HVAC Transmission System for Offshore Wind Power Plants Including Mid-cable Reactive Power Compensation: Optimal design and comparison to VSC-HVDC transmission

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Abstract—The design distance of offshore wind power plants connected through HVAC transmission systems might be extended due to the introduction of mid-cable reactors for reactive power compensation purposes and the latest developments of AC cables for higher voltages. Therefore, the applicability limits between HVAC and HVDC systems must be revised. This paper analyzes the contribution that mid-cable reactive power compensation has on increasing the distance limits of HVAC transmission systems. A methodology is developed to determine an optimal design of such transmission systems. In this methodology, cost of power losses and reactors are minimized for multiple wind speed conditions. As a result, the optimal HVAC voltage level and the optimal number of reactors and their location are determined for different OWPP rated powers and distances. Also, the final transmission system is selected between HVAC and HVDC equivalent configurations based on total costs.

Index Terms—HVAC, HVDC, Offshore Wind Power Plant, Optimization, Reactive Power Compensation, Transmission System

I. INTRODUCTION

OFFSHORE wind power generation is experiencing a significant expansion during the recent years, especially in Europe [1]. A number of transmission system configurations have been proposed to integrate large Offshore Wind Power Plants (OWPPs) to shore based on efficient, reliable and cost-effective designs. Configurations based on High Voltage AC (HVAC) and High Voltage DC (HVDC) are currently considered for offshore transmission systems. HVDC configurations are traditionally used for long distances, since reactive power is not generated and costs of power losses can be reduced compared to HVAC options. However, HVAC configurations are currently being considered for longer distances, including mid-cable reactive power compensation and recently developed AC cables of higher voltages. In particular, Hornsea One and Two are current projects that include such mid-cable reactive power compensation [2]. Therefore, the selection between HVDC and HVAC configurations for long distances should be revised.

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The installation of mid-cable reactors represents a potential solution to improve reactive power compensation [3], [4]. The distribution of reactive power along a non-loaded cable is shown in Fig. ??, where different locations and numbers of reactors are presented [3]. It is clear that if reactors are installed in the middle or equally distributed at both ends of the cables the maximum value of reactive power, *i.e.* the loading of the cable, is reduced, as seen in Fig. ??(b) and Fig. ??(c). Also, combining reactors at both ends of the cables with a mid-cable reactor further decreases the reactive power down to 75% of the maximum value compared to installing a single reactor, as shown in Fig. ??(a) and Fig. ??(d) [5]. Then, even though the cost of installation of an offshore platform for a mid-cable reactor is high, the potential optimization of reactive power flows and the reduction of power losses can be beneficial to reduce the operation costs.

Few studies are focused on the analysis of reactive power compensation using reactors for long distance HVAC-connected OWPPs. In [6], optimization of reactive power compensation is presented by minimizing cost of power losses and reactors and considering several rated powers, voltages and transmission distances. However, only two reactors located at both ends of the cable are analyzed. Also, the improvement of the active power transfer capability over long distances including mid-cable reactors and comparison with HVDC configurations is presented in [7]. However, the optimal sizing and location of compensation reactors is not addressed.

This paper presents an optimal design for the transmission system of HVAC-connected OWPPs, where the contribution of mid-cable reactive power compensation is studied in detail. The analysis and optimization of an HVAC offshore transmission system considering different locations and number of reactors has not been fully investigated in the literature, especially when mid-cable reactors included. Therefore, the contributions of this paper can be summarized as follows:

- A methodology is presented to select the optimal configuration for an HVAC offshore transmission system. This includes a minimization of reactor and power losses cost based on multiple wind speed conditions. In addition, this methodology compares the optimal HVAC configuration with an equivalent HVDC option.
- Selection between HVAC and HVDC configurations and selection of the number of reactors in HVAC options is defined for a range of distances and OWPP rated powers.

Initially, a power flow model and a cost model are defined for HVAC and HVDC transmission systems. Then, the design methodology is developed based on a set of voltage levels, reactor locations and number of reactors. As a result, this methodology is applied for several OWPPs rated powers and distances to shore and two specific case studies are presented in detail in order to understand the influence of the mid-cable reactor on the break-even distance.

II. DESCRIPTION OF TRANSMISSION CONFIGURATIONS

The HVAC and HVDC transmission systems considered in the paper are described in this Section and shown in Fig. ??.

A. HVAC transmission system

The configuration of an HVAC transmission system for offshore wind power plants (OWPPs) is shown in Fig. ??(a) and Fig. ??(a). This configuration is based on two substations interconnected with cross-linked polyethylene (XLPE) cables. The substations include power transformers, gas or air insulated switchgears and reactive power compensation equipment. Offshore transformers are used to step up the voltage from the collector grid of an OWPP, which operates at medium voltage (33 or 66 kV) to the transmission level (110, 150 and 220 kV). Also, onshore transformers are used to step up the voltage to the onshore grid operating level (220-400 kV). The preferred transformer topology is based on two transformers in parallel, which are rated at 60 % of the OWPP nominal power in order to increase power export availability [8]. In this case, three-core XLPE cables are considered for the transmission system, which has been recently used in projects Hornsea One and Two [2] due to reduced power losses and less installation costs [9]. A number of cable circuits are connected in parallel, which depends on the rated power of OWPP and the transmission voltage. Also, reactors are used along the cables in order to compensate reactive power, which leads to a reduction of power losses and provides further voltage control. In particular, a maximum of three reactors are considered, where all possible locations and combinations are specified in Fig. ??.

B. HVDC transmission system

In this paper, a Voltage Source Converter HVDC (VSC-HVDC) topology based on symmetrical monopolar configuration is considered as shown in Fig. ??(b) and Fig. ??(b). This configuration consists of two VSCs interconnected with transmission DC cables, which are rated up to 525 kV [10]. The converters are connected to each AC side through transformers, which are the same as in Section II-A.

III. MODELING OF TRANSMISSION CONFIGURATIONS

Transmission systems are modeled for steady-state analysis in order to calculate power losses. Offshore wind power plants are represented considering the operation at different wind speeds. Also, the cost modeling of all components is described in this Section based on expressions and data from the literature.

A. HVAC transmission system

The model presented in this Section is used to calculate total costs of the HVAC transmission system as well as to comply with the voltage and current operational limits. As a result, detailed models of the components, a power flow formulation and cost functions are presented in the following subsections:

1) *Cable model*: Long transmission cables are modeled using a formulation based on hyperbolic functions [11], which defines the following expressions:

$$\begin{bmatrix} \underline{V}_s \\ \underline{I}_s \end{bmatrix} = \begin{bmatrix} \cosh(\theta) & \underline{Z}_c \sinh(\theta) \\ \sinh(\theta)/\underline{Z}_c & \cosh(\theta) \end{bmatrix} \begin{bmatrix} \underline{V}_r \\ \underline{I}_r \end{bmatrix} \quad (1)$$

$$\underline{Z}_c = \sqrt{\frac{\underline{Z}}{\underline{Y}}}; \quad \theta = l\sqrt{\underline{Z}\underline{Y}} \quad (2)$$

$$\underline{Z} = R + j\omega L; \quad \underline{Y} = j\omega \frac{C}{2} \quad (3)$$

where $\underline{V}_s$ and $\underline{I}_s$ are voltages and currents at the sending end terminal, $\underline{V}_r$ and $\underline{I}_r$ are voltages and currents at the receiving end terminal, $\underline{Z}_c$ is the characteristic impedance, and θ is the characteristic angle. The cable parameters are defined as per unit length in (3), where R is the resistance, L is the inductance, C is the capacitance and l is the cable length.

As a result, cables are represented with an equivalent π section, shown in Fig. ??(a), where $\underline{Z}_\pi$ and $\underline{Y}_\pi$ are defined as:

$$\begin{aligned} \underline{Z}_\pi &= \underline{Z}_c \sinh(\theta) = \underline{Z}l \frac{\sinh(\theta)}{\theta} \\ \underline{Y}_\pi &= \frac{\tanh(\theta/2)}{\underline{Z}_c} = \frac{\underline{Y}l \tanh(\theta/2)}{\theta/2} \end{aligned} \quad (4)$$

It should be noted that this formulation provides higher accuracy than equivalent π section directly obtained from cable parameters [11].

2) *Transformer model*: The transformer is represented as an equivalent circuit referred to the transmission system side, as shown in Fig. ??(b). The equivalent impedance $\underline{Z}_{tr}$ and admittance $\underline{Y}_{tr}$ of the transformer are expressed as:

$$\underline{Z}_{tr} = R_{tr} + jX_{tr}; \quad \underline{Y}_{tr} = G_{tr} - jB_{tr} \quad (5)$$

$$R_{tr} = P_{Cu}^{loss} \left(\frac{U_{r-tr}}{S_{r-tr}} \right)^2; \quad X_{tr} = \sqrt{\left(u_k \frac{U_{r-tr}^2}{S_{r-tr}} \right)^2 - R_{tr}^2} \quad (6)$$

$$G_{tr} = \frac{P_{Fe}^{loss}}{U_{r-tr}^2}; \quad B_{tr} = i_o \frac{S_{r-tr}}{U_{r-tr}^2} \quad (7)$$

where P_{Cu}^{loss} are the copper losses, U_{r-tr} is the rated voltage of the transformer at the transmission system side, S_{r-tr} is the rated power of the transformer, P_{Fe}^{loss} are the iron losses, u_k is the short circuit voltage and i_o is the open circuit current.

3) *Shunt reactor model*: Reactors are modeled with admittance $\underline{Y}_l = 1/(j\omega L_r)$ where L_r is the equivalent inductance of the reactor.

4) *Main grid*: The grid is modeled with a Thévenin equivalent, where $\underline{U}_g$ is the Thévenin voltage and $\underline{Z}_g = R_g + jX_g$ is the Thévenin impedance. This grid equivalent is calculated from the short circuit ratio (SCR) and X_g/R_g ratio.

5) *Power flow formulation*: The power flow model of the HVAC transmission system is defined in per-unit system, as shown in Fig. ???. In case of a multiple number of cable circuits and transformers, equivalent impedances and admittances represent the aggregation of such components in parallel.

Then, the power flow equations in per-unit system are:

$$\begin{aligned}
\underline{u}_1 \underline{i}_1^* &= p_{owf} + j q_{owf} \\
\underline{u}_1 &= \underline{u}_2 + \underline{z}_{tr} \underline{i}_2 \\
\underline{i}_1 &= (\underline{y}_{tr} + \underline{y}_l) \underline{u}_1 + \underline{i}_2 \\
\underline{u}_2 &= \underline{u}_3 + \underline{z}_{\pi 1} \underline{i}_3 \\
\underline{i}_2 &= (\underline{y}_{\pi 1} + \underline{y}_l) \underline{u}_2 + \underline{i}_3 \\
\underline{i}_3 &= (\underline{y}_{\pi 1} + \underline{y}_l + \underline{y}_{\pi 2}) \underline{u}_3 + \underline{i}_4 \\
\underline{u}_3 &= \underline{u}_4 + \underline{z}_{\pi 2} \underline{i}_4 \\
\underline{i}_4 &= (\underline{y}_{\pi 2} + \underline{y}_l) \underline{u}_4 + \underline{i}_5 \\
\underline{u}_4 &= \underline{u}_5 + \underline{z}_{tr} \underline{i}_5 \\
\underline{i}_5 &= (\underline{y}_{tr} + \underline{y}_l) \underline{u}_5 + \underline{i}_g \\
\underline{u}_5 &= \underline{u}_g + \underline{z}_g \underline{i}_g
\end{aligned} \tag{8}$$

The power losses of the HVAC transmission system represent ohmic losses coming from cables and transformers. As a result, the power losses in MW can be expressed as:

$$P_{loss-AC} = (p_{owf} - p_g) \cdot S_b = (p_{owf} - \text{Re}\{\underline{u}_5 \underline{i}_g^*\}) \cdot S_b \tag{9}$$

where p_{owf} is the active power coming from the OWPP, p_g is the active power delivered to the grid and S_b is the base value of the power.

6) *Cost modeling*: Cost functions are presented for AC cables, switchgears, transformers, reactors, AC substation platform and power losses.

The cost of AC cables is expressed as [12]:

$$C_{cb-AC} = \frac{(A + B e^{C S_{r-cb}} + D) \cdot (9n + 1)}{10E} \cdot l \tag{10}$$

where A, B, C, D and E are coefficients defined in Table I, which are dependent on the cable voltage [13], [14], S_{r-cb} is the rated apparent power of the cable in MVA and l is the cable length in km.

The cost of switchgears is calculated as [15]:

$$C_{gis-AC} = 0.0117 \cdot U_{AC-N} + 0.0231 \tag{11}$$

where U_{AC-N} is the nominal transmission voltage in kV.

The cost of transformers is obtained as [16]:

$$C_{tr} = 0.0427 \cdot S_{r-tr}^{0.7513} \tag{12}$$

where S_{r-tr} is the rated power of the transformer in MVA.

The cost of reactors is derived from [6], [15], [17] as:

$$C_{react} = K \cdot Q_l + P \tag{13}$$

where K and P are the constant values defined in Table II, which are dependent on the location of reactor, $Q_l = Y_l \cdot U_{AC-N}^2$ is the reactive power compensated by the reactors.

The substation platform cost is calculated as [14], [18]:

$$C_{ss-AC} = 2.534 + 0.0887 \cdot P_{owf-N} \tag{14}$$

where P_{owf-N} is the nominal power of the offshore wind power plant in MW.

The operation cost of AC power losses is expressed as:

$$C_{loss-AC} = 8760 \cdot t_{owf} \cdot C_E \cdot P_{loss-AC} \tag{15}$$

where t_{owf} is the life time of the wind power plant in years and C_E is the cost of energy in €/MWh. The expected life time is to be at least 25 years with the possibility to extend by up to an additional 25 years [19].

TABLE I
COEFFICIENTS FOR XLPE SUBMARINE AC CABLES [13], [14]

	30 kV	70 kV	150 kV	220 kV	400 kV
A	0.411	0.688	1.971	3.181	5.8038
B	0.596	0.625	0.209	0.11	0.044525
C	0.041	0.0205	0.0166	0.0116	0.0072
D			$17 \cdot 10^4$		
E			8.98		

TABLE II
COEFFICIENTS FOR SHUNT REACTORS

Location	K	P
Onshore	0.01049	0.8312
Offshore	0.01576	1.244
Middle	0.01576	12.44

B. HVDC transmission system

In this case, the HVDC system is modeled only to calculate total costs. Therefore, a simplified power flow formulation and cost functions are presented in the following subsections:

1) *Power flow formulation*: The HVDC system is modeled with a single-line diagram which includes converter stations and DC cables, as shown in Fig. ???. The converter stations represent the VSCs and associated transformers, while the DC cables are modeled as equivalent resistances for the positive and negative poles. Then, power losses of the HVDC transmission system in MW can be expressed as:

$$P_{loss-DC} = (p_{owf} - p_g) \cdot S_b = (p_{loss-VSC} + p_{loss-cb}) \cdot S_b \tag{16}$$

where $p_{loss-VSC}$ are the converter station power losses and $p_{loss-cb}$ the cable power losses, which are approximated as:

$$p_{loss-VSC} \approx 2 p_{owf} 0.01 \tag{17}$$

$$p_{loss-cb} \approx 2 r_{dc} i_{dc}^2 = 2 r_{dc} \left(\frac{p_{owf}}{u_{DC-N}} \right)^2 \tag{18}$$

where u_{DC-N} is the nominal DC voltage. It is observed that the VSC converter station power losses are assumed to be 1% of the generated power.

2) *Cost modeling*: Cost functions are presented for DC cables, converter stations, DC substation platform and power losses.

The cost of DC cables is presented in [12] as:

$$C_{cb-DC} = \frac{(A + B P_{r-cb} + D) \cdot (9n + 1)}{10E} \cdot l \tag{19}$$

where A, B, D and E are coefficients defined in Table III which are dependent on the cable voltage, P_{r-cb} is the rated power of the cable in MW and l is the cable length in km.

The offshore and onshore converter stations are defined in the following equations [12]:

$$C_{conv-off} = 42 + 27 \cdot \frac{P_{conv-r}}{300} \quad (20)$$

$$C_{conv-on} = 18 + 27 \cdot \frac{P_{conv-r}}{300} \quad (21)$$

where P_{conv-r} is the rated power of the converter.

The cost of a DC substation platform is in average 250% higher than an equivalent AC option due to additional elements [15], [20], [7].

The operation cost of DC power losses is expressed as in (15), but considering $P_{loss-DC}$.

TABLE III
COEFFICIENTS FOR DC CABLES [13], [14]

	±80 kV	±150 kV	±320 kV	±525 kV
A	$-0.25179 \cdot 10^6$	$-0.1 \cdot 10^6$	$0.286 \cdot 10^6$	$0.7454 \cdot 10^6$
B	$0.03198 \cdot 10^6$	$0.0164 \cdot 10^6$	$0.00969 \cdot 10^6$	$0.0061 \cdot 10^6$
D		$22 \cdot 10^6$		
E		8.98		

C. Offshore wind power plant

OWPP is modeled considering different wind speeds, which are characterized following a Weibull distribution. Therefore, the probability of different wind speeds is expressed as [21]:

$$p_w = \frac{k}{c} \left(\frac{v}{c}\right)^{k-1} \exp\left(-\left(\frac{v}{c}\right)^k\right) \quad (22)$$

where v is the wind speed, c is the scale factor and k is the shape factor. Typical values for offshore locations are $c = 9$ [22]) and $k = 2$ [23], which results in the Weibull distribution function shown in Fig. ??(a).

The OWPP is presented as a P-Q node for the power flow formulation, where P follows the power generation curve in Fig. ??(b). Also, it is assumed that the OWPP controller ensures that the total reactive power injection at the low-voltage side of the offshore transformer is 0, which follows the grid code in GB [24]. If the wind turbines were expected to absorb reactive power for compensation purposes, the transformer would need to be oversized accordingly.

IV. METHODOLOGY

A methodology is presented in Fig. ?? for selecting the optimal voltage and defining location, size and number of reactors in an HVAC transmission system. This methodology is applied for a defined OWPP rated power S_{owf-N} and transmission cable length l . Also, the main grid parameters, SCR and X_g/R_g , are included as inputs of the methodology.

Several HVAC transmission configurations are considered based on different voltage levels, U_i , and the reactor combinations, C_i , defined in Fig. ??. In particular, for a given U_i , cable and transformer parameters are calculated. Then, the cost of reactors and power losses is optimized for each configuration of U_i and C_i and considering OWPP operation under multiple wind speeds. As a result, the optimal solution is selected based on the total cost of each HVAC transmission configuration. Also, HVAC and HVDC are compared in terms

of total cost in order to select the final offshore transmission system.

A. Definition of cable and transformer parameters

The HVAC cable parameters are obtained from data of manufacturers [25], considering the cable section S and the given voltage U_i , while the transformer parameters are calculated from (5),(6) and (7) based on U_i and S_{owf-N} .

The cable section is also selected from data of manufacturers [25] using the rated current through the cables $I_{r-i} = S_{owf-N}/(\sqrt{3}U_i)$. If I_{r-i} exceeds the largest rated current available from manufacturers, a multiple number of cable circuits N_{cb} is considered.

B. Optimization definition

The objective of the optimization is to minimize cost of power losses and reactors while complying with operational limits. Then, the optimization problem is expressed as:

$$\begin{aligned} F_{obj}(x) &= C_{loss-obj}(x) + C_{react-obj}(x) \\ \text{subject to } h_m(x) &= 0, m \in [1, M] \\ g_n(x) &\leq 0, n \in [1, N] \end{aligned} \quad (23)$$

where x is the variable vector, $F_{obj}(x)$ is the objective function, $C_{loss-obj}$ is the cost of power losses, $C_{react-obj}$ is the reactor investment cost, $h_m(x)$ for $m \in [1, M]$ are the equality constraints and $g_n(x)$ for $n \in [1, N]$ are the inequality constraints.

The variable vector x contains voltages and currents of all nodes in Fig. ??, admittances of added reactors for each wind speed range j and maximum reactor values for all wind speeds. This vector is expressed as:

$$\begin{aligned} x &= [x_1, \dots, x_j, \dots, x_{N_w}, Y_{l-1}^{max}, \dots, Y_{l-i}^{max}, \dots, Y_{l-N_{react}}^{max}] \\ x_j &= [\underline{U}_{1j}, \underline{U}_{2j}, \underline{U}_{3j}, \underline{U}_{4j}, \underline{U}_{5j}, \dots \\ &\quad \underline{I}_{1j}, \underline{I}_{2j}, \underline{I}_{3j}, \underline{I}_{4j}, \underline{I}_{5j}, \underline{I}_{gj}, \dots \\ &\quad \underline{Y}_{l-1j}, \dots, \underline{Y}_{l-N_{react}j}] \\ i &\in [1, N_{react}]; \quad j \in [1, N_w] \end{aligned} \quad (24)$$

where N_w is the number of wind speed ranges considered in the optimization, Y_{l-i}^{max} is the maximum value of reactor i for all wind speeds and N_{react} is the number of reactors.

The cost functions are defined as:

$$C_{loss-obj} = 8760 \cdot t_{owf} \cdot C_E \cdot \sum_{j=1}^{N_w} (P_{loss-j} \cdot p_{w-j}) \quad (25)$$

$$C_{react-obj} = \sum_{i=1}^{N_{react}} (Y_{l-i}^{max} \cdot K + P) \quad (26)$$

where P_{loss-j} are the power losses in (9) at wind speed range j and p_{w-j} is the probability of wind speed range j .

The equality constraints $h_m(x)$ are obtained from the power flow equations in (8) and for each wind speed range j . The inequality constraints $g_n(x)$ are defined based on limits for voltage, current, reactive power and reactor values. However, these limits can be also defined based on grid code require-

ments. The lower and upper limits of currents and voltages are expressed as:

$$U_{min} \leq U_{kj} \leq U_{max}; \quad I_{kj} \leq I_{max} \quad (27)$$

$$k \in [1, 5]; \quad j \in [1, N_w]$$

where U_{min} and U_{max} are the minimum and maximum voltage limits and I_{max} is the maximum current limit. It is assumed that the voltage operational limits are set to $\pm 10\%$ of the nominal value, while the maximum current is 10% of the cable rated value.

The reactive power delivered to the grid Q_{gj} is also limited as follows:

$$Q_{min} \leq Q_{gj} \leq Q_{max}, \quad j \in [1, N_w] \quad (28)$$

where Q_{min} and Q_{max} are the minimum and maximum reactive power values. In this case, the maximum reactive power is set to 0, $Q_{min} = Q_{max} = 0$, but in general this can be also defined by grid code requirements.

The reactors are limited by the maximum values defined in the variable vector x :

$$Y_{l-ij} \leq Y_{l-i}^{max} \quad (29)$$

$$i \in [1, N_{react}]; \quad j \in [1, N_w]$$

It is observed that these reactor constraints are used to obtain the maximum reactor value for all wind speed conditions. The purpose of this methodology is to provide values that could be later evaluated by manufacturers as realistic. The upper limit for Y_{l-i}^{max} is 0, as it is defined negative in III-A3, while the lower limit is mainly limited by the optimization itself as it is directly impacting the objective function.

The optimization is implemented in MATLAB using the function *fmincon*, which is suitable to solve non-linear problems. In particular, interior-point and SQP were selected as specific algorithms for the optimization problem. The computational performance for each combination of rated power and transmission distance depends on the time required for finding feasible solutions, which varies from 45 to 140 s in conventional desktop computer (i7-7500U, 2.9 GHz, 16 GB RAM). However, other algorithms and software could be also used to implement the optimization problem of the methodology in Fig. 9. and reduce the computation time [26]–[28].

V. ANALYSIS OF OFFSHORE TRANSMISSION CONFIGURATIONS

In this Section, offshore transmission configurations are compared in terms of total costs and specific case studies are presented to analyze costs and selection of optimal configurations in detail. Values of system parameters are summarized in Table IV of Appendix.

A. Cost comparison

The methodology presented in Section IV is used to identify the range of OWPP rated powers and distances where different offshore transmission configurations are selected based on total cost.

The selection between HVAC and HVDC transmission systems is presented in Fig. ??(a). The results are presented for OWPP rated powers between 100 MW and 2500 MW with a variation of 100 MW and for distances between 25 km and 220 km with a variation of 5 km. It is observed that for high rated powers the break-even distance between HVAC and HVDC is around 150 km. As shown in early literature, the break distance was around 80 km [13], but with the introduction of mid-cable reactor compensation, this distance is increased up to around 120-160 km [7] which agrees with the results of this paper.

Also, the distance ranges for selecting number of reactors for HVAC configurations are identified as shown in Fig. ??(b). One reactor is selected for a distance up to 30-45 km, while two reactors are preferred up to around 70-80 km, except for low powers where this distance is increased.

It should be mentioned that for low rated powers, the selection of the transmission system can be influenced by the cost of the power losses and reactors, which are obtained from the optimization in Section IV-B. As a result, the break-even distance does not show a clear trend and 150 kV could be selected as optimal voltage.

B. Case studies

Two case studies are analyzed in this Section. The first case study is based on the project Hornsea 3, which has a planned rated power of 2400 MW and a distance from shore of 120 km [1]. The selected configuration corresponds to an HVAC transmission system of 220 kV and three reactors, as seen in Fig.??.

As part of the methodology in Section IV, the cost of power losses and reactors is optimized leading to the results shown in Fig. ??, where combinations are grouped according to the number of reactors. The optimal combination is C_{13} , which corresponds to an optimal voltage of 220 kV and reactors located at the offshore wind farm, the middle of the cable and the onshore grid. It is observed that installing more than one reactor shows a significant cost reduction around 300 M€, while installing three reactors instead of two results in a cost reduction around 40-90 M€. In particular, combinations with a reactor located at the middle of the cable contributes to a further decrease of approximately 50 M€. Also, a cost difference of 100 M€ is observed between voltage levels.

Aside from cost comparisons, the optimization in Section IV-B ensures that voltages and currents in every node are within the limits defined in (27) for different wind powers, as seen in Fig. ??(a) and (b). Also, reactive power compensated by the reactors is presented in Fig. ??(c), which results in the following range of values for each reactor location:

$$0.48 \leq Q_{md} \leq 0.57; \quad 0.18 \leq Q_{off} \leq 0.26 \quad (30)$$

$$0.25 \leq Q_{on} \leq 0.28$$

where the equivalent reactor admittances are equal to the compensated reactive powers, since the system is analyzed in p.u. It is observed that maximum reactive power compensation is required for low wind generation.

The selected HVAC configuration must include the investment and installation cost of the system, as shown in Fig. ??,

where C_{13} with 220 kV is still the configuration with the lowest total cost. It is observed that the final cost of the system is primarily dependent of the cable cost, representing up to 60% of the total cost when 110 kV is used. In particular, the cable cost is affected by the number of cable circuits, which is defined from the voltage level. This results in a cost reduction of approximately 1000 M€ between 110 and 220 kV.

The final offshore transmission system is selected based on the total cost comparison between HVAC and HVDC configurations, as shown in Fig. ??(a). In this case, HVDC configuration is 17% more expensive than the HVAC option. It is clear that the highest cost in HVAC corresponds to the cable cost (46% of total cost), while in HVDC this corresponds to the substation cost (58% of total cost), mainly due to the converter. Also, it is observed that reactive power compensation represents a small proportion of the total cost.

In addition, the possibility to include a variable tap changer in the onshore transformer is analyzed. Fig. ?? evaluates the impact that different tap changer values have on the total cost. In particular, a normalized transformer ratio $\tau = 1$ presents the initial value used in the previous analysis. It is observed that a tap changer variation of 5% results in a cost variation below 2%, therefore a different setting of the transformer ratio could have a minor impact on the final selection between HVAC and HVDC transmission system.

The second case study represents a system with OWPP rated power of 100 MW and distance from shore equal to 100 km, where the optimization of power losses and reactor cost has an influence on the selection of the HVAC configuration.

The optimal combination is C_5 , as shown in Fig. ??, which corresponds to an optimal voltage of 150 kV and reactors located at the offshore wind farm and the onshore side of the cable. It is observed that combinations including the mid-cable reactor show a higher cost. Also, combinations with 220 kV might be more expensive than 150 kV. This is because a low OWPP rated power is considered for this second case study, defining the same number of cable circuits ($N_{cb} = 1$) independently of the voltage level. As a result, cost of the power losses increases for options with higher voltages due to smaller cable sections.

The selected HVAC configuration after including investment and installation costs remains as combination C_5 with 150 kV, as shown in Fig. ??. In this case, substation and cable costs are similar for all voltage levels, since the number of cable circuits is the same. Therefore, the optimal cost for power losses and reactors determines the HVAC configuration. The HVAC configuration is finally selected over the equivalent HVDC configuration, as shown in Fig. ??(b), where cable cost is similar for both configurations.

C. Sensitivity analysis

The comparison between HVAC and HVDC transmission system can be further analyzed with a sensitivity analysis that includes components with a significant impact in the total cost. In particular, the HVAC cables, the converter and the power losses are identified as the main cost components from the previous analysis. First, HVAC cable and converter cost

variation are analyzed in Fig. ?? and ??, where three rated powers of OWPP (100, 1000 and 2500 MW) are considered along with a distance range from 25 to 220 km. In general, the break-even distance only varies few tenths of kilometers. For 100 MW and converter cost reduction, the break-even distance varies for around 30 km, while for 1000 MW and 2500 MW, the change is between 10 and 15 km. On the other hand, by modifying the cost of HVAC cable, the intersection shifts for around 25 km in all cases.

Next, the impact of the power losses cost is analyzed based on the cost of energy and the lifetime of the OWPP, as shown in Fig. ?? and ??. It is observed that for lower powers, the influence of power losses cost is more significant. This is because a low number of cables is used, which do not have a large contribution on the total cost. Therefore, the break-even distance varies from around 5 km (high rated powers) to 50 km (low rated powers).

VI. CONCLUSION

In this paper, the contribution of a mid-cable reactor in an HVAC offshore transmission system for OWPP is analyzed in detail. The introduction of such mid-cable reactor can reduce the total cost and extend the break-even distance between HVAC and HVDC transmission configurations.

Therefore, a methodology is presented to design an HVAC transmission system for specific OWPP rated powers and distances from shore. The cost of power losses and reactive power compensation are optimized for multiple wind speed conditions. As a result, this methodology selects the optimal HVAC voltage and provides the location, size and number of reactors. Also, the HVAC configuration is compared with an equivalent HVDC configuration in order to select the final offshore transmission system based on total cost.

The results conclude that using three reactors including a mid-cable reactor could be a potential solution for high OWPP rated powers and for a distance range from 70 km up to 150 km. However, the cost reduction of HVAC cables and converters and the considerations in the cost of energy and lifetime of the OWPP can change the break-even distance in the range of tenths of kilometers. It is also seen that from the analyzed voltages, 220 kV is the most favorable solution. Therefore, high voltages are preferred, since a reduced number of cable circuits is used, except for low OWPP rated powers, where the cost of power losses and reactors can determine the voltage selection.

APPENDIX

Values of system parameters are presented in Table IV.

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TABLE IV
SYSTEM PARAMETERS

Variable	Definition	Value
SCR	Short circuit ratio	5
X_g/R_g	Ratio of the system reactance to the system resistance	10
t_{owf}	Life time of the OWPP	30 years
C_E	Cost of energy	100 €/MWh
P_{Cu}^{loss}	Copper losses	60 kW
P_{Fe}^{loss}	Iron losses	40 kW
u_k	Short circuit voltage	18 %
i_o	Open circuit current	1.2%

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