubble equivalent diameter in ethanol, and found two distinct
 519 behaviors: (i) For $d < 0.47$ mm, the bubble coalesces directly
 520 with no bouncing. (ii) For $d > 0.47$ mm, a linear relation

521 between the amplitude of the first bounce and the bubble
 522 diameter was derived:

$$h_1 = (0.72 \pm 0.03)d - (0.08 \pm 0.04). \quad (29)$$

523 Extending this result to hypergravity conditions, we can
 524 introduce Eq. 2 in the above relation, to predict the behavior
 525 of h_1 as a function of the gravity level. Fig.11 shows the
 526 amplitude of the first bounce as a function of the gravity level.
 527 It is important to note that for Figs 10 and 11, each data point
 528 refers to a different bubble size, thus graphs do not actually
 529 represent the effect of gravity on the frequency and amplitude
 530 of bouncing for a fixed bubble size. The measured values of h_1
 531 are slightly lower than those given by the prediction, specially
 532 for high gravity levels. An increase of the energy dissipation
 533 at high gravity levels could be the cause of this discrepancy.
 534 However, there are no available models to quantify such
 535 dissipation.

536 IV. CONCLUSIONS AND FUTURE CONSIDERATIONS

537 We have studied the effects of the gravity level on the bubble
 538 detachment from a nozzle, steady rise, and bouncing upon
 539 impact with a free surface.

540 The bubble detachment size has been found to decrease as
 541 the gravity level increases, in very good agreement with the
 542 prediction based on the competition between buoyancy and
 543 surface tension forces.

544 The terminal velocity in the bubble rise increases with
 545 gravity, although the bubble size is smaller at higher gravity
 546 levels. A good agreement between the experimental results and
 547 the prediction by wave analogy has been obtained.

548 No clear effects of the gravity level on the bubble shape
 549 have been obtained.

550 Concerning the dynamics of bubble bouncing, we have
 551 modelled the system as a damped oscillator with the free
 552 surface acting as an elastic membrane. The experimental
 553 determination of the frequency of bouncing as a function of
 554 the gravity level showed a very good agreement with the
 555 theoretical prediction. The amplitude of the first bounce has
 556 been found to decrease as the gravity level increases. However,
 557 the bubble size varies for each gravity level, hence the effects

of gravity on the frequency and amplitude of bouncing for a fixed bubble size remains unknown. Finally, we have observed that the motion of the bubble can be approximated by that of an underdamped oscillator even if viscosity is negligible. This reflects that the viscosity is not the main responsible for damping.

It would be of interest to consider bubbles of different size at a fixed gravity level in future experiments. This would allow to test the existing theoretical models, with a changing gravity level, in terms of dimensionless numbers. The study of liquids with different properties can also be of interest. In addition, a study of the restitution coefficient and the drainage time, would help to predict the number of bounces. The restitution coefficient gives an idea of the amount of kinetic energy lost in each bounce, so we could be able to predict the approach velocity, and hence the contact time, on the next bounce.

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